

Lagrangian mean curvature flow and the Gibbons-Hawking ansatz

Gonalo Oliveira on joint work with Jason Lotay

Departamento de Matemática, Instituto Superior Técnico

Geometria em Lisboa, February, 2025

History

- ▶ String theories tried to describe particle physics by having strings propagate in a 10d space-time with 6d rolled up in a Calabi-Yau manifold.

History

- ▶ String theories tried to describe particle physics by having strings propagate in a 10d space-time with 6d rolled up in a Calabi-Yau manifold.
- ▶ Not all theories and Calabi-Yau's lead to different physics \implies mirror symmetry (reflecting complex and symplectic geometry).

History

- ▶ String theories tried to describe particle physics by having strings propagate in a 10d space-time with 6d rolled up in a Calabi-Yau manifold.
- ▶ Not all theories and Calabi-Yau's lead to different physics \implies mirror symmetry (reflecting complex and symplectic geometry).
- ▶ Other than the string, the theories involve (mem-)branes, crucial for Math formulations of mirror symmetry (e.g. homological, SYZ).

History

- ▶ String theories tried to describe particle physics by having strings propagate in a 10d space-time with 6d rolled up in a Calabi-Yau manifold.
- ▶ Not all theories and Calabi-Yau's lead to different physics \implies mirror symmetry (reflecting complex and symplectic geometry).
- ▶ Other than the string, the theories involve (mem-)branes, crucial for Math formulations of mirror symmetry (e.g. homological, SYZ).
- ▶ Example: Special Lagrangian (sLag) submflds (are volume minimizing).

History

- ▶ String theories tried to describe particle physics by having strings propagate in a 10d space-time with 6d rolled up in a Calabi-Yau manifold.
- ▶ Not all theories and Calabi-Yau's lead to different physics \implies mirror symmetry (reflecting complex and symplectic geometry).
- ▶ Other than the string, the theories involve (mem-)branes, crucial for Math formulations of mirror symmetry (e.g. homological, SYZ).
- ▶ Example: Special Lagrangian (sLag) submflds (are volume minimizing).
- ▶ **Question:** When does a Lagrangian admit a (unique) sLag rep. in its Hamiltonian isotopy class?

History

- ▶ String theories tried to describe particle physics by having strings propagate in a 10d space-time with 6d rolled up in a Calabi-Yau manifold.
- ▶ Not all theories and Calabi-Yau's lead to different physics \implies mirror symmetry (reflecting complex and symplectic geometry).
- ▶ Other than the string, the theories involve (mem-)branes, crucial for Math formulations of mirror symmetry (e.g. homological, SYZ).
- ▶ Example: Special Lagrangian (sLag) submflds (are volume minimizing).
- ▶ **Question:** When does a Lagrangian admit a (unique) sLag rep. in its Hamiltonian isotopy class?
 - ▶ A (unique) sLag exists in a Hamiltonian isotopy class of Lagrangians iff a stability condition holds (Thomas).

History

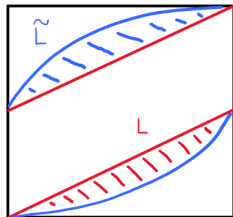
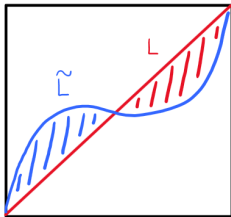
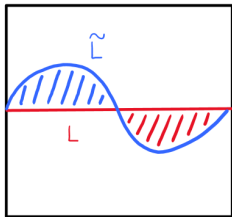
- ▶ String theories tried to describe particle physics by having strings propagate in a 10d space-time with 6d rolled up in a Calabi-Yau manifold.
- ▶ Not all theories and Calabi-Yau's lead to different physics \implies mirror symmetry (reflecting complex and symplectic geometry).
- ▶ Other than the string, the theories involve (mem-)branes, crucial for Math formulations of mirror symmetry (e.g. homological, SYZ).
- ▶ Example: Special Lagrangian (sLag) submflds (are volume minimizing).
- ▶ **Question:** When does a Lagrangian admit a (unique) sLag rep. in its Hamiltonian isotopy class?
 - ▶ A (unique) sLag exists in a Hamiltonian isotopy class of Lagrangians iff a stability condition holds (Thomas).
 - ▶ A Lagrangian can be decomposed into a sequence of sLags \sim Harder–Narasimhan filtration (Thomas–Yau, Douglas, Bridgeland, Joyce).

2-dimensions: The “best” Lagrangians

- ▶ Consider a flat torus $\mathbb{T} = \mathbb{R}^2/\Lambda$ and $\omega = dx \wedge dy$, $\Omega = dx + \sqrt{-1}dy$.
- ▶ Any curve $L \subset \mathbb{T}$ is Lagrangian ($\omega|_L = 0$).

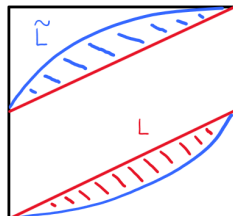
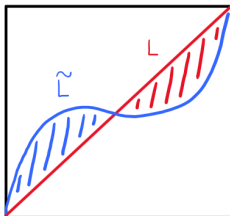
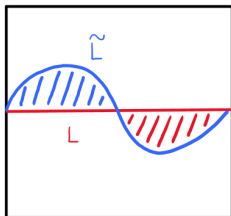
2-dimensions: The “best” Lagrangians

- ▶ Consider a flat torus $\mathbb{T} = \mathbb{R}^2/\Lambda$ and $\omega = dx \wedge dy$, $\Omega = dx + \sqrt{-1}dy$.
- ▶ Any curve $L \subset \mathbb{T}$ is Lagrangian ($\omega|_L = 0$).
- ▶ $\tilde{L} \sim L$ (Hamiltonian isotopic) if the signed area they enclose vanishes.



2-dimensions: The “best” Lagrangians

- ▶ Consider a flat torus $\mathbb{T} = \mathbb{R}^2/\Lambda$ and $\omega = dx \wedge dy$, $\Omega = dx + \sqrt{-1}dy$.
- ▶ Any curve $L \subset \mathbb{T}$ is Lagrangian ($\omega|_L = 0$).
- ▶ $\tilde{L} \sim L$ (Hamiltonian isotopic) if the signed area they enclose vanishes.



- ▶ Straight lines are the “best” representatives.

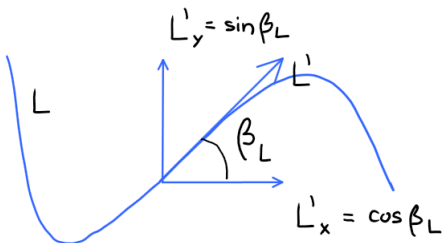
- ▶ Parameterize by $L(s) = (L_x(s), L_y(s))$ with $|L'|^2 = 1$.

- Parameterize by $L(s) = (L_x(s), L_y(s))$ with $|L'|^2 = 1$. Then, with $\Omega = dx + \sqrt{-1}dy$

$$L^* \Omega = (L'_x + \sqrt{-1}L'_y) ds$$

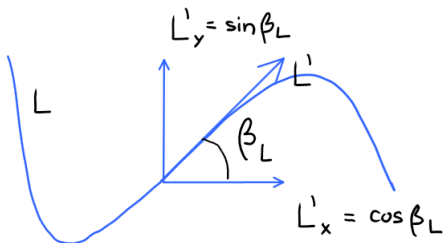
- Parameterize by $L(s) = (L_x(s), L_y(s))$ with $|L'|^2 = 1$. Then, with $\Omega = dx + \sqrt{-1}dy$

$$L^*\Omega = (L'_x + \sqrt{-1}L'_y) ds$$



- Parameterize by $L(s) = (L_x(s), L_y(s))$ with $|L'|^2 = 1$. Then, with $\Omega = dx + \sqrt{-1}dy$

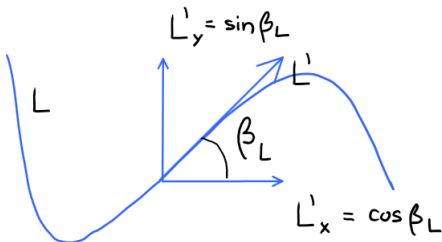
$$L^*\Omega = (L'_x + \sqrt{-1}L'_y) ds$$



$$\begin{aligned} L^*\Omega &= (\cos(\beta_L) + \sqrt{-1} \sin(\beta_L)) ds \\ &= e^{i\beta_L} ds, \end{aligned}$$

- Parameterize by $L(s) = (L_x(s), L_y(s))$ with $|L'|^2 = 1$. Then, with $\Omega = dx + \sqrt{-1}dy$

$$L^*\Omega = (L'_x + \sqrt{-1}L'_y) ds$$



$$\begin{aligned} L^*\Omega &= (\cos(\beta_L) + \sqrt{-1} \sin(\beta_L)) ds \\ &= e^{i\beta_L} ds, \end{aligned}$$

- $\implies L$ is a straight line iff $\beta_L = \text{constant} \Leftrightarrow L'' = 0$.

- ▶ Parameterize by $L(s) = (L_x(s), L_y(s))$ with $|L'|^2 = 1$. Then,

$$L^* \Omega = e^{i\beta_L} ds,$$

where $\beta_L =$ angle between L' and x -axis.

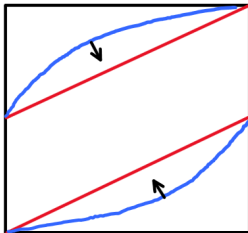
- ▶ $\implies L$ is a straight line iff $\beta_L = \text{constant} \Leftrightarrow L'' = 0$.

- ▶ Parameterize by $L(s) = (L_x(s), L_y(s))$ with $|L'|^2 = 1$. Then,

$$L^* \Omega = e^{i\beta_L} ds,$$

where β_L = angle between L' and x-axis.

- ▶ $\implies L$ is a straight line iff $\beta_L = \text{constant} \Leftrightarrow L'' = 0$.
- ▶ Given L_0 , how can we deform it until it becomes straight?

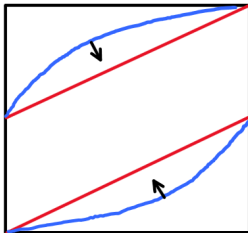


- Parameterize by $L(s) = (L_x(s), L_y(s))$ with $|L'|^2 = 1$. Then,

$$L^* \Omega = e^{i\beta_L} ds,$$

where β_L = angle between L' and x-axis.

- $\implies L$ is a straight line iff $\beta_L = \text{constant} \Leftrightarrow L'' = 0$.
- Given L_0 , how can we deform it until it becomes straight?



In the direction of its curvature $= L'' \rightsquigarrow$ Curve shortening flow $\{L_t\}_{t \geq 0}$:

$$\partial_t L_t = L_t''$$

4-dimensional X

- ▶ $L^2 \subset (X^4, \omega, \Omega)$ oriented embedded Lagrangian, i.e. $\omega|_L = 0$.

¹assuming $\pi_1(X)$ is finite

4-dimensional X

- $L^2 \subset (X^4, \omega, \Omega)$ oriented embedded Lagrangian, i.e. $\omega|_L = 0$. Then

$$\Omega|_L = e^{i\beta_L} \text{vol}_L,$$

for a function $e^{i\beta_L} : L \rightarrow \text{U}(1)$ called the Lagrangian angle.

¹assuming $\pi_1(X)$ is finite

4-dimensional X

- ▶ $L^2 \subset (X^4, \omega, \Omega)$ oriented embedded Lagrangian, i.e. $\omega|_L = 0$. Then

$$\Omega|_L = e^{i\beta_L} \text{vol}_L,$$

for a function $e^{i\beta_L} : L \rightarrow \text{U}(1)$ called the Lagrangian angle.

- ▶ L is special Lagrangian (sLag) if it has constant Lagrangian angle,

¹assuming $\pi_1(X)$ is finite

4-dimensional X

- ▶ $L^2 \subset (X^4, \omega, \Omega)$ oriented embedded Lagrangian, i.e. $\omega|_L = 0$. Then

$$\Omega|_L = e^{i\beta_L} \text{vol}_L,$$

for a function $e^{i\beta_L} : L \rightarrow \text{U}(1)$ called the Lagrangian angle.

- ▶ L is special Lagrangian (sLag) if it has constant Lagrangian angle, i.e.

$$\text{Re}(e^{-i\beta_L} \Omega|_L) = \text{vol}_L, \text{ for a constant } \beta_L \in \mathbb{R}.$$

¹assuming $\pi_1(X)$ is finite

4-dimensional X

- ▶ $L^2 \subset (X^4, \omega, \Omega)$ oriented embedded Lagrangian, i.e. $\omega|_L = 0$. Then

$$\Omega|_L = e^{i\beta_L} \text{vol}_L,$$

for a function $e^{i\beta_L} : L \rightarrow \text{U}(1)$ called the Lagrangian angle.

- ▶ L is special Lagrangian (sLag) if it has constant Lagrangian angle, i.e.

$$\text{Re}(e^{-i\beta_L} \Omega|_L) = \text{vol}_L, \text{ for a constant } \beta_L \in \mathbb{R}.$$

\implies minimize volume in their homology class.

¹assuming $\pi_1(X)$ is finite

4-dimensional X

- ▶ $L^2 \subset (X^4, \omega, \Omega)$ oriented embedded Lagrangian, i.e. $\omega|_L = 0$. Then

$$\Omega|_L = e^{i\beta_L} \text{vol}_L,$$

for a function $e^{i\beta_L} : L \rightarrow \text{U}(1)$ called the Lagrangian angle.

- ▶ L is special Lagrangian (sLag) if it has constant Lagrangian angle, i.e.

$$\text{Re}(e^{-i\beta_L} \Omega|_L) = \text{vol}_L, \text{ for a constant } \beta_L \in \mathbb{R}.$$

\implies minimize volume in their homology class.

- ▶ $L \sim \tilde{L}$ if \exists a symplectic isotopy $\{\rho_t : X \rightarrow X\}_{t \in [0,1]}$ ¹ with $\rho_1(L) = \tilde{L}$.

¹assuming $\pi_1(X)$ is finite

4-dimensional X

- ▶ $L^2 \subset (X^4, \omega, \Omega)$ oriented embedded Lagrangian, i.e. $\omega|_L = 0$. Then

$$\Omega|_L = e^{i\beta_L} \text{vol}_L,$$

for a function $e^{i\beta_L} : L \rightarrow \text{U}(1)$ called the Lagrangian angle.

- ▶ L is special Lagrangian (sLag) if it has constant Lagrangian angle, i.e.

$$\text{Re}(e^{-i\beta_L} \Omega|_L) = \text{vol}_L, \text{ for a constant } \beta_L \in \mathbb{R}.$$

\implies minimize volume in their homology class.

- ▶ $L \sim \tilde{L}$ if \exists a symplectic isotopy $\{\rho_t : X \rightarrow X\}_{t \in [0,1]}$ ¹ with $\rho_1(L) = \tilde{L}$.

\implies if $L \sim \text{sLag}$ then \exists a lift

$$\beta_L = \arg(e^{i\beta_L}) : L \rightarrow \mathbb{R}, \text{ called a } \textit{grading}.$$

¹assuming $\pi_1(X)$ is finite

4-dimensional X

- ▶ $L^2 \subset (X^4, \omega, \Omega)$ oriented embedded Lagrangian, i.e. $\omega|_L = 0$. Then

$$\Omega|_L = e^{i\beta_L} \text{vol}_L,$$

for a function $e^{i\beta_L} : L \rightarrow \text{U}(1)$ called the Lagrangian angle.

- ▶ L is special Lagrangian (sLag) if it has constant Lagrangian angle, i.e.

$$\text{Re}(e^{-i\beta_L} \Omega|_L) = \text{vol}_L, \text{ for a constant } \beta_L \in \mathbb{R}.$$

\implies minimize volume in their homology class.

- ▶ $L \sim \tilde{L}$ if \exists a symplectic isotopy $\{\rho_t : X \rightarrow X\}_{t \in [0,1]}$ ¹ with $\rho_1(L) = \tilde{L}$.

\implies if $L \sim \text{sLag}$ then \exists a lift

$$\beta_L = \arg(e^{i\beta_L}) : L \rightarrow \mathbb{R}, \text{ called a } \textit{grading}.$$

- ▶ Can connect sum (graded) Lagrangians

¹assuming $\pi_1(X)$ is finite

4-dimensional X

- ▶ $L^2 \subset (X^4, \omega, \Omega)$ oriented embedded Lagrangian, i.e. $\omega|_L = 0$. Then

$$\Omega|_L = e^{i\beta_L} \text{vol}_L,$$

for a function $e^{i\beta_L} : L \rightarrow \text{U}(1)$ called the Lagrangian angle.

- ▶ L is special Lagrangian (sLag) if it has constant Lagrangian angle, i.e.

$$\text{Re}(e^{-i\beta_L} \Omega|_L) = \text{vol}_L, \text{ for a constant } \beta_L \in \mathbb{R}.$$

\implies minimize volume in their homology class.

- ▶ $L \sim \tilde{L}$ if \exists a symplectic isotopy $\{\rho_t : X \rightarrow X\}_{t \in [0,1]}$ ¹ with $\rho_1(L) = \tilde{L}$.

\implies if $L \sim \text{sLag}$ then \exists a lift

$$\beta_L = \arg(e^{i\beta_L}) : L \rightarrow \mathbb{R}, \text{ called a } \textit{grading}.$$

- ▶ Can connect sum (graded) Lagrangians, but $L_+ \# L_- \approx L_- \# L_+$.

¹assuming $\pi_1(X)$ is finite

4-dimensional X

- ▶ $L^2 \subset (X^4, \omega, \Omega)$ oriented embedded Lagrangian, i.e. $\omega|_L = 0$. Then

$$\Omega|_L = e^{i\beta_L} \text{vol}_L,$$

for a function $e^{i\beta_L} : L \rightarrow \text{U}(1)$ called the Lagrangian angle.

- ▶ L is special Lagrangian (sLag) if it has constant Lagrangian angle, i.e.

$$\text{Re}(e^{-i\beta_L} \Omega|_L) = \text{vol}_L, \text{ for a constant } \beta_L \in \mathbb{R}.$$

\implies minimize volume in their homology class.

- ▶ $L \sim \tilde{L}$ if \exists a symplectic isotopy $\{\rho_t : X \rightarrow X\}_{t \in [0,1]}$ ¹ with $\rho_1(L) = \tilde{L}$.

\implies if $L \sim \text{sLag}$ then \exists a lift

$$\beta_L = \arg(e^{i\beta_L}) : L \rightarrow \mathbb{R}, \text{ called a } \textit{grading}.$$

- ▶ Can connect sum (graded) Lagrangians, but $L_+ \# L_- \sim L_- \# L_+$.
- ▶ L is *unstable* if $L \sim L_+ \# L_-$ whose “average” gradings satisfy

$$\arg \int_{L_+} \Omega \geq \arg \int_{L_-} \Omega.$$

¹assuming $\pi_1(X)$ is finite

Circle action

- ▶ Assume $(X^4, \omega_1, \omega_2, \omega_3)$ has a circle symmetry. \exists infinite families of examples \implies fertile testing ground for conjectures.

Circle action

- ▶ Assume $(X^4, \omega_1, \omega_2, \omega_3)$ has a circle symmetry. \exists infinite families of examples \implies fertile testing ground for conjectures.
- ▶ The projection onto the orbit space is

$$\mu = (\mu_1, \mu_2, \mu_3) : X \rightarrow \mathbb{R}^3,$$

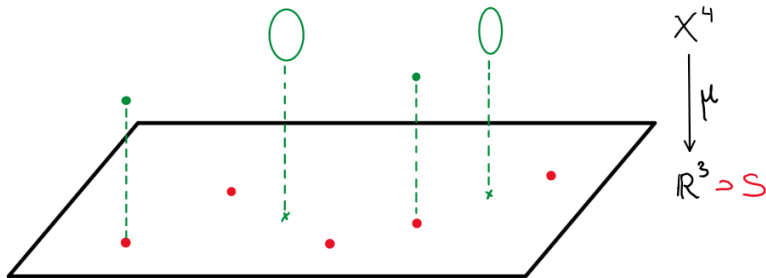
with $\mu^{-1}(p)$ a point iff $p \in \mathcal{S} \subset \mathbb{R}^3$, a discrete set.

Circle action

- ▶ Assume $(X^4, \omega_1, \omega_2, \omega_3)$ has a circle symmetry. \exists infinite families of examples \implies fertile testing ground for conjectures.
- ▶ The projection onto the orbit space is

$$\mu = (\mu_1, \mu_2, \mu_3) : X \rightarrow \mathbb{R}^3,$$

with $\mu^{-1}(p)$ a point iff $p \in S \subset \mathbb{R}^3$, a discrete set.



Circle action

- ▶ Assume $(X^4, \omega_1, \omega_2, \omega_3)$ has a circle symmetry. \exists infinite families of examples \implies fertile testing ground for conjectures.
- ▶ The projection onto the orbit space is

$$\mu = (\mu_1, \mu_2, \mu_3) : X \rightarrow \mathbb{R}^3,$$

with $\mu^{-1}(p)$ a point iff $p \in \mathcal{S} \subset \mathbb{R}^3$, a discrete set.

- ▶ A circle-invariant surface L in X is the pre-image of a curve γ in \mathbb{R}^3 :

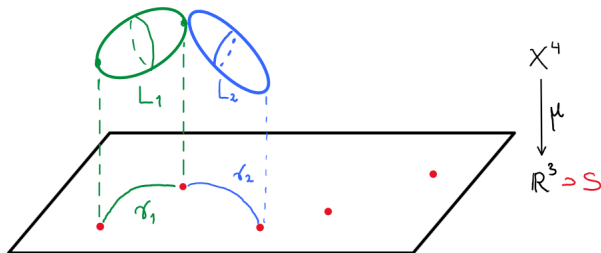
Circle action

- ▶ Assume $(X^4, \omega_1, \omega_2, \omega_3)$ has a circle symmetry. \exists infinite families of examples \implies fertile testing ground for conjectures.
- ▶ The projection onto the orbit space is

$$\mu = (\mu_1, \mu_2, \mu_3) : X \rightarrow \mathbb{R}^3,$$

with $\mu^{-1}(p)$ a point iff $p \in \mathcal{S} \subset \mathbb{R}^3$, a discrete set.

- ▶ A circle-invariant surface L in X is the pre-image of a curve γ in \mathbb{R}^3 :



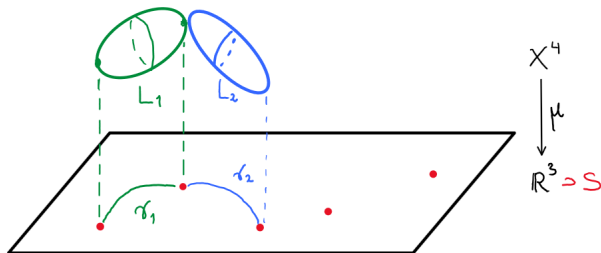
Circle action

- Assume $(X^4, \omega_1, \omega_2, \omega_3)$ has a circle symmetry. \exists infinite families of examples \implies fertile testing ground for conjectures.
- The projection onto the orbit space is

$$\mu = (\mu_1, \mu_2, \mu_3) : X \rightarrow \mathbb{R}^3,$$

with $\mu^{-1}(p)$ a point iff $p \in \mathcal{S} \subset \mathbb{R}^3$, a discrete set.

- A circle-invariant surface L in X is the pre-image of a curve γ in \mathbb{R}^3 :



- $L = \mu^{-1}(\gamma)$ is Lagrangian if and only if γ is planar (\perp to μ_1 -axis).

Circle action

- ▶ Assume $(X^4, \omega_1, \omega_2, \omega_3)$ has a circle symmetry. \exists infinite families of examples \implies fertile testing ground for conjectures.
- ▶ The projection onto the orbit space is

$$\mu = (\mu_1, \mu_2, \mu_3) : X \rightarrow \mathbb{R}^3,$$

with $\mu^{-1}(p)$ a point iff $p \in \mathcal{S} \subset \mathbb{R}^3$, a discrete set.

- ▶ A circle-invariant surface L in X is the pre-image of a curve γ in \mathbb{R}^3 .
- ▶ $L = \mu^{-1}(\gamma)$ is Lagrangian if and only if γ is planar (\perp to μ_1 -axis).

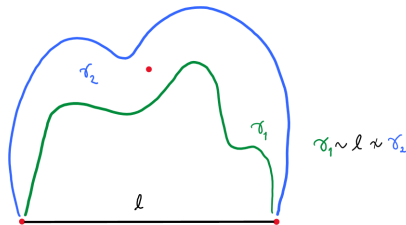
Circle action

- ▶ Assume $(X^4, \omega_1, \omega_2, \omega_3)$ has a circle symmetry. \exists infinite families of examples \implies fertile testing ground for conjectures.
- ▶ The projection onto the orbit space is

$$\mu = (\mu_1, \mu_2, \mu_3) : X \rightarrow \mathbb{R}^3,$$

with $\mu^{-1}(p)$ a point iff $p \in \mathcal{S} \subset \mathbb{R}^3$, a discrete set.

- ▶ A circle-invariant surface L in X is the pre-image of a curve γ in \mathbb{R}^3 .
- ▶ $L = \mu^{-1}(\gamma)$ is Lagrangian if and only if γ is planar (\perp to μ_1 -axis).
- ▶ $\mu^{-1}(\gamma_1) \sim \mu^{-1}(\gamma_2)$ iff $\gamma_1 \sim \gamma_2$ planarly and away from \mathcal{S} .



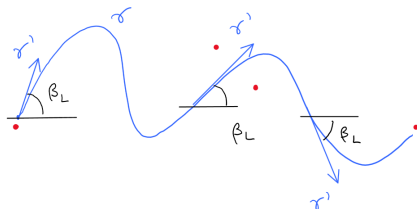
Circle action

- ▶ Assume $(X^4, \omega_1, \omega_2, \omega_3)$ has a circle symmetry. \exists infinite families of examples \implies fertile testing ground for conjectures.
- ▶ The projection onto the orbit space is

$$\mu = (\mu_1, \mu_2, \mu_3) : X \rightarrow \mathbb{R}^3,$$

with $\mu^{-1}(p)$ a point iff $p \in \mathcal{S} \subset \mathbb{R}^3$, a discrete set.

- ▶ A circle-invariant surface L in X is the pre-image of a curve γ in \mathbb{R}^3 .
- ▶ $L = \mu^{-1}(\gamma)$ is Lagrangian if and only if γ is planar (\perp to μ_1 -axis).
- ▶ $\mu^{-1}(\gamma_1) \sim \mu^{-1}(\gamma_2)$ iff $\gamma_1 \sim \gamma_2$ planarly and away from \mathcal{S} .
- ▶ The grading β_L of $L = \mu^{-1}(\gamma)$ is the angle γ' makes with a fixed line.



Circle action

- ▶ Assume $(X^4, \omega_1, \omega_2, \omega_3)$ has a circle symmetry. \exists infinite families of examples \implies fertile testing ground for conjectures.
- ▶ The projection onto the orbit space is

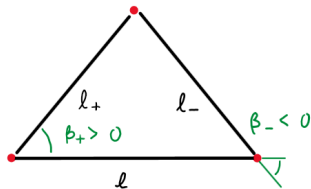
$$\mu = (\mu_1, \mu_2, \mu_3) : X \rightarrow \mathbb{R}^3,$$

with $\mu^{-1}(p)$ a point iff $p \in \mathbf{S} \subset \mathbb{R}^3$, a discrete set.

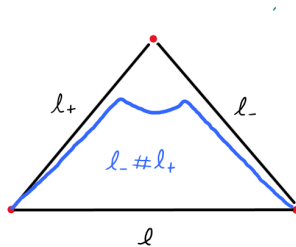
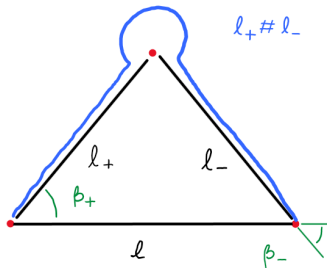
- ▶ A circle-invariant surface L in X is the pre-image of a curve γ in \mathbb{R}^3 .
- ▶ $L = \mu^{-1}(\gamma)$ is Lagrangian if and only if γ is planar (\perp to μ_1 -axis).
- ▶ $\mu^{-1}(\gamma_1) \sim \mu^{-1}(\gamma_2)$ iff $\gamma_1 \sim \gamma_2$ planarly and away from S .
- ▶ The grading β_L of $L = \mu^{-1}(\gamma)$ is the angle γ' makes with a fixed line.

$\implies L$ is a sLag iff γ is a straight line.

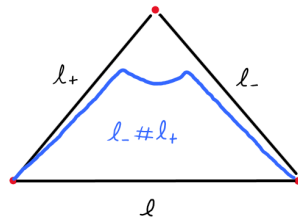
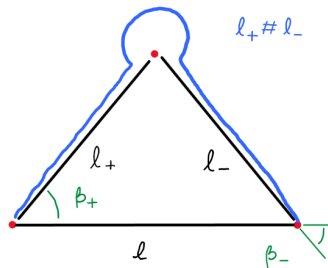
Stability



Stability

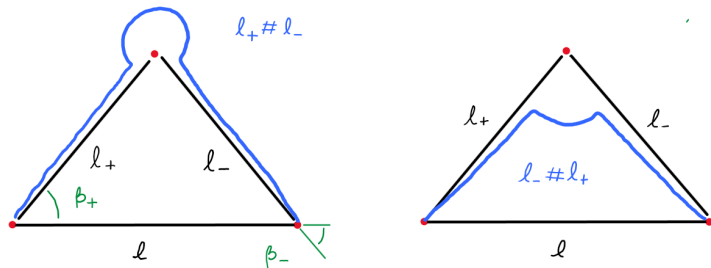


Stability



- $L = \mu^{-1}(\gamma)$ is stable iff $\gamma \sim l$, the straight line connecting its endpoints.

Stability



- $L = \mu^{-1}(\gamma)$ is stable iff $\gamma \sim \ell$, the straight line connecting its endpoints.
 $\mu^{-1}(\ell)$ is the unique circle-invariant sLag in $[L]$.

Tackling the Conjectures

Theorem (Jason Lotay, –)

$L \subseteq X$ a circle-invariant Lagrangian sphere, then:

$$L \sim_{U(1)} sLag \Leftrightarrow L \text{ is } U(1)\text{-stable.}$$

In this situation, such a sLag is unique.

² $\sup \beta - \inf \beta < \pi$

³If $L \sim L_+ \# L_-$, then: $\text{Area}(L) < \text{Area}(L_+) + \text{Area}(L_-)$

Tackling the Conjectures

Theorem (Jason Lotay, –)

$L \subseteq X$ a circle-invariant Lagrangian sphere, then:

$$L \sim_{U(1)} sLag \Leftrightarrow L \text{ is } U(1)\text{-stable.}$$

In this situation, such a sLag is unique.

Theorem (Jason Lotay, –)

The MCF starting at an almost calibrated² and flow stable³ circle invariant Lagrangian L exists for all time and converges smoothly to a sLag.

² $\sup \beta - \inf \beta < \pi$

³If $L \sim L_+ \# L_-$, then: $\text{Area}(L) < \text{Area}(L_+) + \text{Area}(L_-)$

Tackling the Conjectures

Theorem (Jason Lotay, –)

$L \subseteq X$ a circle-invariant Lagrangian sphere, then:

$$L \sim_{U(1)} sLag \Leftrightarrow L \text{ is } U(1)\text{-stable.}$$

In this situation, such a sLag is unique.

Theorem (Jason Lotay, –)

The MCF starting at an almost calibrated² and flow stable³ circle invariant Lagrangian L exists for all time and converges smoothly to a sLag.

Conclusion: We have proved circle-invariant versions of:

- ▶ The Thomas conjecture.
- ▶ The Thomas–Yau conjecture.

² $\sup \beta - \inf \beta < \pi$

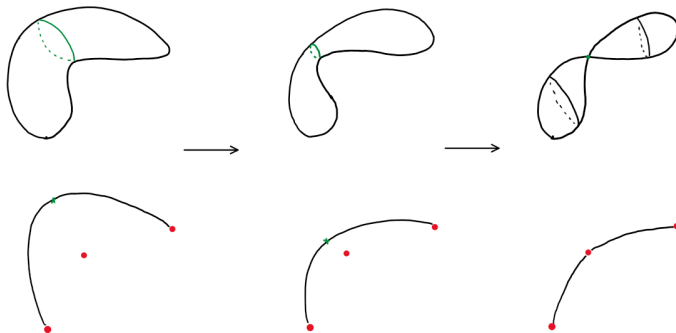
³If $L \sim L_+ \# L_-$, then: $\text{Area}(L) < \text{Area}(L_+) + \text{Area}(L_-)$

What happens for unstable Lagrangians?

- ▶ Finite time singularities exist and occur when γ_t hits S .

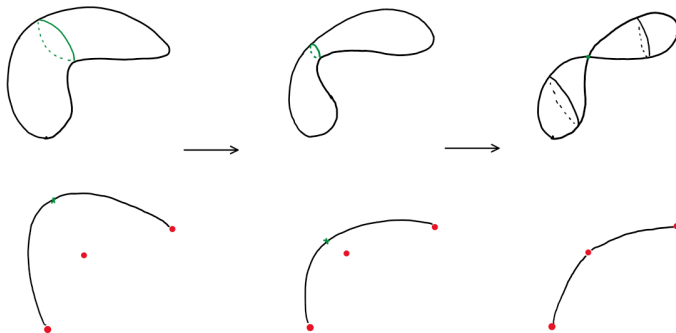
What happens for unstable Lagrangians?

- ▶ Finite time singularities exist and occur when γ_t hits S .
- ▶ This leads to the so-called “neck pinch” singularities.



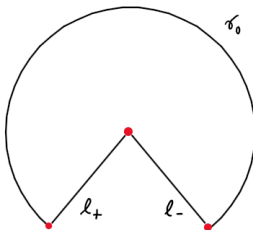
What happens for unstable Lagrangians?

- ▶ Finite time singularities exist and occur when γ_t hits S .
- ▶ This leads to the so-called “neck pinch” singularities.



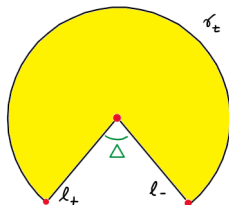
What happens for unstable Lagrangians?

- ▶ Finite time singularities exist and occur when γ_t hits S .
- ▶ This leads to the so-called “neck pinch” singularities.
- ▶ Consider, for example, the convex curve $\gamma_0 \sim \ell_+ \# \ell_-$.



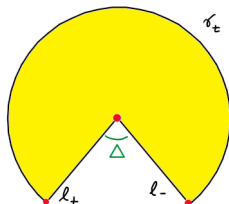
What happens for unstable Lagrangians?

- ▶ Finite time singularities exist and occurs when γ_t hits S .
- ▶ This leads to the so-called “neck pinch” singularities.
- 1 Look at the pacman disk D_t (the holomorphic disk in yellow)



What happens for unstable Lagrangians?

- ▶ Finite time singularities exist and occurs when γ_t hits S .
- ▶ This leads to the so-called “neck pinch” singularities.
- 1 Look at the pacman disk D_t (the holomorphic disk in yellow)

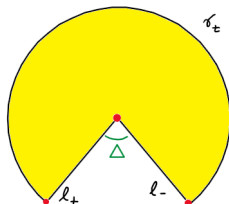


For as long as γ_t hits no singularity

$$\frac{d}{dt} \text{Area}(D_t) \leq -(\pi - \Delta) < 0.$$

What happens for unstable Lagrangians?

- ▶ Finite time singularities exist and occurs when γ_t hits S .
 - ▶ This leads to the so-called “neck pinch” singularities.
- 1 Look at the pacman disk D_t (the holomorphic disk in yellow)



For as long as γ_t hits no singularity

$$\frac{d}{dt} \text{Area}(D_t) \leq -(\pi - \Delta) < 0.$$

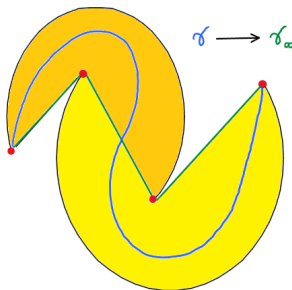
\implies there is a finite time singularity as otherwise $\text{Area}(D_t)$ would become zero in finite time.

What happens for unstable Lagrangians?

- ▶ Finite time singularities exist and occurs when γ_t hits S .
- ▶ This leads to the so-called “neck pinch” singularities.
 - 1 Look at the evolution of pacman disks.
 - 2 Use pacman disks as barriers to establish the existence of singularities.

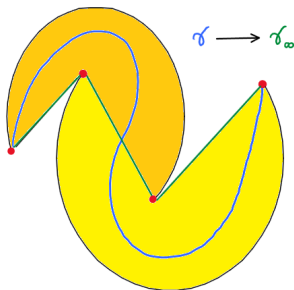
What happens for unstable Lagrangians?

- ▶ Finite time singularities exist and occurs when γ_t hits S .
- ▶ This leads to the so-called “neck pinch” singularities.
 - 1 Look at the evolution of pacman disks.
 - 2 Use pacman disks as barriers to establish the existence of singularities.



What happens for unstable Lagrangians?

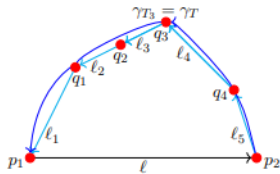
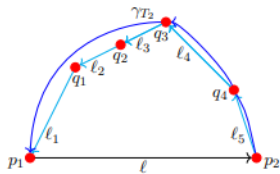
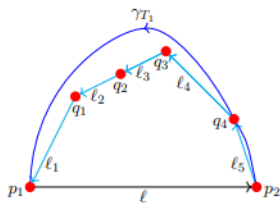
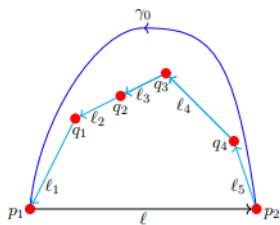
- ▶ Finite time singularities exist and occurs when γ_t hits S .
- ▶ This leads to the so-called “neck pinch” singularities.
 - 1 Look at the evolution of pacman disks.
 - 2 Use pacman disks as barriers to establish the existence of singularities.



- 3 Restart the flow (for a piecewise smooth curve) after a singularity.

Flow through singularities and long-time convergence

Theorem (Jason Lotay, –)



Flow through singularities and long-time convergence

Theorem (Jason Lotay, –)

Let L_0 be a circle-invariant, almost calibrated Lagrangian in X . There is a continuous family $\{L_t\}_{t \in [0, +\infty)}$ so that the following holds.

- (a) $\exists 0 < T_1 \leq \dots \leq T_l < \infty$ such that the family $\{L_t\}_{t \in [0, \infty) \setminus \{T_1, \dots, T_l\}}$ satisfies MCF.

Flow through singularities and long-time convergence

Theorem (Jason Lotay, –)

Let L_0 be a circle-invariant, almost calibrated Lagrangian in X . There is a continuous family $\{L_t\}_{t \in [0, +\infty)}$ so that the following holds.

- (a) $\exists 0 < T_1 \leq \dots \leq T_l < \infty$ such that the family $\{L_t\}_{t \in [0, \infty) \setminus \{T_1, \dots, T_l\}}$ satisfies MCF.
- (b) At each singular time T_i the flow undergoes a “neck pinch” singularity.

Flow through singularities and long-time convergence

Theorem (Jason Lotay, –)

Let L_0 be a circle-invariant, almost calibrated Lagrangian in X . There is a continuous family $\{L_t\}_{t \in [0, +\infty)}$ so that the following holds.

- (a) $\exists 0 < T_1 \leq \dots \leq T_l < \infty$ such that the family $\{L_t\}_{t \in [0, \infty) \setminus \{T_1, \dots, T_l\}}$ satisfies MCF.
- (b) At each singular time T_i the flow undergoes a “neck pinch” singularity.
- (c) $\exists_{k \in \mathbb{N}}$ and a chain of sLag spheres $\{L_1^\infty, \dots, L_k^\infty\}$ such that as $t \rightarrow +\infty$

$L_t \rightarrow \cup_{j=1}^k L_j^\infty$ uniformly; and

$L_t \rightarrow L_1^\infty + \dots + L_k^\infty$ as currents.

Flow through singularities and long-time convergence

Theorem (Jason Lotay, –)

Let L_0 be a circle-invariant, almost calibrated Lagrangian in X . There is a continuous family $\{L_t\}_{t \in [0, +\infty)}$ so that the following holds.

- (a) $\exists 0 < T_1 \leq \dots \leq T_l < \infty$ such that the family $\{L_t\}_{t \in [0, \infty) \setminus \{T_1, \dots, T_l\}}$ satisfies MCF.
- (b) At each singular time T_i the flow undergoes a “neck pinch” singularity.
- (c) $\exists k \in \mathbb{N}$ and a chain of sLag spheres $\{L_1^\infty, \dots, L_k^\infty\}$ such that as $t \rightarrow +\infty$

$$L_t \rightarrow \cup_{j=1}^k L_j^\infty \text{ uniformly; and}$$

$$L_t \rightarrow L_1^\infty + \dots + L_k^\infty \text{ as currents.}$$

- (d) If the grading on L is a perfect Morse function, then the gradings β_j of the sLags L_j^∞ from (c) can be chosen to satisfy $\beta_1 \geq \dots \geq \beta_k$.

Flow through singularities and long-time convergence

Theorem (Jason Lotay, –)

Let L_0 be a circle-invariant, almost calibrated Lagrangian in X . There is a continuous family $\{L_t\}_{t \in [0, +\infty)}$ so that the following holds.

- (a) $\exists 0 < T_1 \leq \dots \leq T_l < \infty$ such that the family $\{L_t\}_{t \in [0, \infty) \setminus \{T_1, \dots, T_l\}}$ satisfies MCF.
- (b) At each singular time T_i the flow undergoes a “neck pinch” singularity.
- (c) $\exists k \in \mathbb{N}$ and a chain of sLag spheres $\{L_1^\infty, \dots, L_k^\infty\}$ such that as $t \rightarrow +\infty$

$$L_t \rightarrow \cup_{j=1}^k L_j^\infty \text{ uniformly; and}$$

$$L_t \rightarrow L_1^\infty + \dots + L_k^\infty \text{ as currents.}$$

- (d) If the grading on L is a perfect Morse function, then the gradings β_j of the sLags L_j^∞ from (c) can be chosen to satisfy $\beta_1 \geq \dots \geq \beta_k$.

Furthermore: $k = 1$ if L_0 is flow stable, and $k > 1$ otherwise.

Flow through singularities and long-time convergence

Theorem (Jason Lotay, –)

Let L_0 be a circle-invariant, almost calibrated Lagrangian in X . There is a continuous family $\{L_t\}_{t \in [0, +\infty)}$ so that the following holds.

- (a) $\exists 0 < T_1 \leq \dots \leq T_l < \infty$ such that the family $\{L_t\}_{t \in [0, \infty) \setminus \{T_1, \dots, T_l\}}$ satisfies MCF.
- (b) At each singular time T_i the flow undergoes a “neck pinch” singularity.
- (c) $\exists k \in \mathbb{N}$ and a chain of sLag spheres $\{L_1^\infty, \dots, L_k^\infty\}$ such that as $t \rightarrow +\infty$

$$L_t \rightarrow \cup_{j=1}^k L_j^\infty \text{ uniformly; and}$$

$$L_t \rightarrow L_1^\infty + \dots + L_k^\infty \text{ as currents.}$$

- (d) If the grading on L is a perfect Morse function, then the gradings β_j of the sLags L_j^∞ from (c) can be chosen to satisfy $\beta_1 \geq \dots \geq \beta_k$.

Furthermore: $k = 1$ if L_0 is flow stable, and $k > 1$ otherwise.

- Proves a circle invariant version of one of Joyce's conjectures.

Obrigado!

Structure of finite time “neck pinch” singularities

Theorem (Jason Lotay, –)

Let L_0 be embedded, almost calibrated, circle-invariant and $\{L_t\}_{t \in [0, T)}$ with the smooth LMCF starting at L_0 developing a finite time singularity at $p \in X$ when $t \rightarrow T < \infty$.

Structure of finite time “neck pinch” singularities

Theorem (Jason Lotay, –)

Let L_0 be embedded, almost calibrated, circle-invariant and $\{L_t\}_{t \in [0, T)}$ with the smooth LMCF starting at L_0 developing a finite time singularity at $p \in X$ when $t \rightarrow T < \infty$.

Then, there is $\varepsilon(t) \searrow 0$ as $t \nearrow T$ and a fixed size neighborhood of p where $\varepsilon(t)^{-1} L_t$ converges on compact subsets of \mathbb{C}^2 to a unique Lawlor neck.

Structure of finite time “neck pinch” singularities

Theorem (Jason Lotay, –)

Let L_0 be embedded, almost calibrated, circle-invariant and $\{L_t\}_{t \in [0, T)}$ with the smooth LMCF starting at L_0 developing a finite time singularity at $p \in X$ when $t \rightarrow T < \infty$.

Then, there is $\varepsilon(t) \searrow 0$ as $t \nearrow T$ and a fixed size neighborhood of p where $\varepsilon(t)^{-1} L_t$ converges on compact subsets of \mathbb{C}^2 to a unique Lawlor neck.

- Follows from blow-up arguments + recent work of Lotay–Schulze–Székelyhidi.

Structure of finite time “neck pinch” singularities

Theorem (Jason Lotay, –)

Let L_0 be embedded, almost calibrated, circle-invariant and $\{L_t\}_{t \in [0, T)}$ with the smooth LMCF starting at L_0 developing a finite time singularity at $p \in X$ when $t \rightarrow T < \infty$.

Then, there is $\varepsilon(t) \searrow 0$ as $t \nearrow T$ and a fixed size neighborhood of p where $\varepsilon(t)^{-1} L_t$ converges on compact subsets of \mathbb{C}^2 to a unique Lawlor neck.

- ▶ Follows from blow-up arguments + recent work of Lotay–Schulze–Székelyhidi.
- ▶ The theorem contains much more information than the blow up limit. It can be interpreted as saying that there is a fixed Lawlor neck in \mathbb{C}^2 whose blow downs model the movement of L_t in a fixed, definite size neighbourhood U of $p \in X$.

Structure of finite time “neck pinch” singularities

Theorem (Jason Lotay, –)

Let L_0 be embedded, almost calibrated, circle-invariant and $\{L_t\}_{t \in [0, T)}$ with the smooth LMCF starting at L_0 developing a finite time singularity at $p \in X$ when $t \rightarrow T < \infty$.

Then, there is $\varepsilon(t) \searrow 0$ as $t \nearrow T$ and a fixed size neighborhood of p where $\varepsilon(t)^{-1} L_t$ converges on compact subsets of \mathbb{C}^2 to a unique Lawlor neck.

- ▶ Follows from blow-up arguments + recent work of Lotay–Schulze–Székelyhidi.
- ▶ The theorem contains much more information than the blow up limit. It can be interpreted as saying that there is a fixed Lawlor neck in \mathbb{C}^2 whose blow downs model the movement of L_t in a fixed, definite size neighbourhood U of $p \in X$.
- ▶ L 's as in the statement exist for any $X \neq \mathbb{R}^3 \times \mathbb{S}^1$. Moreover, if X contains a pair of sLag spheres of different Lagrangian angles, then there are such L which are compact.

Structure of finite time “neck pinch” singularities

Theorem (Jason Lotay, –)

Let L_0 be embedded, almost calibrated, circle-invariant and $\{L_t\}_{t \in [0, T)}$ with the smooth LMCF starting at L_0 developing a finite time singularity at $p \in X$ when $t \rightarrow T < \infty$.

Then, there is $\varepsilon(t) \searrow 0$ as $t \nearrow T$ and a fixed size neighborhood of p where $\varepsilon(t)^{-1} L_t$ converges on compact subsets of \mathbb{C}^2 to a unique Lawlor neck.

- ▶ Follows from blow-up arguments + recent work of Lotay–Schulze–Székelyhidi.
- ▶ The theorem contains much more information than the blow up limit. It can be interpreted as saying that there is a fixed Lawlor neck in \mathbb{C}^2 whose blow downs model the movement of L_t in a fixed, definite size neighbourhood U of $p \in X$.
- ▶ L 's as in the statement exist for any $X \neq \mathbb{R}^3 \times \mathbb{S}^1$. Moreover, if X contains a pair of sLag spheres of different Lagrangian angles, then there are such L which are compact.