

Equilibria Computation in Algorithmic Game Theory

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Algorithmic game theory

- ▶ many problems in computer science involve **interactions** between multiple self-interested **agents**;
 - ▶ traffic and vehicle routing;
 - ▶ resource allocation;
 - ▶ online advertising;
- ▶ economics and game theory: useful models, **analytical** study;
- ▶ algorithmic game theory: brings a **computational** perspective.

Can we **predict** the behaviour of complex **systems** composed of many self-interested **agents**?

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Contributions from Computer Science:

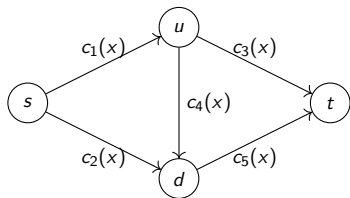
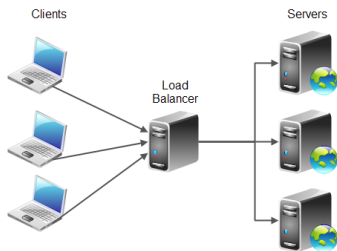
- ▶ worst-case guarantees;
- ▶ approximation bounds;
- ▶ computational complexity.

Games and equilibria

- ▶ a set of **players** N : each $i \in N$ has a **strategy set** S_i ;
- ▶ **costs** $C_i(s_i, \mathbf{s}_{-i})$ depending on the joint strategy of all players;
- ▶ **Pure Nash equilibrium** (PNE): a strategy profile where no player gains by deviating.

$$C_i(s_i, \mathbf{s}_{-i}) \leq C_i(s'_i, \mathbf{s}_{-i}) \quad \text{for all } i \in N, s'_i \in S_i.$$

Example: Congestion games



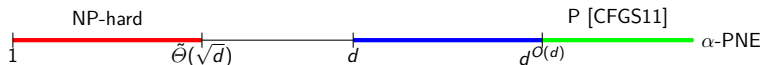
Results for congestion games

- ▶ in the **unweighted** case, PNE always exist and can be found by **best-response sequences** [Ros73].
- ▶ when players have **weights**, PNE need not exist [LO01, GMV05, FKS05].
- ▶ a more general notion: α -**approximate** equilibrium (α -PNE), for $\alpha \geq 1$;

$$C_i(s_i, \mathbf{s}_{-i}) \leq \alpha \cdot C_i(s'_i, \mathbf{s}_{-i}) \quad \text{for all } i \in N, s'_i \in S_i.$$

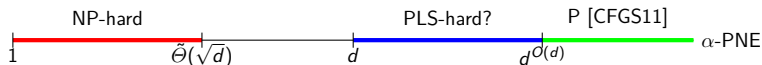
State of the art

- ▶ **polynomial** congestion games: costs are polynomials of degree d .
- ▶ **nonexistence** of exact or α -equilibria for low α . [FKS05, HKS14, CGG⁺23]
- ▶ **NP-hardness** of the exact or α -approximate decision problem for low α . [CGG⁺23]
- ▶ **existence** of α -equilibria for large α . [CF19]
- ▶ **efficient computation** of α -equilibria for even larger α . [CFG11]

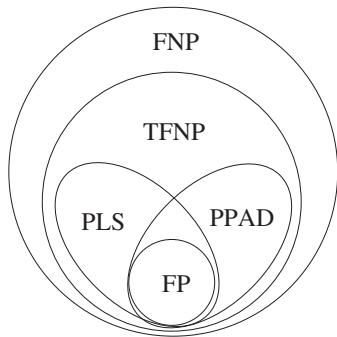


Future directions

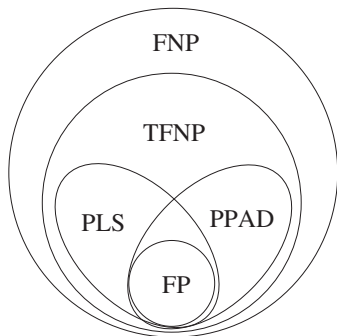
- ▶ can we **narrow** the existence gap between \sqrt{d} and d ?
- ▶ what about the complexity of finding approximate equilibria when we **know** they exist?
- ▶ PLS = Polynomial Local Search problems.



Future directions [Rou16]



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Considering random perturbations on the costs:

- ▶ What is the **average-case** complexity of best-responses?
- ▶ What is the **smoothed** complexity of best-responses?

Conclusion

- ▶ Congestion games: a natural framework to study competition.
- ▶ Game theory: Nash equilibria as a predictive concept.
- ▶ When does a game have Nash equilibria?
- ▶ How to compute Nash equilibria?

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- ▶ Game theory: Nash equilibria as a predictive concept.
- ▶ When does a game have Nash equilibria?
- ▶ How to compute Nash equilibria?

Thank you for your attention!

`https://diogopocas1991.gitlab.io`

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