

Skein Theory and the Geometric Langlands Program

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- Skein modules

Definition: (Przytycki, Turner)

Let M be an n -oriented B -manifold

R a ring with a fixed element $\sigma \in R^\times$.

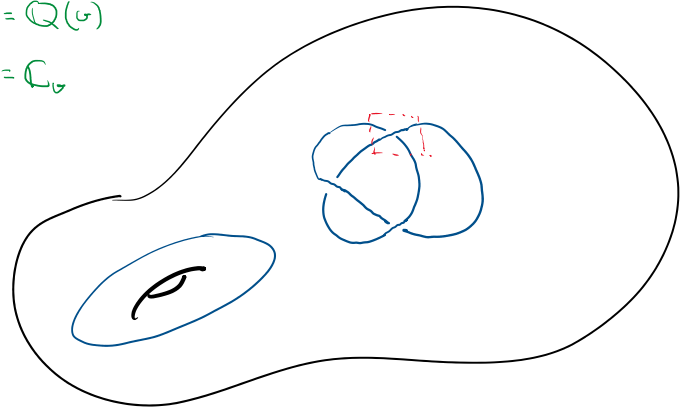
$Sk(M)$ is defined to be the R -module formally spanned by isotopy classes of framed links in M

modulo the relations

$$\boxed{\times} = \sigma \cdot \boxed{\cup} + \sigma^{-1} \cdot \boxed{\cap}$$

$$\boxed{\bigcirc} = (-\sigma^2 - \sigma^{-2}) \cdot \boxed{}$$

e.g. $R = \mathbb{Z}[\sigma, \sigma^{-1}]$
 $R = \mathbb{Q}(\sigma)$
 $R = \mathbb{C}$



Kauffman bracket skein relations.

Examples:

① (Jones, Kauffman) $Sk(\mathbb{R}^3) \cong R$

$$\downarrow$$

$$[L] \longmapsto \kappa_L(\sigma) \in \mathbb{Z}[\sigma, \sigma^{-1}].$$

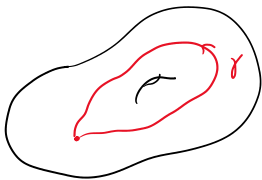
[Can think of $Sk(M)$ as an abstraction to defining a polynomial invariant of knots in M .]

② (Hatz - Przytycki) $Sk(S^2 \times S^1) \cong \mathbb{R} \oplus \bigoplus_{i=1}^{\infty} \mathbb{R} / (1 - v^{2i+4})$

Theorem (Bullcock, Przytycki-Sikora)

$$Sk_{\mathbb{C}^{v=1}}(M) \cong \mathbb{C} [Loc_{SL_2}(M)] = \mathbb{C} [Hom(\pi_1(M), SL_2)]^{SL_2}$$

$$\langle \gamma \rangle \longmapsto \left[\tau_\gamma : \rho \mapsto \text{tr}(\rho(\gamma)) \right]$$



stack

Examples: ① If $M = S^1 \times S^2$, $Loc_G(M) = SL_2 / SL_2$

$$\mathbb{C} [Loc_{SL_2}(M)] = \mathbb{C} [SL_2]^{SL_2} = \mathbb{C} [z]$$

② If $M = T^3 = S^1 \times S^1 \times S^1$,

$$Loc_{SL_2}(M) = \left\{ (A_1, A_2, A_3) \in SL_2^3 \mid \begin{array}{l} A_1 A_2 = A_2 A_1 \\ A_1 A_3 = A_3 A_1 \\ A_2 A_3 = A_3 A_2 \end{array} \right\} / SL_2(\mathbb{C})$$

Theorem (Conner, Gilmer ~'16)

$$\dim_{\mathbb{Q}(v)} Sk_{\mathbb{Q}(v)}(T^3) = 9$$

↑
"generic v"

Theorem (G - Jordan - Safranov ~'19/'22)

If M is closed, then

$$\dim_{\mathbb{Q}(v)} Sk_{\mathbb{Q}(v)}(M) < \infty$$

↑
generic v

Theorem (Gilmer - Marbaum, Detcherry - Woolfe)

$$\dim_{\mathbb{Q}(v)} Sk_{\mathbb{Q}(v)}(\Sigma_g \times S^1) = 2^{2g+1} + 2g - 1.$$

• The skein TQFT

Relative skein modules.

Definition: Let M be a 3-manifold (and $\{p_1, \dots, p_k\} \subseteq \partial M$)

R a ring with a fixed element $\sigma \in R^\times$.

$Sk(M; \{p_1, \dots, p_k\})$ is defined to be the R -module formally

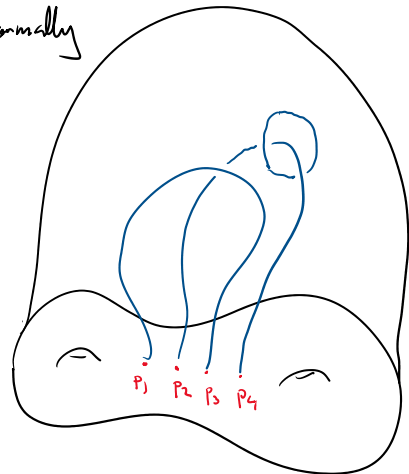
spanned by isotopy classes of framed

framed tangles ending at $\{p_1, \dots, p_k\}$.

modulo the relations

$$\boxed{\times} = \sigma \cdot \boxed{\cup} + \sigma^{-1} \cdot \boxed{\cap}$$

$$\boxed{0} = (-\sigma^2 - \sigma^{-2}) \cdot \boxed{}$$



Proposition (Walker)

Skein modules fit into a TQFT:

$$Bord_{(3,2)}^{\text{or}} \longrightarrow \text{Bimod}_R$$

$$\Sigma^2 \longrightarrow \text{SkCat}(\Sigma)$$



$$\Sigma_1 M_{\Sigma_2}^3 \longrightarrow \text{SkCat}(\Sigma_1) \text{SkMod}(M)_{\text{SkCat}(\Sigma_2)}$$





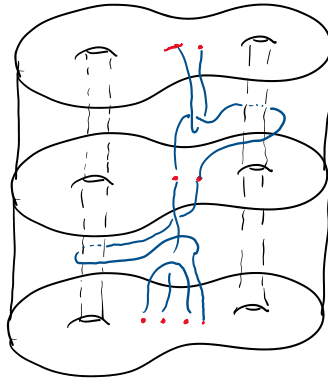
Σ a 2-manifold.

Where: $\text{SkCat}(\Sigma)$ has objects given by finite subsets $\{p_1, \dots, p_k\} \subseteq \Sigma$,

$$\text{Hom}_{\text{SkCat}(\Sigma)}(\{p_1, \dots, p_k\}, \{q_1, \dots, q_\ell\}) \quad \mathbb{R}\text{-linear category}$$

$$:= \text{Sk}(\Sigma \times [0, 1]; \{p_1, \dots, p_k\} \times \{0\} \cup \{q_1, \dots, q_\ell\} \times \{1\})$$

Composition = "stacking"



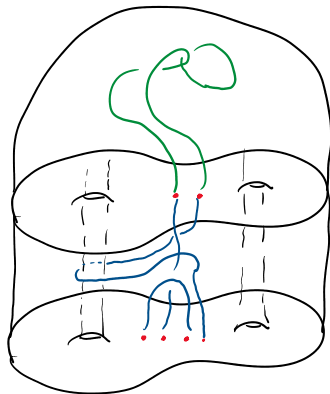
Note: $\text{End}_{\text{SkCat}(\Sigma)}(\phi) =: \text{SkAlg}(\Sigma)$.

and

Given M a 3-manifold with $\partial M \cong \Sigma$

$$\text{SkMod}(M): \text{SkCat}(\Sigma) \longrightarrow \mathbb{R}\text{-mod}$$

$$\{p_1, \dots, p_k\} \longmapsto \text{Sk}(M; \{p_1, \dots, p_k\})$$



"Gluing law":

$$\text{Sk}(M_1 \cup_{\Sigma} M_2) \cong \left[\text{SkMod}(M_1) \otimes \text{SkMod}(M_2) \right]_{\text{SkCat}(\Sigma)}$$

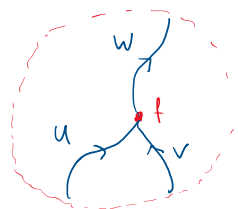
• More general skein theories

Given \mathcal{A} an R -linear ribbon braided monoidal category.

$\rightsquigarrow \text{Sk}_{\mathcal{A}}(M)$: R -module formally spanned by \mathcal{A} -labelled ribbon graphs, modulo local evaluation relations.

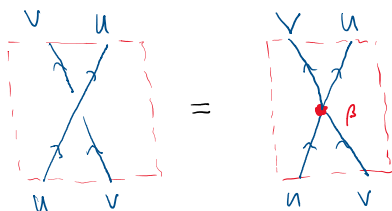
(Reshetikhin-Turaev)

$u, v, w \in \mathcal{A}$



$$f \in \text{Hom}_{\mathcal{A}}(u \otimes v, w)$$

"Universal skein relation":



Similarly, define $\text{SkCat}_{\mathcal{A}}(\Sigma)$, $\text{SkMod}_{\mathcal{A}}(M)$, etc.

cf. Beta factorization homology (Ayala-Francois) $\text{Sk}_{\mathcal{A}}(M) = H_0 \int_M \mathcal{A}$

Examples: ① $\mathcal{A} = \text{Rep}_q(G)$, $R = \mathbb{C}(q^{\pm 1/2})$ G ex. reductive group
compact Lie group
 $\rightsquigarrow \text{Sk}_G(M)$

e.g. $\text{Sk}(M) \xrightarrow{\sim} \text{Sk}_{\text{SL}_2}(M)$



② $\mathcal{A} = \text{Rep}(G)$, $R = \mathbb{C}$ $\text{Map}(M_B, BG)$ AKSZ

② $\mathcal{A} = \text{Rep}(G) \quad R = \mathbb{C}$ Map(MB) v
AKSZ
 $\rightsquigarrow \text{Sk}_{G,2}(M) = \mathbb{C}[\text{Loc}_G(M)]$

③ \mathcal{A} a modular tensor category, $R = \mathbb{C}$
 $\rightsquigarrow \text{Sk}_g(M) \cong \mathbb{C}$
framing data.

Theorem (GJS)

If M is closed then $\dim \text{Sk}_{G,2}(M) < \infty$.

Langlands (Kapustin-Witten)

4d TQFT (exists at 4d $N=4$ SYM G)

parameter $\mathcal{P} \in \mathbb{CP}^1 \cong S^2$
0, ∞

$\mathcal{Z}_{G,\mathcal{P}}(M) \stackrel{\text{proposal}}{\cong} H_0 \text{Sk}_{G,2}(M)$
3-manifold
 $q = e^{-\frac{1}{\hbar}}$

S-duality / Langlands duality: $\mathcal{Z}_{G,\mathcal{P}} \simeq \mathcal{Z}_{G^\vee,\mathcal{P}^\vee}$

where G^\vee is the Langlands dual group

$\mathcal{P}^\vee = -\frac{1}{\mathcal{P}}$

hard

Conjecture:

$\dim \text{Sk}_{G,2}(M) = \dim \text{Sk}_{G^\vee,2}(M)$

[We have checked this in a very small number of cases, e.g. $M = T^3$, $G = \text{SL}_2$, $G^\vee = \text{PGL}_2$.]

Conjecture:

(G-Satake) $\left[\text{Sk}_g(M) \cong \left| H^0(\overline{\text{Loc}}_g(M); \phi) \right|^{DT \text{ sheaf}} \right]$

Conjecture: (G-Satake)

↑
work in progress

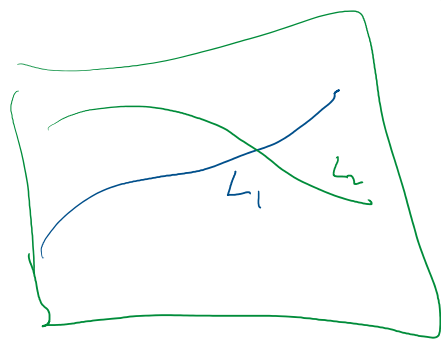
$$Sh_{G,2}(M) \cong \left(H^0 \left(Loc_G(M); \phi \right) \right)^{DT \text{ sheet}}$$

↑
perverse sheaf of "vanishing cycles".

Deformation quantization \longleftrightarrow DT sheet.

Bussi-Brav-Dupont-Joyce-Szendroi

S = holomorphic symplectic manifold



↘
 \mathcal{W}_S deformation quantization.

\mathcal{O}
 M_{L_2}

$L_1, L_2 \leftarrow (-1)$ -shifted symplectic

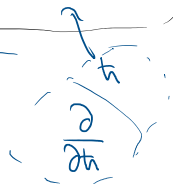
$\rightsquigarrow \exists$ perverse sheaf ϕ
on L_1, L_2 (Bussi).

$$\begin{aligned} & R\text{Ham}_{\mathcal{W}_S}(M_{L_1}, M_{L_2}) [?] \\ & \text{or } IS \\ & M_{L_1} \otimes_{\mathcal{W}_S}^L M_{L_2} \end{aligned}$$

DQ vector space

$$\xrightarrow{\sim} H^*(L_1, L_2; \phi)$$

↑
(G-S)



$M, \partial M = \Sigma$

$Loc_G(M) \rightarrow Loc_G(\Sigma)$

e.g. $M = S^3 - N(K), G = SL_2$.