

Invariance of Symplectic Cohomology under deformations.

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joint work with

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Geometry Seminar, Lisbon, 5 May 2020

Example from Morse Theory

(M, g) Riemannian manifold

$$[\alpha] \in H^1(M, \mathbb{Z}) \cong [M, S^1]$$

$$\begin{array}{ccc} t \curvearrowright \tilde{M} & \xrightarrow{f} & \mathbb{R} \curvearrowright \text{deck transformation} \\ \pi \downarrow & & \downarrow +1 \\ M & \xrightarrow{\alpha} & S^1 \end{array} \quad \begin{array}{l} \pi^* \alpha = df \\ \text{Assume } f \text{ Morse.} \end{array}$$

Morse cohomology $H^*(\tilde{M}, f)$

Chain complex generated by critical points
← Differential counts $-\nabla f$ trajectories, so
must allow infinite sums $\sum a_n x_n \leftarrow x_n \in \text{Crit } f$
provided $f(x_n) \rightarrow \infty$. $\uparrow a_n \in \mathbb{Z}$

* Equivalently: pick lifts $\text{zeros}(\alpha) \rightarrow \text{Crit}(f)$
 $x \mapsto \tilde{x}$

$$\pi^{-1}x = \left\{ t^n \tilde{x} : \begin{array}{l} n \in \mathbb{Z} \\ x \in \text{zeros}(\alpha) \end{array} \right\} \Rightarrow C^*(\tilde{M}, f) = \bigoplus_{x \in \text{zeros}(\alpha)} \mathbb{Z}((t)) \cdot \tilde{x}$$

$\nwarrow$ Laurent series

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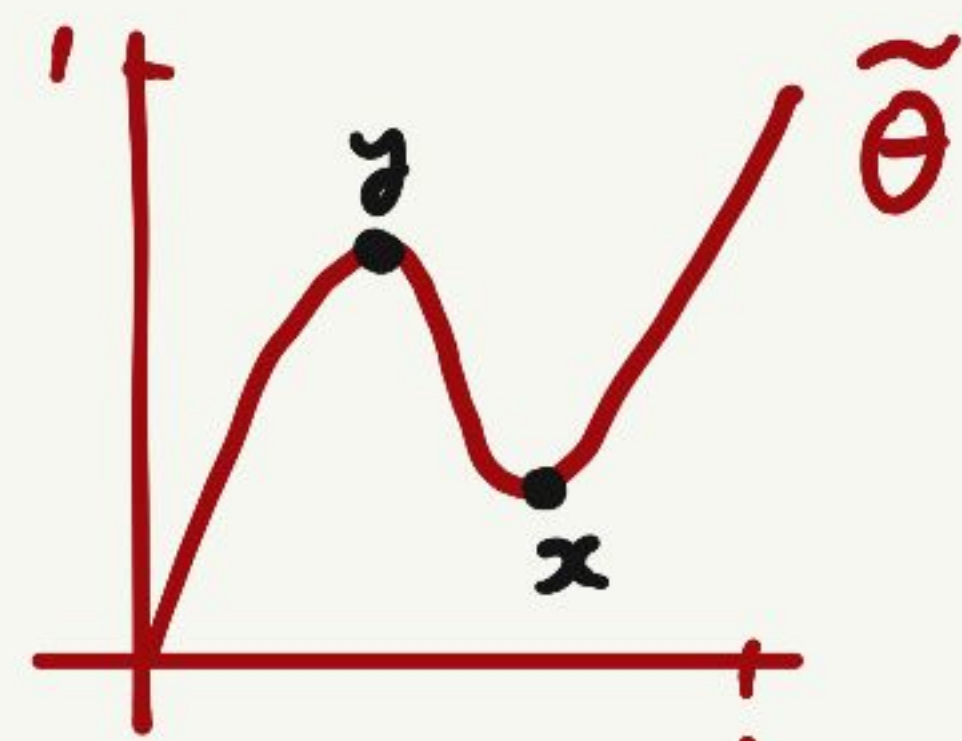
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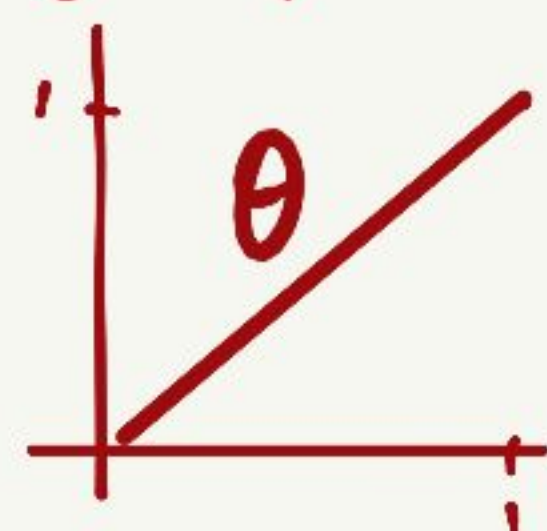
Example

$$M = S^1$$

$$\alpha = d\tilde{\theta}$$

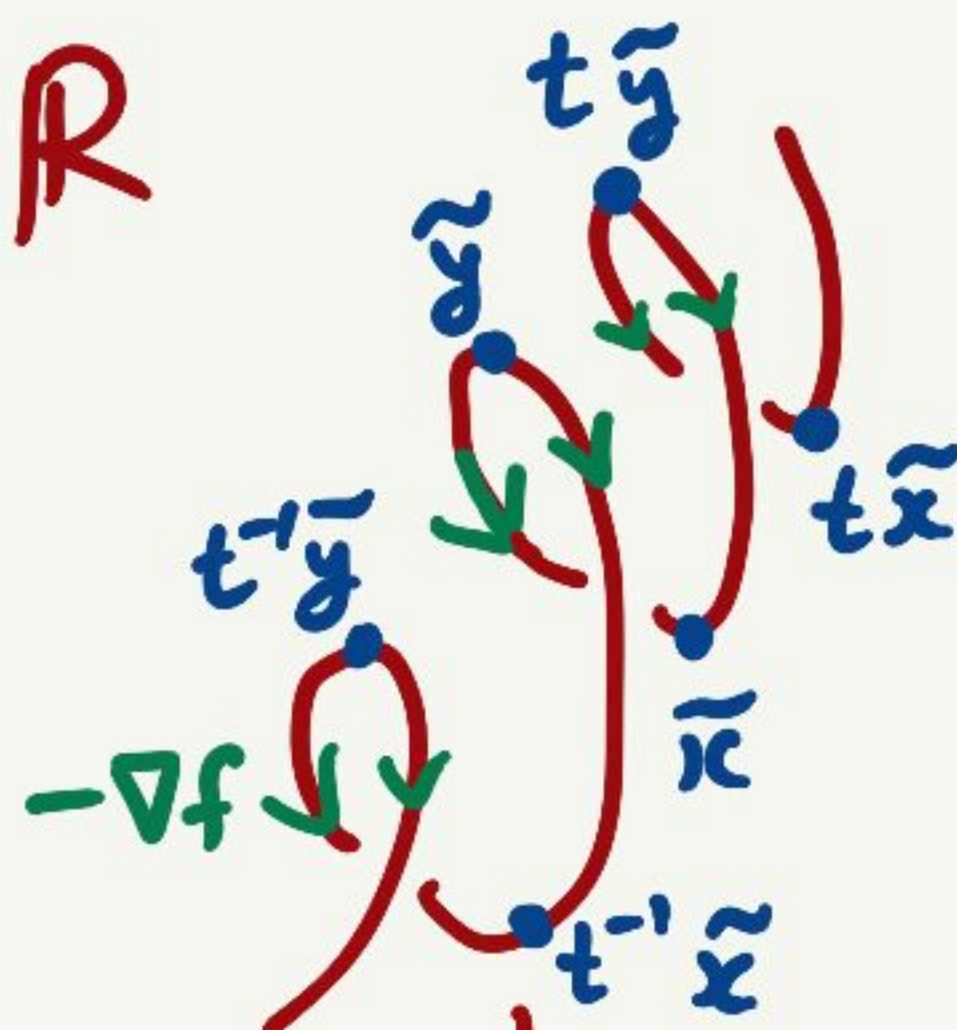


(perturbation
of angle function



$\tilde{M} = \mathbb{R}$
 $\pi^* \theta = (\text{id}: \mathbb{R} \rightarrow \mathbb{R})$
 no critical points
 so $H^* = 0$.

$$\tilde{M} = \mathbb{R}$$



$$M = S^1$$

$$\xrightarrow{f}$$

$$\mathbb{R}$$

$$\begin{array}{l} \mathbb{Z}((t)) \tilde{y} \\ \mathbb{Z}((t)) \tilde{x} \end{array} \quad \partial$$

$$\begin{aligned} \partial \tilde{x} &= \tilde{y} - t \tilde{y} \\ &= \underbrace{(1-t)}_{\text{invertible}} \tilde{y} \end{aligned}$$

$$\Rightarrow H^*(M, \alpha) = 0$$

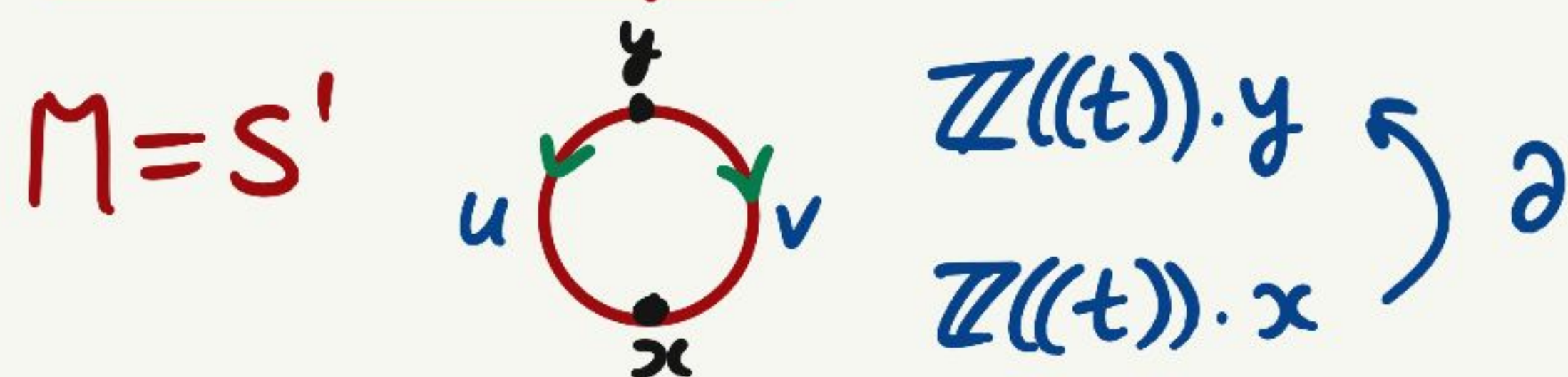
Can we just work in M ?

$$C^*(M; \alpha) = \bigoplus_{x \in \text{Zeros}(\alpha)} \mathbb{Z}(t) \cdot x$$

X_α = vector field : $g(\cdot, X_\alpha) = \alpha$

Differential $\partial x = \sum \pm \underbrace{t^{-\int u^* \alpha}}_{\text{weighted count of } X_\alpha\text{-trajectories } u} y$

In the example:



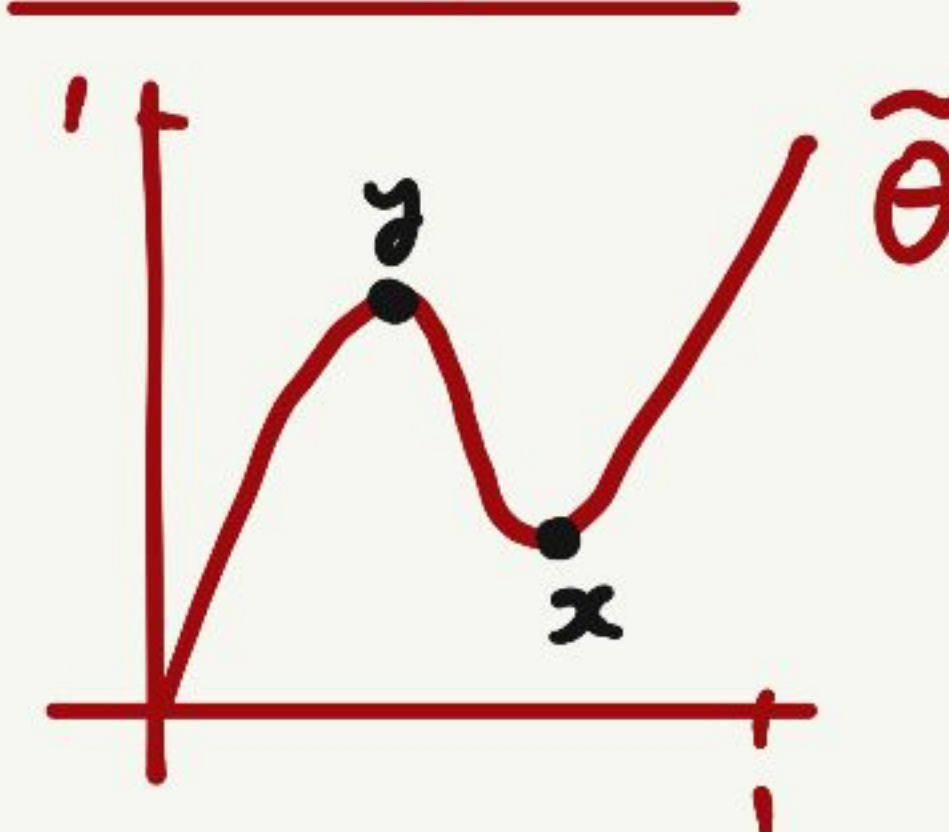
$$\partial x = t^{-\int u^* \alpha} y - t^{-\int v^* \alpha} y$$

$$\tilde{\theta}(y) - \tilde{\theta}(x)$$

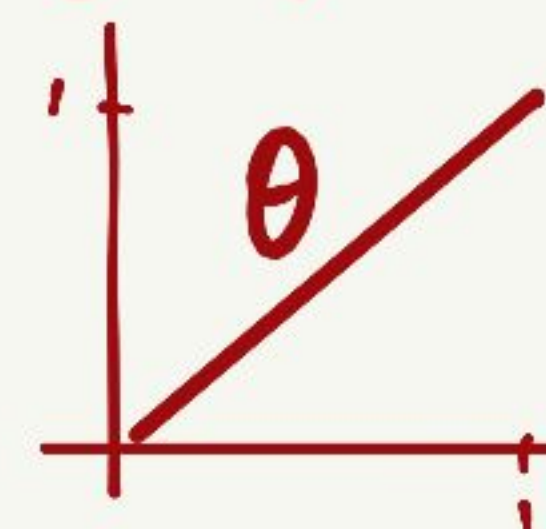
$$\tilde{\theta}(y) + 1 - \tilde{\theta}(x)$$

change of variables $x \mapsto t^{\tilde{\theta}(x)} x$
 $y \mapsto t^{\tilde{\theta}(y)} y$ gives back:
 $\partial x = (1-t)y$

Example $M = S^1$ $\alpha = d\tilde{\theta}$

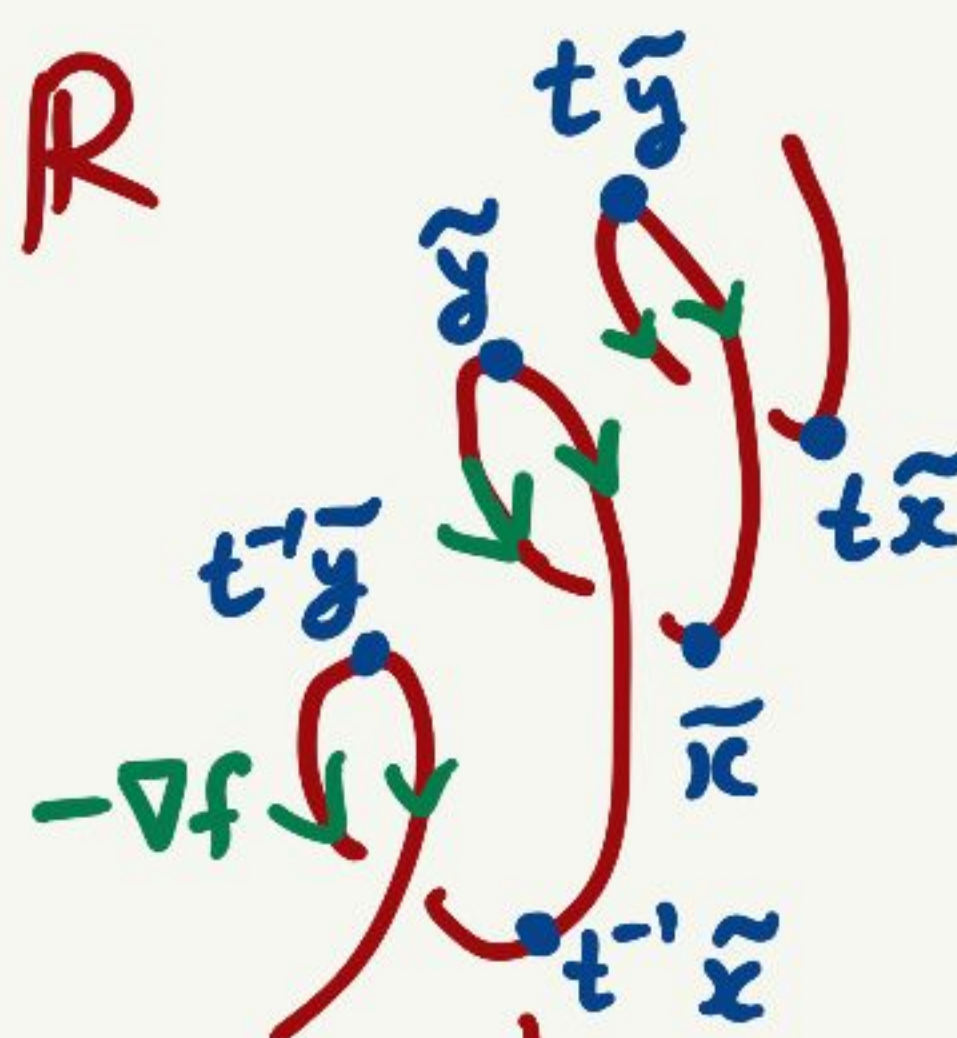


(perturbation of angle function)



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$M = S^1$

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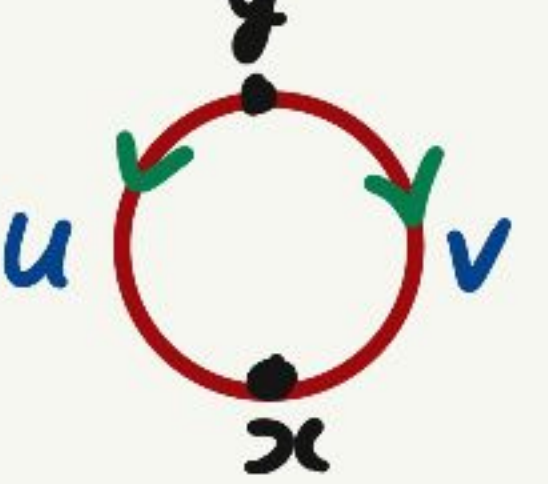
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 $y \mapsto t^{\tilde{\theta}(y)} y$ $\partial x = (1-t)y$

$H^*(M; \alpha)$ called Novikov cohomology

so Morse cohomology for M for vector field X_α
 but use local system of coefficients $\underline{\Lambda}_\alpha$
 for $[\alpha] \in H^1(M; \mathbb{Z})$

Classical invariance theorems:

1) if deform α within its class $[\alpha] \in H^1(M; \mathbb{Z})$
 then $H^*(M; \alpha)$ same up to isomorphism.

2) if deformation α_s does not preserve $[\alpha]$?

$$H^*(M; \alpha_1) \cong H^*(M; \alpha_0; \underline{\Lambda}_{\alpha_1 - \alpha_0})$$

Not entirely obvious since the flowlines have changed

need local system
 same flowlines, but infinitesimal twist of coefficients

Example $\alpha_0 = d(\text{Morse function } h)$

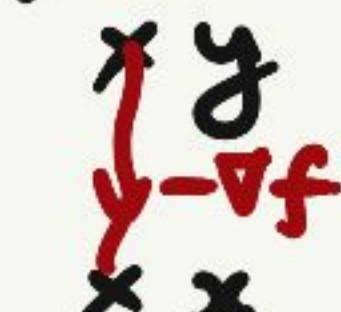
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$$\cong H^*(M; \underline{\Lambda}_\alpha)$$

e.g. $M = S^1$, h = height function, but insert $t^{-\int u^* \alpha}$.

Floer cohomology

Farber, Pajitnov, Ranicki

classical (Morse)	Floer
M manifold	$\mathcal{L}M = C^\infty(S^1, M)$ free loop space (M, ω) symplectic mfd
$f: M \rightarrow \mathbb{R}$ Morse function	$A_H: \mathcal{L}M \rightarrow \mathbb{R}$ Action functional choice of Hamiltonian $H: M \rightarrow \mathbb{R}$
Crit f	Crit $A_H = 1$ -periodic Hamiltonian orbits $x'(t) = X_H$ ($\omega(\cdot, X_H) = dH$)
g Riemannian metric	L^2 -metric $\int \omega(\cdot, J \cdot) dt$ (choice ω -compatible almost complex structure J)
$-\nabla f$ trajectory $u: \mathbb{R} \rightarrow M$ $\partial_s u = -\nabla f$	$-\nabla A_H$ trajectory $u: \mathbb{R} \times S^1 \rightarrow M$ $\partial_s u + J \partial_t u = -\nabla H$
Morse chain complex $\partial x = \pm y + \dots$ 	Floer chain complex $\partial x = \pm t^{E(u)} y + \dots$ "energy" 

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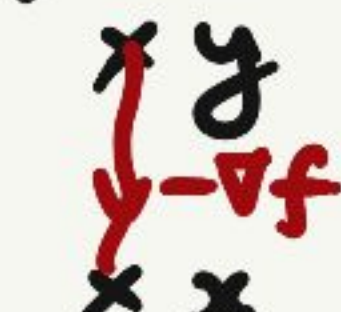
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Floer's invariance theorem 1987:

For M closed, if change H, J
 $HF^*(M, \omega, J, H)$ same up to iso.

Moser's argument

If deform ω within its class $[\omega] \in H^2(M; \mathbb{R})$
 (M, ω) same up to symplectomorphism.
 $(\Rightarrow HF^*$ same up to iso, for M closed)

For closed M :

deform H to C^2 -small Morse function f
 $\Rightarrow 1$ -orbits become critical points of f ,
 Floer traj. become $-\nabla f$ traj.

$\Rightarrow HF^* \cong H^*(M; \Lambda)$ Novikov ring behaves like $\mathbb{Z}((t))$

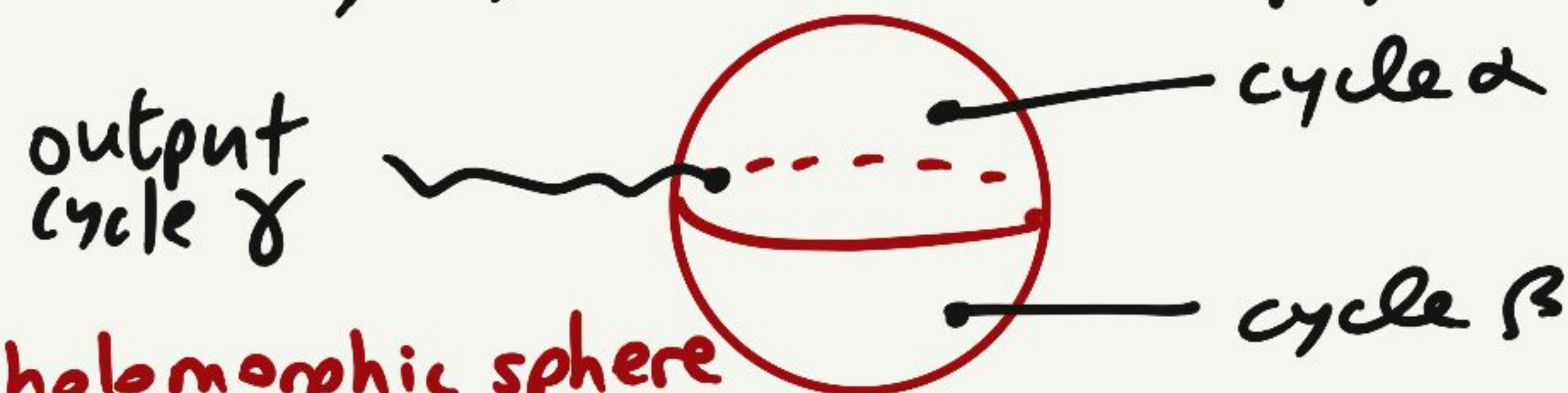
Piunikhin-Salamon-Schwarz 1996 As a ring,

$HF^* \cong QH^*(M, \omega)$



Quantum Cohomology $QH^*(M, \omega)$

$H^*(M; \Lambda)$ but deform cup product :



J-holomorphic sphere
 $\partial_s u + J \partial_t u = 0$

$$\alpha * \beta = \pm t^{E(u)} \gamma + \dots$$

"energy" = $\int u^* \omega$

Notice :

- 1) If deform J , the moduli space of spheres changes. FACT: ring QH^* same up to iso, as long as J tames ω ($\omega(v, Jv) > 0 \forall v \neq 0$)
- 2) If deform ω by a little, then ω still tames J
 $\Rightarrow$ deformation theorem

$$QH^*(M, \omega_1) \cong QH^*(M, \omega_0; \underline{\Delta \omega_1 - \omega_0})$$

Easy since don't even need to change moduli spaces.

means we insert weights $\pm \int u^* (\omega_1 - \omega_0)$ in counts of spheres

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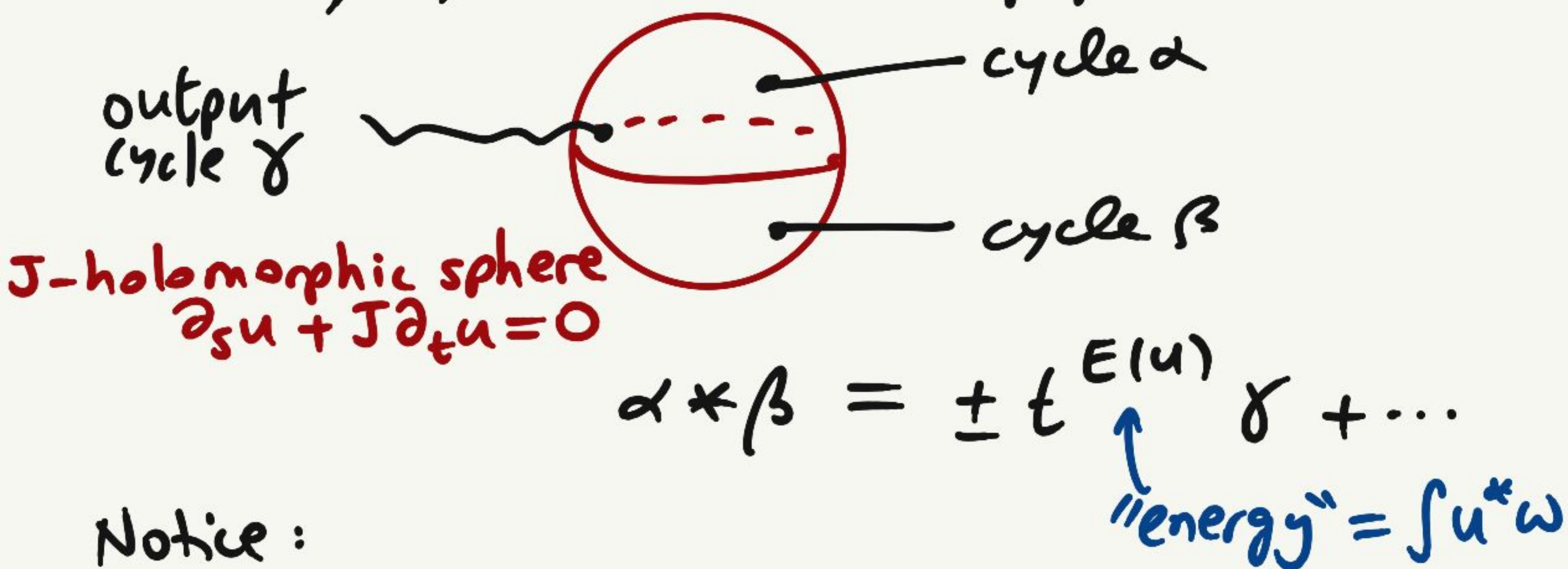
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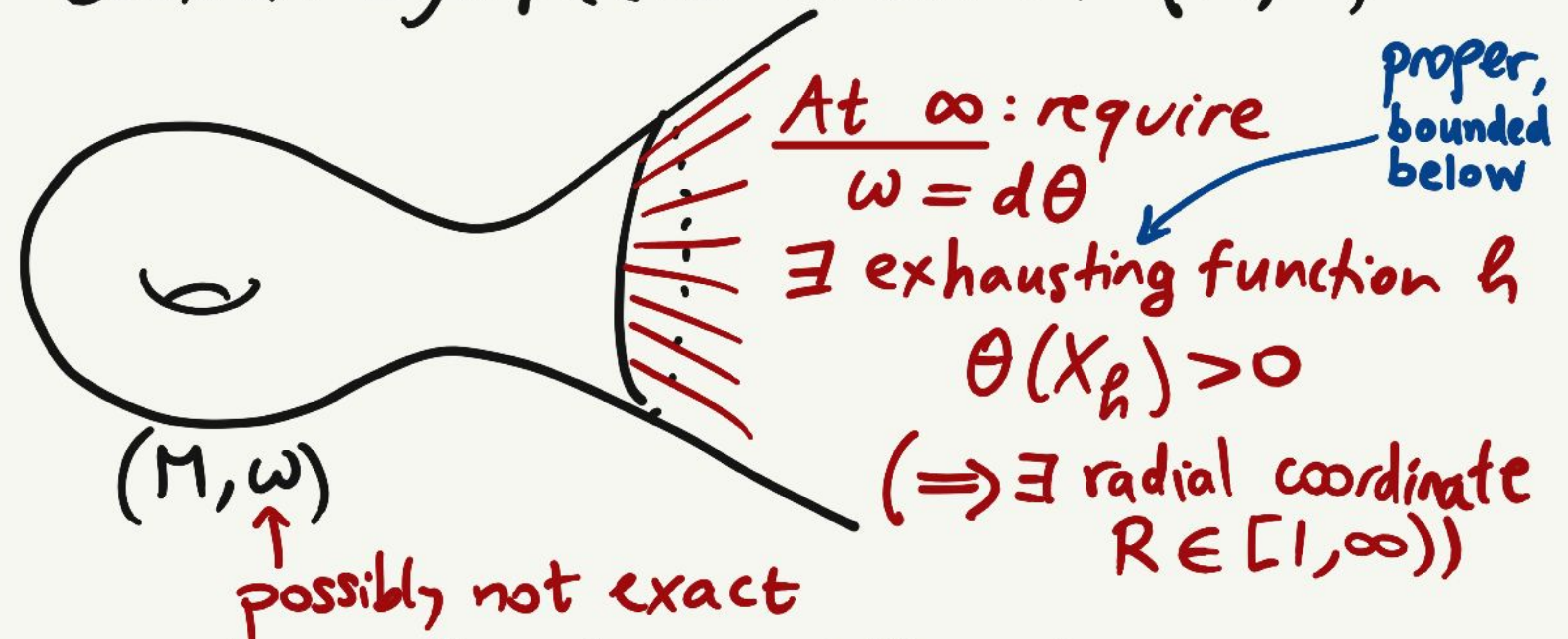
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Symplectic Cohomology

Convex symplectic manifold (M, ω)



- Examples :
- $(T^*N, \omega = d\theta)$ $h = \|p\|^2$
 - Magnetic $(T^*\Sigma, \omega = d\theta + \pi^* \sigma)$
 surface closed 2-form on Σ
 - Negative complex line bundles e.g. $\mathcal{O}(-k) \rightarrow \mathbb{CP}^m$

$$SH^*(M, \omega) = \varinjlim HF^*(M, H)$$

where H linear in R at ∞ , and in limit: slope $\rightarrow \infty$.

$$QH^*(M, \omega) = HF^*(M, H \text{ with small slope}) \xrightarrow{\subset^*} SH^*$$

Def Isomorphism of such M : symplectomorph
 $\varphi: (M, \omega_0, \theta_0) \rightarrow (M, \omega_1, \theta_1)$, $\varphi^* \theta_1 = \theta_0$ at ∞ .

Invariance Thm (R. 2010, based on Seidel 2008)

Such isos preserve SH^* .

Rmk $\Rightarrow SH^*$ independent of h .

determines R

to appear:

International Journal
of Mathematics

Observation (Benedetti - R. 2018) isos preserve

$$[\omega, \theta] \in H^2(M, \infty) \cong H_c^2(M) \quad (*)$$

Rmk $\Rightarrow$ Moser argument that deforms ω within
class $[\omega] \in H^2(M)$ may not preserve $(*)$
 $\Rightarrow (*)$ is an obstruction to existence of iso.

Rmk Liouville manifold means $\omega = d\theta$ on M

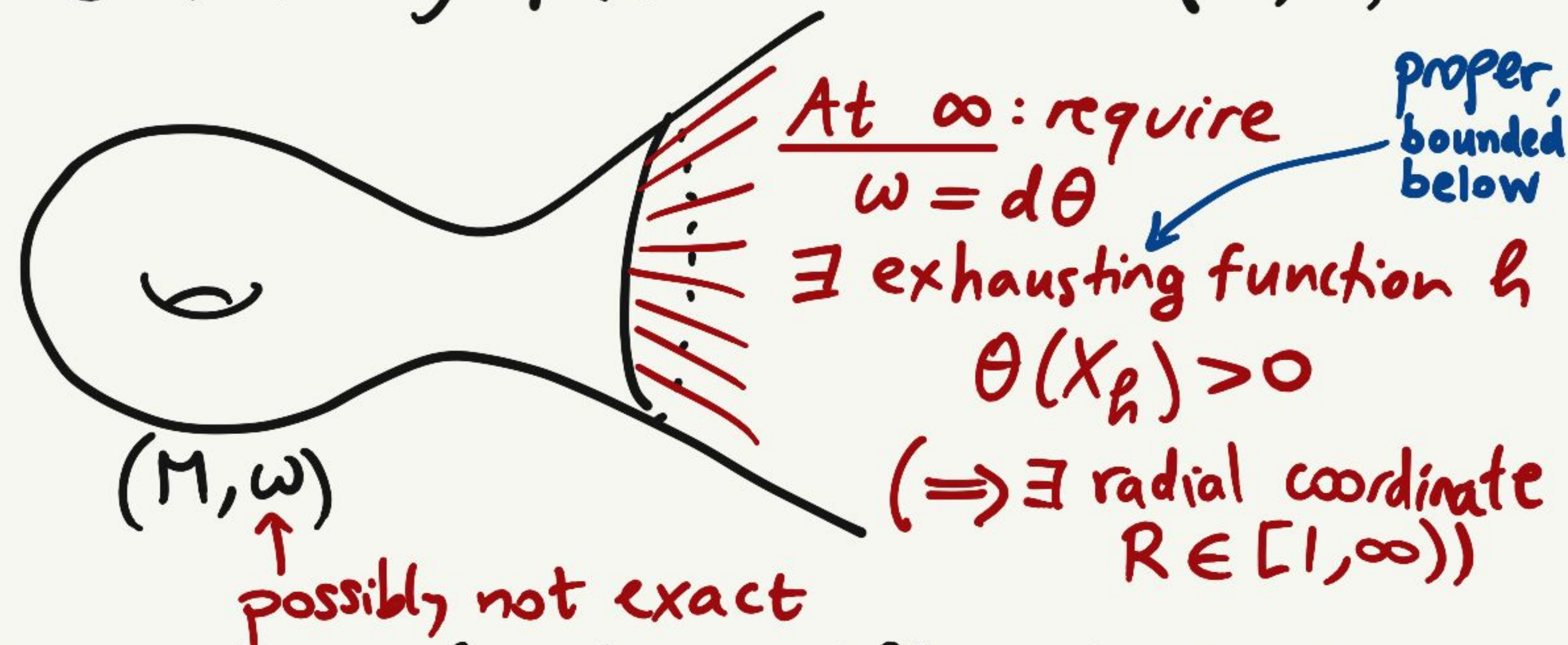
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Not same as just saying ω exact since θ
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e.g. Contreras-Macarini-Paternain 2004:

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Symplectic CoHomology

Convex symplectic manifold (M, ω)



Examples: $(T^*N, \omega = d\theta)$ $h = \|p\|^2$

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Invariance under deformations

Def Deformation of (M, ω, θ) means family (M, ω_s, θ_s) convex with exhausting h_s at ∞ .
 $(h: M \times [0, 1] \rightarrow \mathbb{R})$

Theorem 1 (B.-R.)

(after "completing at ∞ ")

$[\omega_s, \theta_s] \in H_c^2(M)$ constant $\Rightarrow \exists$ iso $(M, \omega_0, \theta_0) \rightarrow (M, \omega_1, \theta_1)$
 $\Rightarrow SH^*$ same

Theorem 2 (B.-R.)

If $[\omega_s, \theta_s]$ not constant, for small $s > 0$:

$$SH^*(M, \omega_s, \theta_s) \cong SH^*(M, \omega_0, \theta_0, \Delta_{\omega_s - \omega_0})$$

$c^* \uparrow$

$\uparrow c^*$

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moduli spaces changed

same moduli spaces as for ω_0 but use local system (infinitesimal deform.)

ring isos

For large $s \gg 0$, Theorem 2 may not hold: even the infinitesimal deformation may not exist.



$$\partial y = \pm t \underbrace{\int u^*(\omega_s - \omega_0)}_{\text{can be } < 0} t^{E(u)} \alpha + \dots$$

$\uparrow$ local system $\quad \quad \quad \uparrow$ energy ≥ 0

for convergence need total weights $\rightarrow \infty$

Local system $\underline{\Delta}_\omega$ is really on $\mathcal{L}M$

$$H^2(M, \mathbb{R}) \xrightarrow{ev^*} H^2(\mathcal{L}M \times S^1, \mathbb{R}) \xrightarrow{\text{project to Künneth summand}} H^1(\mathcal{L}M, \mathbb{R})$$

$$[\omega] \xrightarrow{\text{transgression}} [\tau\omega]$$

If $\tau\omega_s \in \mathbb{R}_{\geq 0} \cdot (\tau\omega_0 + \zeta_0) \in H^1(\mathcal{L}M, \mathbb{R})$

then during the deformation can keep the local system constant = $\underline{\Delta}_{\tau\omega_0 + \zeta_0}$

Theorem 3 (B.-R.)

$$SH^*(M, \omega_s, \theta_s, \underline{\Delta}_{\zeta_s}) \cong SH^*(M, \omega_0, \theta_0, \underline{\Delta}_{\zeta_0})$$

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Application 1

$$M = T^*S^2$$

$$\omega_\sigma = d\theta + \pi^*\sigma$$

$$SH^*(T^*S^2, \omega_\sigma) \cong SH^*(T^*S^2, d\theta, \underline{\Delta}_{\tau\pi^*\sigma})$$

Thm. 3

$$\cong H_{2-*}(\mathcal{L}S^2; \underline{\Delta}_{\tau\sigma})$$

R. 2009
(based on Viterbo 1999)

$$= \begin{cases} H_{2-*}(\mathcal{L}S^2; \wedge) & \text{if } [\sigma] = 0 \\ 0 & \text{if } [\sigma] \neq 0 \in H^2(S^2; \mathbb{R}) \end{cases}$$

R. 2009

For $\dim N \geq 3$, T^*N not convex at ∞ , but Groman-Merry 2018 constructed $SH^*(T^*N, \omega_\sigma)$ and showed $\cong SH^*(T^*N, d\theta, \underline{\Delta}_{\tau\pi^*\sigma})$, using the key energy estimate that we used in Theorem 3.

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$\pi: T^*S^2 \rightarrow S^2$
closed 2-form on S^2

Application 2

locally $\mathbb{R}^n \subset \mathbb{C}^n$

Fukaya category $F(M)$

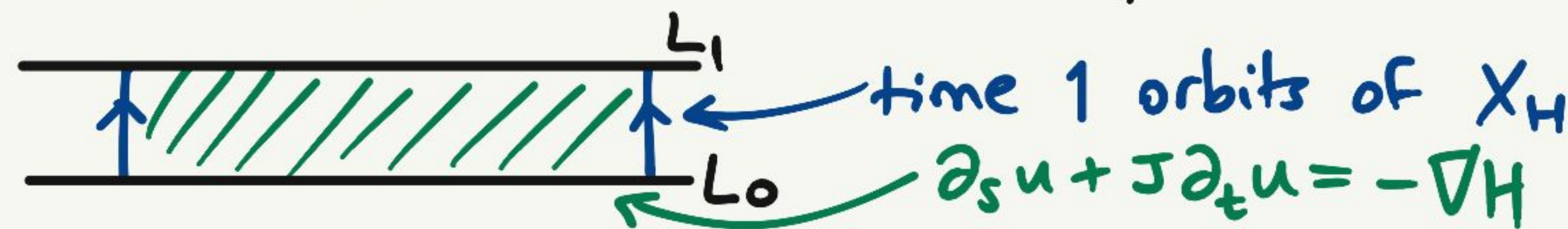
objects: Lagrangian submanifolds $L \subset M$

$$\text{hom}(L_0, L_1) = CF^*(L_0, L_1)$$

Lagrangian Floer chain complex



Actually need a Hamiltonian perturbation

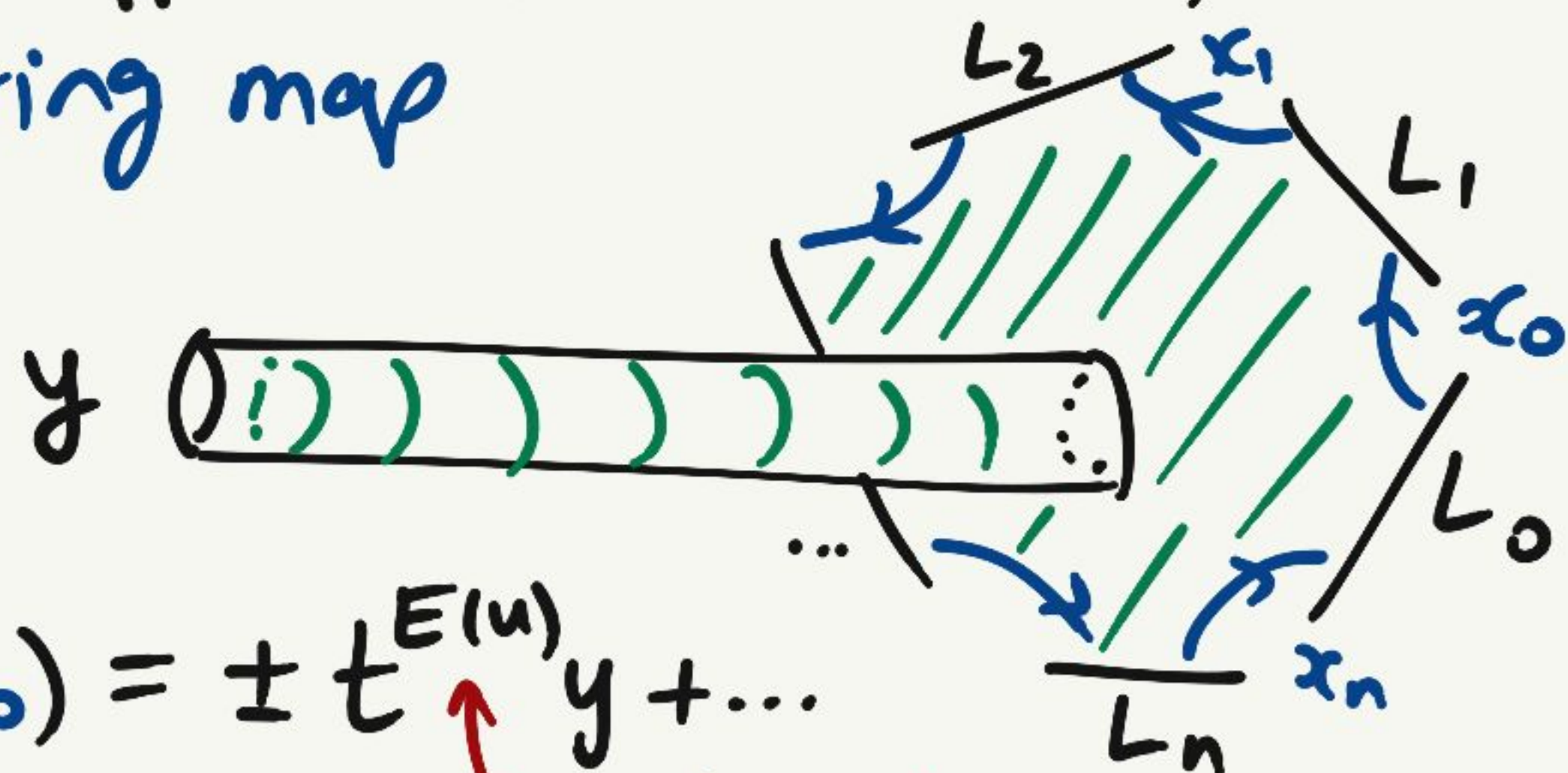


$\Rightarrow$ just the Lagrangian boundary version of $HF^*(M, H)$

If M not closed, define wrapped Fukaya cat. by taking $\varinjlim$ like we did for SH^* .

$$OC^* : HH_*(F_{\text{wrapped}}(M)) \rightarrow SH^*(M)$$

Open-closed string map



$$OC(x_n \otimes \dots \otimes x_0) = \pm t^{E(u)} y + \dots$$

topological energy

Abouzaid 2010 "generation criterion" (for M exact)

If $OC(\alpha) = 1 \in SH^*$ and α involves only $L_0, \dots, L_n$ then $L_0, \dots, L_n$ split-generate category.

R. - Smith 2012 (for M Fano)

$QH^* = \bigoplus QH^*_\lambda \leftarrow$ generalized eigensummands of $C_*(M)^*$. $\odot QH^*$ carries over to OC which is a module hom over SH^*

$$OC = \bigoplus (OC_\lambda : HH_*(F_{\text{wrapped}, \lambda}) \rightarrow SH^*_\lambda)$$

and generation holds here $\uparrow$ if hit unit here $\uparrow$

Same holds for F_λ and QH^*_λ .

Application 2

locally $\mathbb{R}^n \subseteq \mathbb{C}^n$

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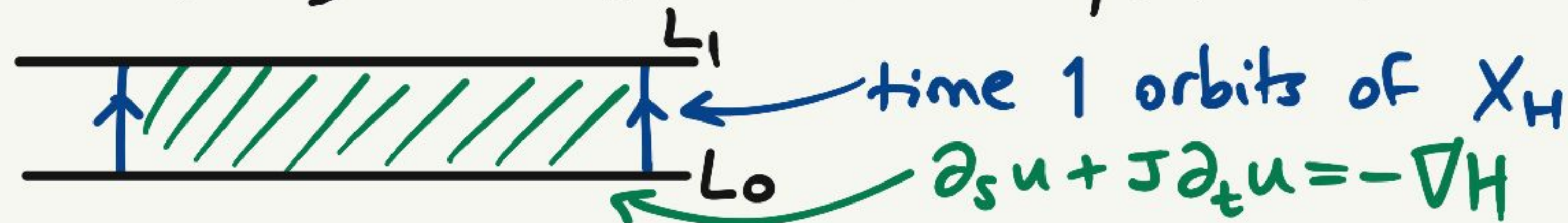
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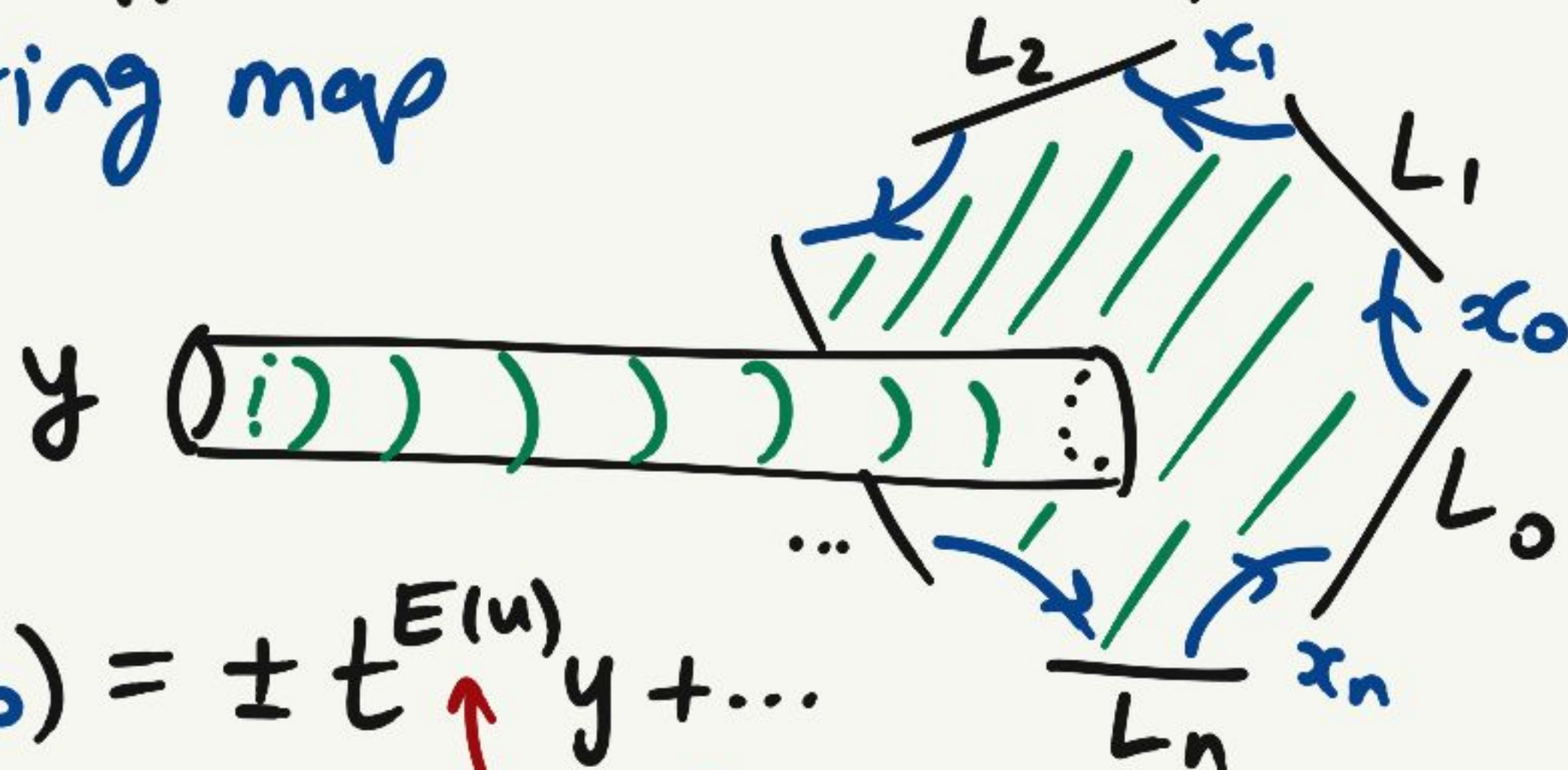


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Example $\mathbb{CP}^2$

moment map $\mathbb{CP}^2 \xrightarrow{\pi}$

$$L = \pi^{-1}(\text{barycentre}) \cong \text{torus } S^1 \times S^1$$

$$c_1 = 3\omega$$

$$QH^* = \Lambda[x]/(x^3 - t) \cong \Lambda \oplus \Lambda \oplus \Lambda$$

eigenspaces for x

$\omega \leftrightarrow x$

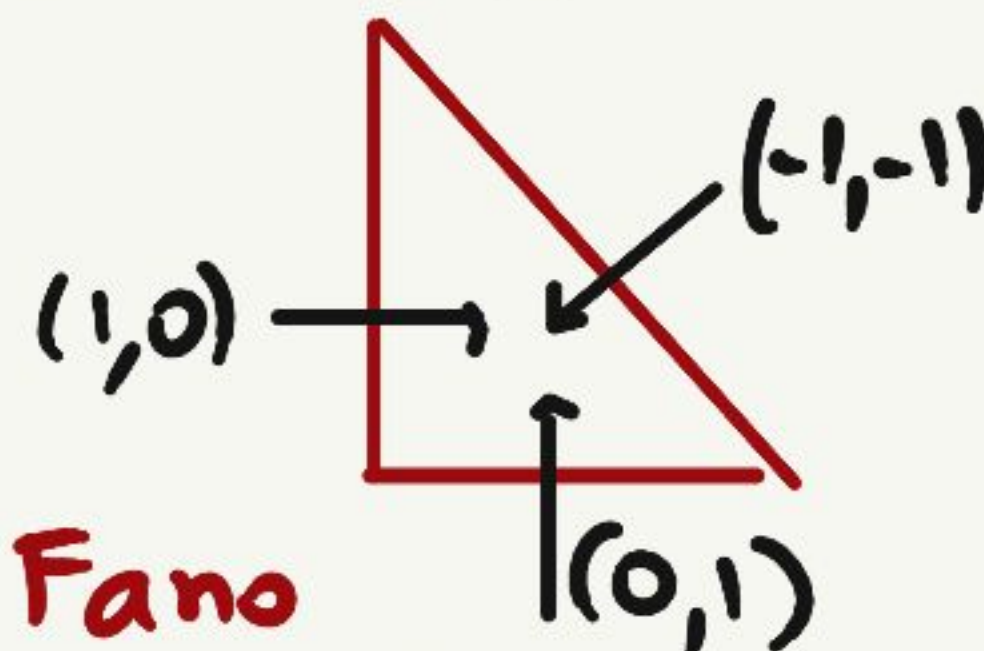


$$\text{Superpotential } W = z_1 + z_2 + t z_1^{-1} z_2^{-1}$$

Batyrev/Givental : $QH^* \cong \text{Jac}(W)$
1993 1998

for M toric Fano

Cho-Oh : Crit W determine holonomies on L
2006 s.t. $HF^*(L, L, \text{hol}) \neq 0$



Above get L with 3 holonomies
 $\lambda = W = \text{critical value}$ are 3 evals of c_1

By R. - Smith 2012:

$$OC^0 : HF(L_\lambda, L_\lambda) \rightarrow QH^*_\lambda = \Lambda$$

$OC^0(\text{point}) \neq 0$ due to "constant solution at point" field so any non-zero elt is unit
 $\Rightarrow L_\lambda$ generates

R. 2015:

For non-compact Fano toric manifold
(+ assumptions to ensure SH^* exists):

$$SH^*(M, \omega) \cong Jac(W) \quad (\text{not } QH^*!) \\ \cong QH^*(M, \omega) PD[D_i]$$

↑ localize ring at
toric divisors

Ostrover-Tyomkin 2009:

If superpotential W is Morse then QH^* is
semi-simple i.e. $\oplus$ fields.

$\Rightarrow$ the generation trick for $\mathbb{CP}^2$ essentially works.

Deformation argument: (M, ω) toric Fano

$\Rightarrow \exists$ family of toric Kähler forms ω_F near ω

Moment polytope $\Delta_F = \{y \in \mathbb{R}^n : \langle y, e_i \rangle \geq F(e_i)\}$
 $[\omega_F] = \sum -F(e_i) PD[D_i]$
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$e_i =$ inward normals
to polytope

monotone ω :
($F(e_i) = 1, [\omega_F] = c_1$)

R. 2015: For generic F (so deform ω to ω_F)

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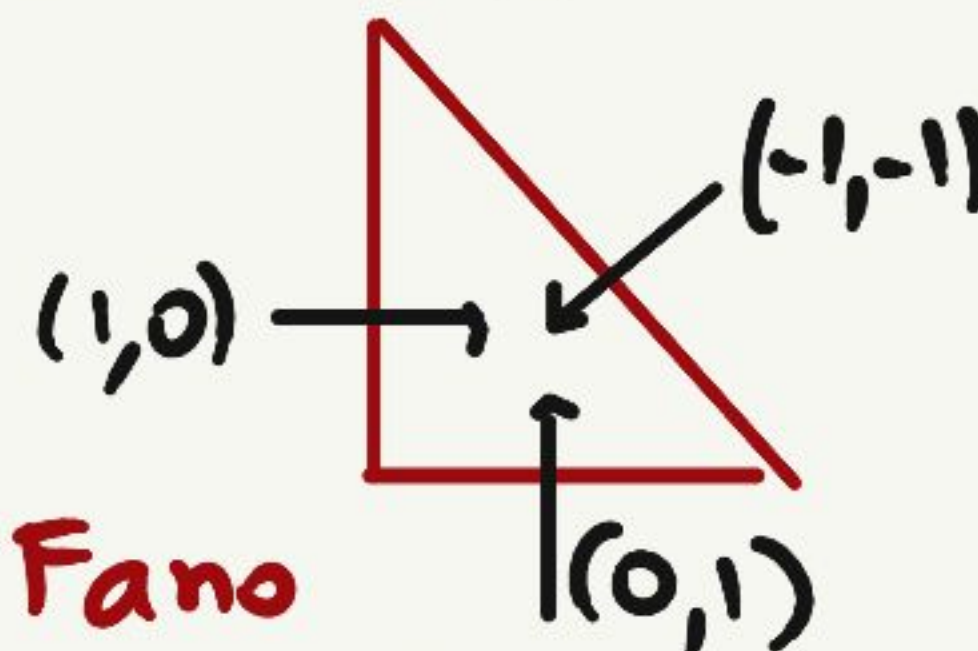
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$$W_F = \sum t^{-F(e_i)} z^{e_i} \quad \left(\begin{array}{l} \text{monotone } \omega: \\ F(e_i) = 1, [\omega_F] = c_1 \end{array} \right)$$

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More precisely: if W Morse but $\exists$ several
critical points of W with same eigenvalue λ ,
then argument of $\mathbb{CP}^2$ has an issue:

$$QH^*_\lambda = 1 \oplus \dots \oplus 1 \quad \text{e.g. } (1, 0, \dots, 0) \\ \text{not a unit}$$

Deforming ω we can separate these
eigenvalues, then do a limiting argument
to show that the limit holonomies make the
 L_λ hit all 1 summands, so (several) L_λ 's
generate F_λ .

↑ OC_λ hits $(1, 1, \dots, 1)$

So deforming ω can be useful in symplectic
topology even if you seek results about the
undeformed ω .

Thank you for listening!