



**NYU**

Center for  
Data Science



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# Progress and hurdles in the statistical mechanics of deep learning

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IST seminar series Mathematics, Physics & Machine Learning

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## **Collaborators:**

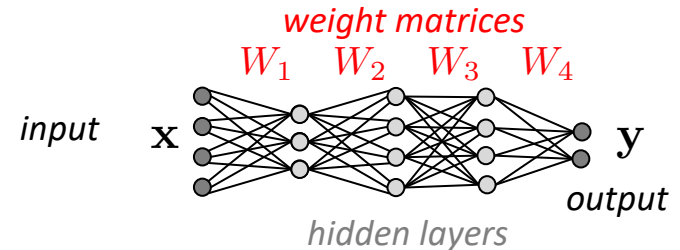
Andre Manoel (Owkin), Jean Barbier (ICTP Trieste), Clément Luneau (EPFL),  
Nicolas Macris (EPFL), Florent Krzakala (ENS Paris), Lenka Zdeborova (IPHT Saclay)

# Understanding machine learning with deep neural nets

## ▷ Supervised learning with neural networks

▷ training data  $\mathcal{D} = \{\mathbf{y}^{(k)}, \mathbf{x}^{(k)}\}_{k=1}^P$

▷ fit with class of parametrized functions  $\mathbf{y} = f(\mathbf{W}_L f(\mathbf{W}_{L-1} \dots f(\mathbf{W}_1 \mathbf{x})))$



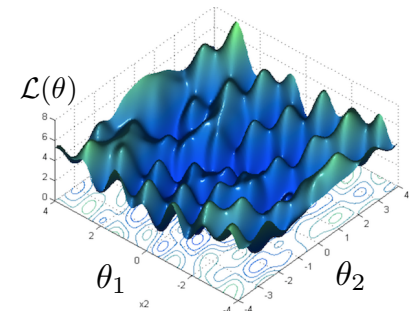
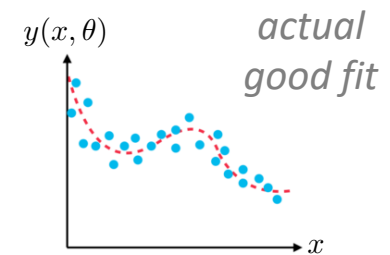
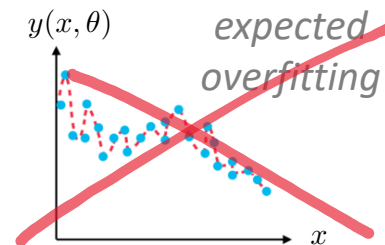
## ▷ Impressive performances (automatic vision, natural language processing etc.)

## ▷ Interesting properties

▷ universal approximators

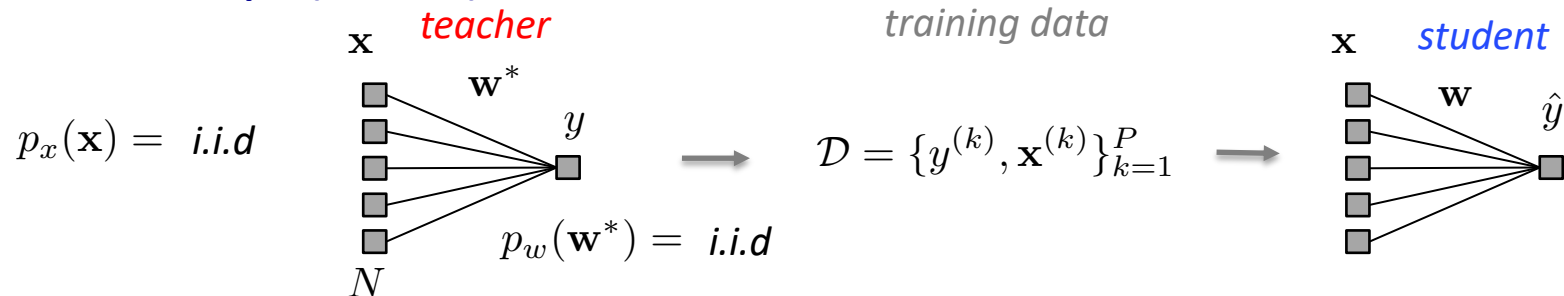
▷ not prone to overfitting

▷ train with local descent algorithm despite of non-convexity



# Statistical mechanics of learning, initiated in the 80s

▷ **Focus on simple (solvable) models**



▷ **Consider the Bayesian posterior statistics**  $p(\mathbf{w}|\mathcal{D}) = \frac{p(\mathcal{D}|\mathbf{w}) p_w(\mathbf{w})}{p(\mathcal{D})}$   
*e.g. Bayes optimal estimator (minimum mean square error)*

$$\min_{\hat{\mathbf{w}}} \int d\mathbf{w} (\mathbf{w} - \hat{\mathbf{w}})^2 p_S(\mathbf{w}|\mathcal{D}) \longrightarrow \hat{\mathbf{w}}_{\text{MMSE}} = \int d\mathbf{w} \mathbf{w} p_S(\mathbf{w}|\mathcal{D})$$

▷ **The thermodynamic limit = infinitely large model**

→ typical cases concentrate at the average

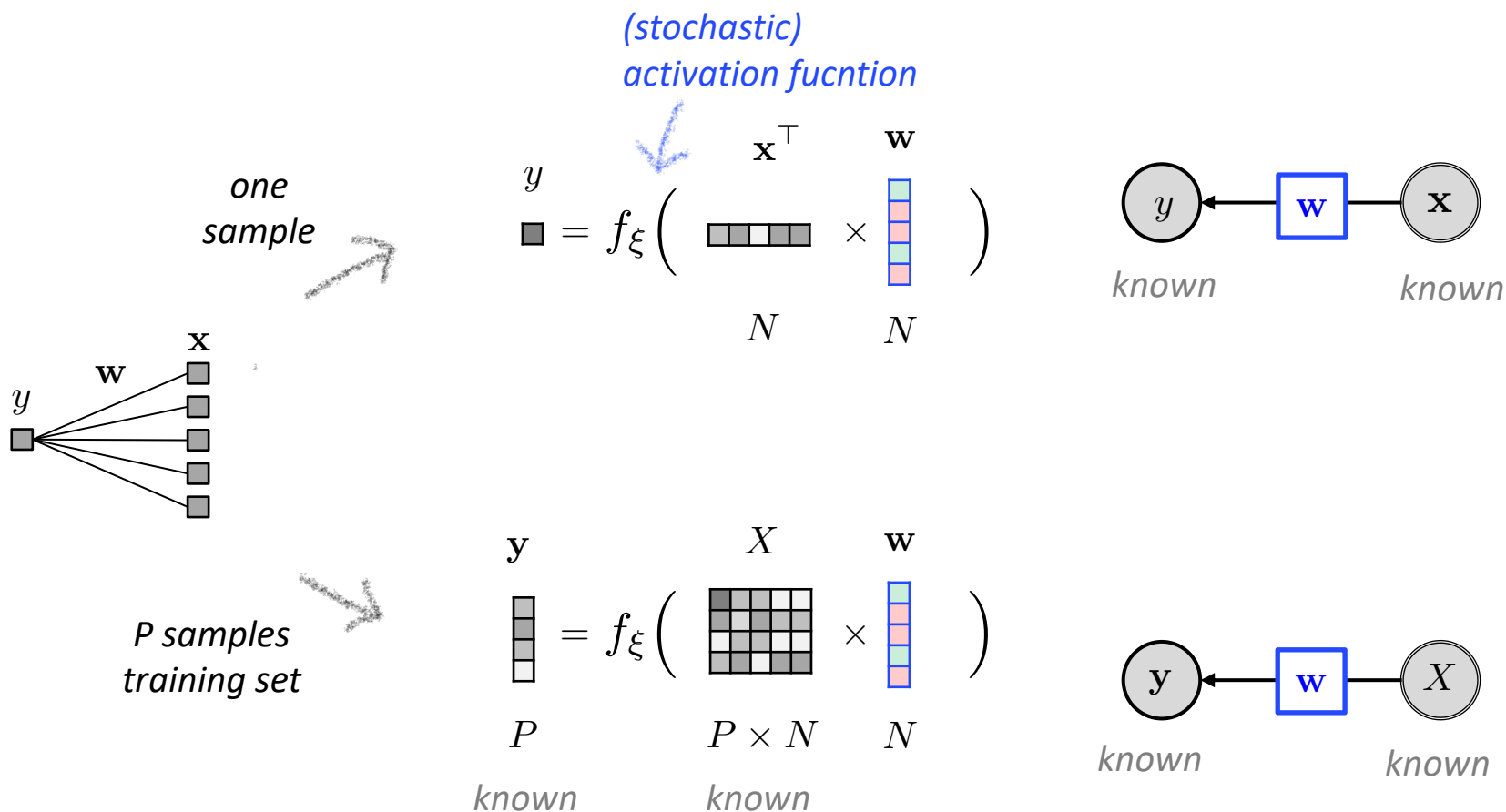
$$N \rightarrow \infty \quad \alpha = P/N$$

## Mean-field tools from the stat. phys. of disordered systems:

*e.g. Bayes optimal square error*  $\text{MMSE}(\alpha) = \lim_{N \rightarrow \infty} \frac{1}{N} \int d\mathbf{w} (\mathbf{w} - \hat{\mathbf{w}}_{\text{MMSE}})^2 p_S(\mathbf{w}|\mathcal{D})$

Starting point:

# Perceptron a.k.a Generalized Linear Model (GLM)







# Mean-Field methods for statistical inference analysis

## The tools

### Information theoretic analysis

Non-rigorous computations of asymptotic posterior statistics

*replica method*

*high temperature expansions  
(naïve MF, TAP)*

Mathematical rigorous proofs of the conjecture

*Guerra interpolation,  
Adaptive interpolation*

### Algorithms

Message passing algorithms for inference on finite size models

*belief propagation (BP),  
approximate message passing (AMP),  
expectation propagation (EP)*

Statistical analysis of asymptotic performance of message passing algorithms

*state evolution (SE)*

# “Mean-field approximations” in deep learning literature

- more general than tools above
- neglect correlations thanks to randomness in the thermodynamic (large-size) limit

## \* Analysis of statistical of inference Focus of this talk

*non-exhaustive!*

Reviews: - Zdeborová & Krzakala (2016) *Statistical physics of inference: Thresholds and algorithms*.  
 - Gabrié. (2020) *Mean field inference methods for neural networks*.

## \* Signal propagation in deep neural networks

- Trainability of very deep network at init. e.g. Schoenholz et al.(2017). *Deep Information Propagation*.
- Separation of structured data  
 e.g. Cohen, et al (2020). *Separability and geometry of object manifolds in deep neural networks*.

## \* Role of over-parametrization in trainability with Gradient Descent methods

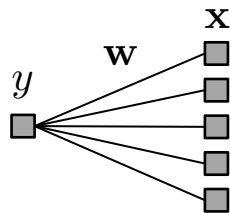
- Convergence of SGD for 2-layers neural networks  
 Chizat & Bach (2018), Mei, Montanari & Nguyen (2018), Rotskoff & Vanden-Eijnden (2018)
- Neural Tangent Kernels, Equivalence to Gaussian processes, “Lazy training”  
 Jacot et al (2018), Lee et al (2019), review: Bahri et al (2020) *Statistical Mechanics of Deep Learning*
- Online learning e.g. Goldt, et al (2019). Dynamics of stochastic gradient descent for two-layer neural networks in the teacher-student setup

## \* Gradient Descent algorithms and landscape interactions

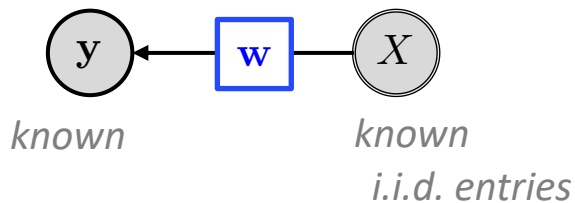
Dauphin et al (2014). Identifying and attacking the saddle point problem in high-dimensional non-convex optimization  
 Sarao Mannelli & Zdeborova (2020). *Thresholds of descending algorithms in inference problems*.

# From perceptron/GLM with random i.i.d. matrices to deep neural networks ?

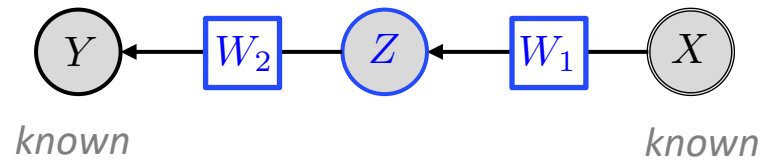
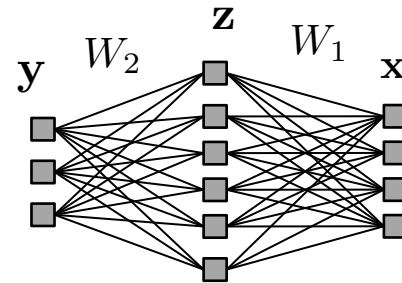
*perceptron*



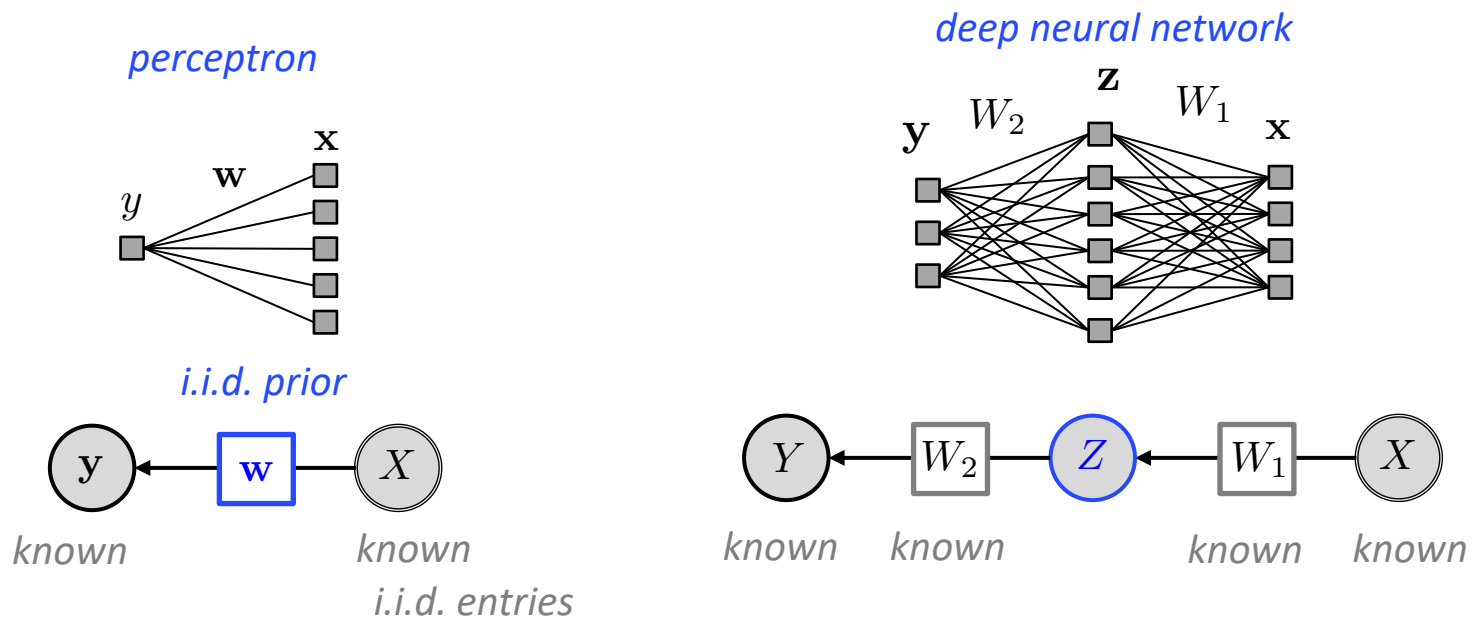
*i.i.d. prior*



*deep neural network*

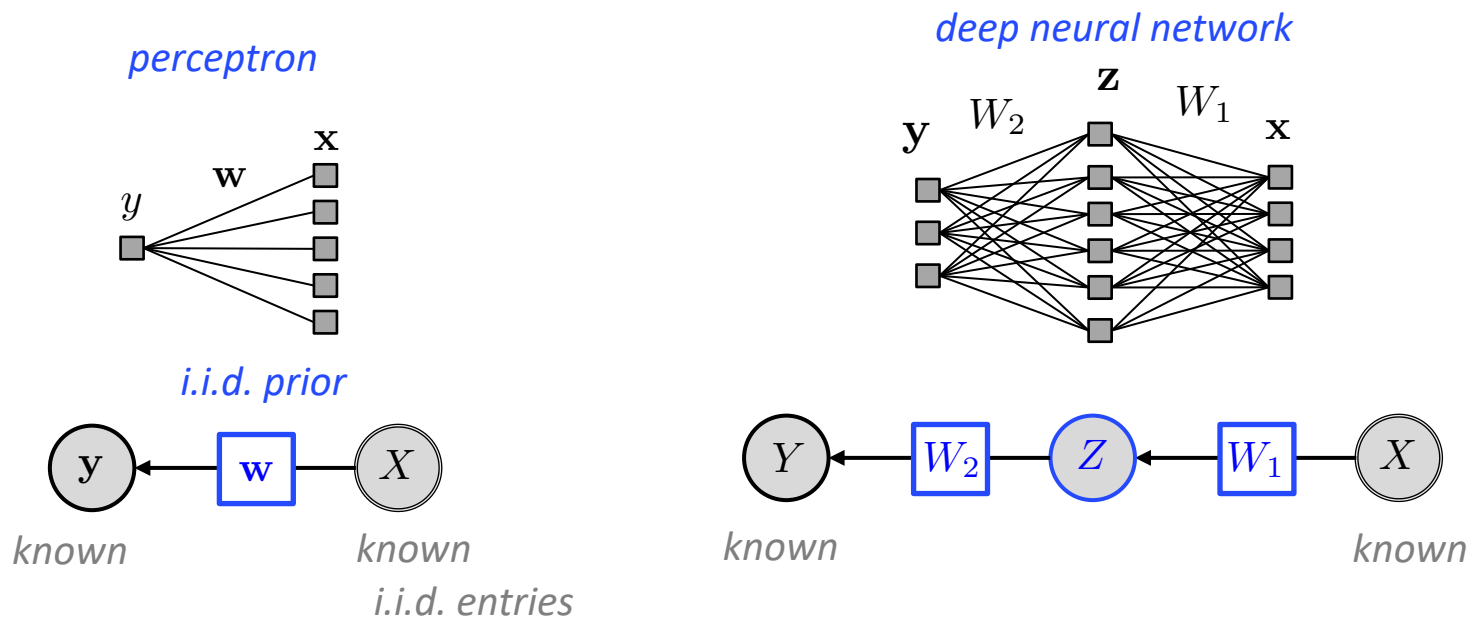


# From perceptron/GLM with random i.i.d. matrices to deep neural networks ?



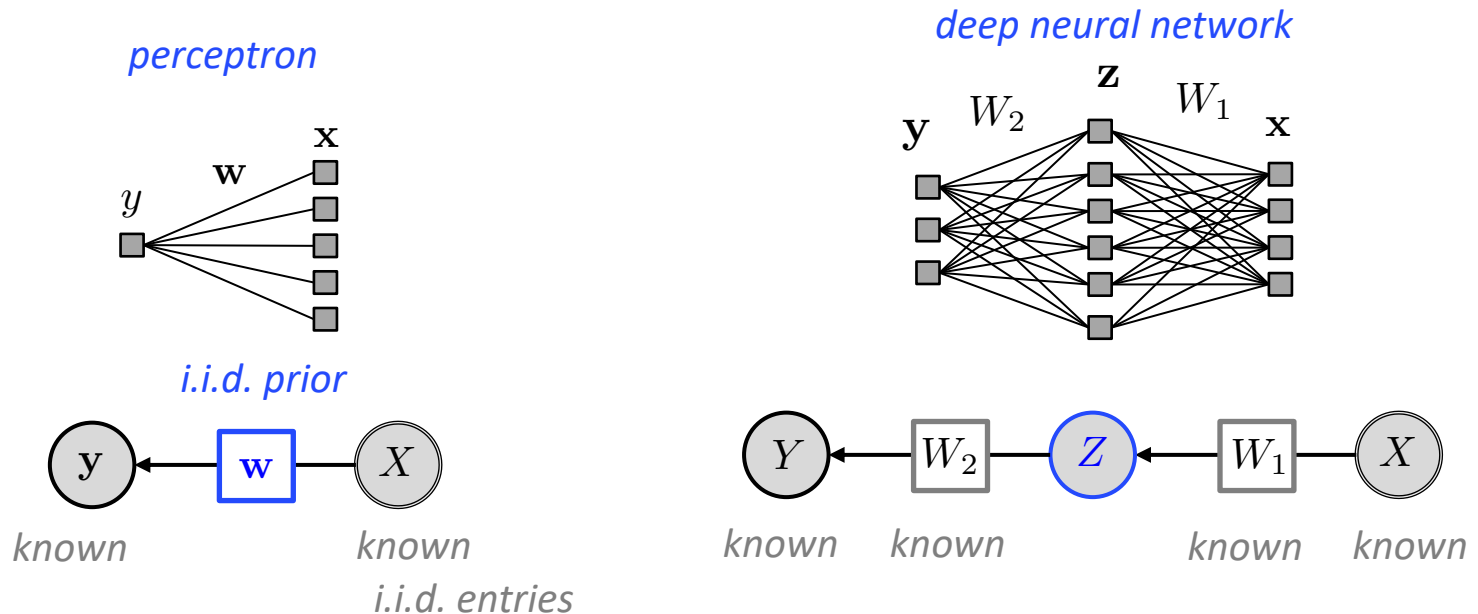
- 1. Inference of layers variables in deep networks (with learned weight matrices)**
- 2. The challenge of weight inference and structured weights**

# From perceptron/GLM with random i.i.d. matrices to deep neural networks ?



1. Inference of layers variables in deep networks (with learned weight matrices)
2. The challenge of weight inference and structured weights

# From perceptron/GLM with random i.i.d. matrices to deep neural networks ?



**1. Inference of layers variables in deep networks (with learned weight matrices)**

2. The challenge of weight inference and structured weights





# Layers inference in deep neural network with i.i.d weights

$$\begin{array}{c}
 \mathbf{y} \\
 \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array}
 = f_{\xi} \left( \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} \times f_{\xi} \left( \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} \times \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} \right) \right) \\
 M \\
 \text{known}
 \end{array}
 \quad
 \begin{array}{c}
 \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} \\
 M \times K \\
 \text{known}
 \end{array}
 \quad
 \begin{array}{c}
 \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} \\
 K \times N \\
 \text{known}
 \end{array}
 \quad
 \begin{array}{c}
 \mathbf{x} \\
 \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} \\
 N
 \end{array}
 \quad
 \begin{array}{l}
 N \text{ input dim} \\
 K \text{ hidden dim} \\
 M \text{ output dim}
 \end{array}$$

*i.i.d. entries* (pointing to  $W_1$  and  $W_2$ )  
*i.i.d. prior* (pointing to  $\mathbf{x}$ )

**decompose the problem in sub-problems**  $N \rightarrow \infty$   $\alpha_1 = K/N$   $\alpha_2 = M/N$

$$\left\{ \begin{array}{l}
 \mathbf{y} \\
 \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array}
 = f_{\xi} \left( \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} \times \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} \right) \approx \text{GLM} \\
 \mathbf{z} \\
 \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array}
 = f_{\xi} \left( \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} \times \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} \right) \approx \text{GLM}
 \end{array} \right.$$

*hidden layer state* (pointing to  $\mathbf{z}$ )

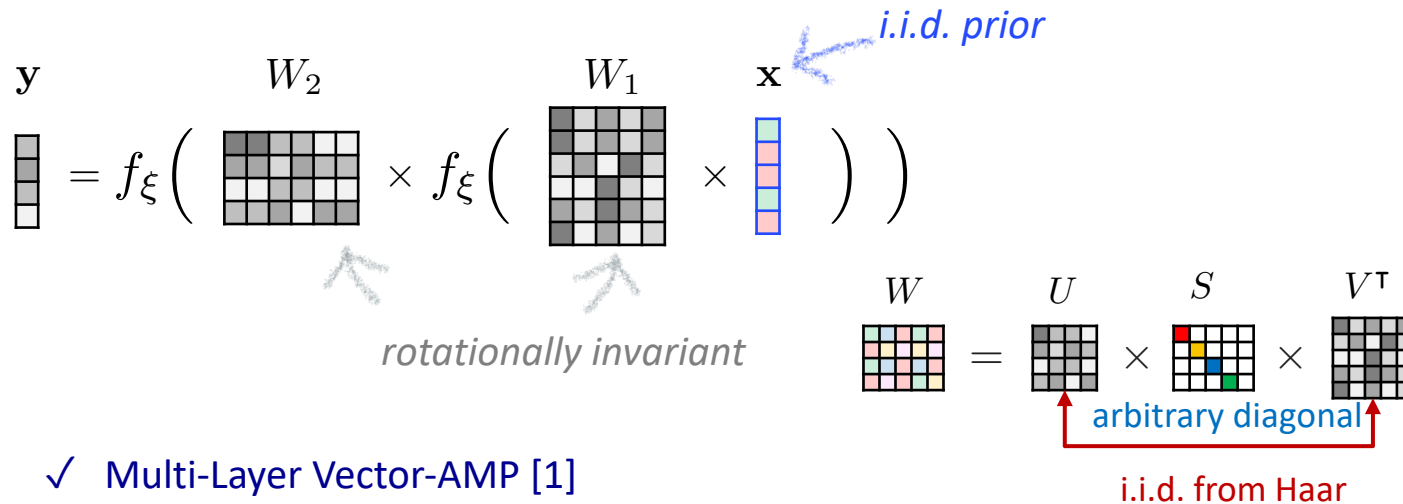
- ✓ Multi-Layer AMP (arbitrary depth) [1]
- ✓ Corresponding state evolution (SE) [1]
- ✓ Replica free energy (mmse, entropy) [1]
- ✓ Rigorously proven for 2 layers [2, 3]

[1] Manoel et al (2017) *Multi-layer generalized linear estimation*.

[2] Gabrié et al (2018) *Entropy and mutual information in models of deep neural networks*.

[3] Reeves (2018) *Additivity of Information in Multilayer Networks via Additive Gaussian Noise Transforms*.

# Layers inference in deep neural network with weight matrices with correlations



- ✓ Multi-Layer Vector-AMP [1]
- ✓ Corresponding state evolution [1]
- ✓ Replica free energy (mmse, entropy) [2, 3]  
(extension of single layer formula by [4])
- ✗ Proof ?

[1] Fletcher et al (2018) *Inference in deep networks in high dimensions*.

[2] Gabrié et al (2018) *Entropy and mutual information in models of deep neural networks*.

[3] Reeves (2018) *Additivity of Information in Multilayer Networks via Additive Gaussian Noise Transforms*.

[4] Shinzato & Kabashima (2009) *Learning from correlated patterns by simple perceptrons*

# Explicit weight learning, empirical verification

## Learning the weight matrices while remaining rotationally inv.?

### e.g. with gradient descent

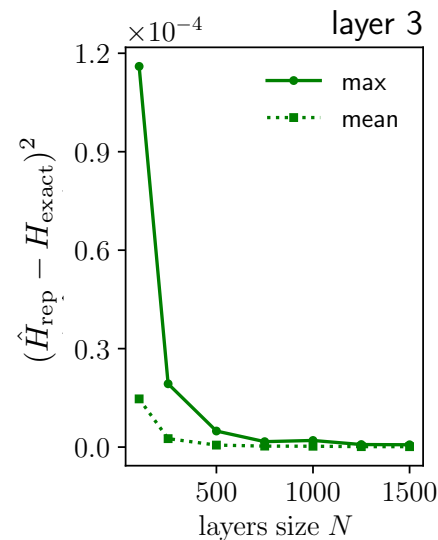
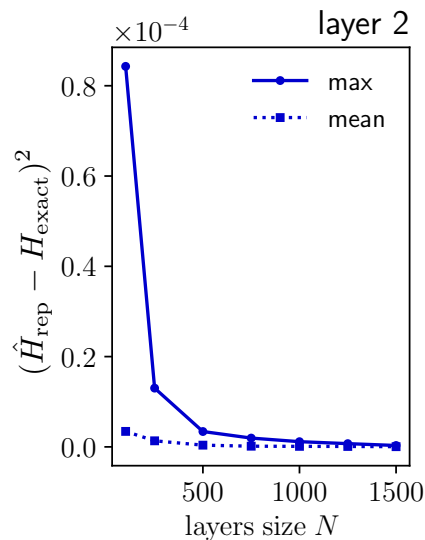
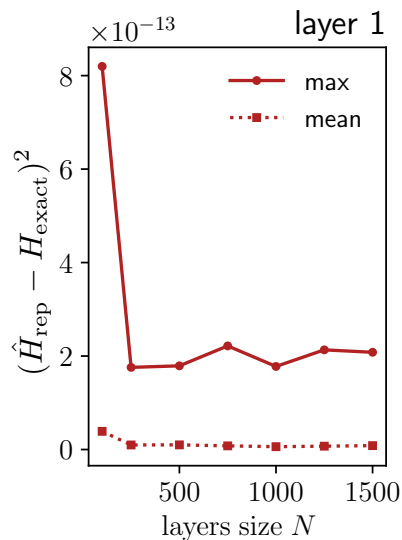
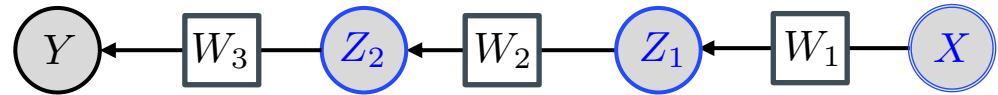
- Initialize Gaussian i.i.d  $W$  matrices
- Singular value decomposition
- Only learn spectrum (N degrees of freedom instead of  $N^2$ )

$$W_\ell = U_\ell \times S_\ell \times V_\ell^\top$$

orthogonal      diagonal      orthogonal  
fixed            updated            fixed

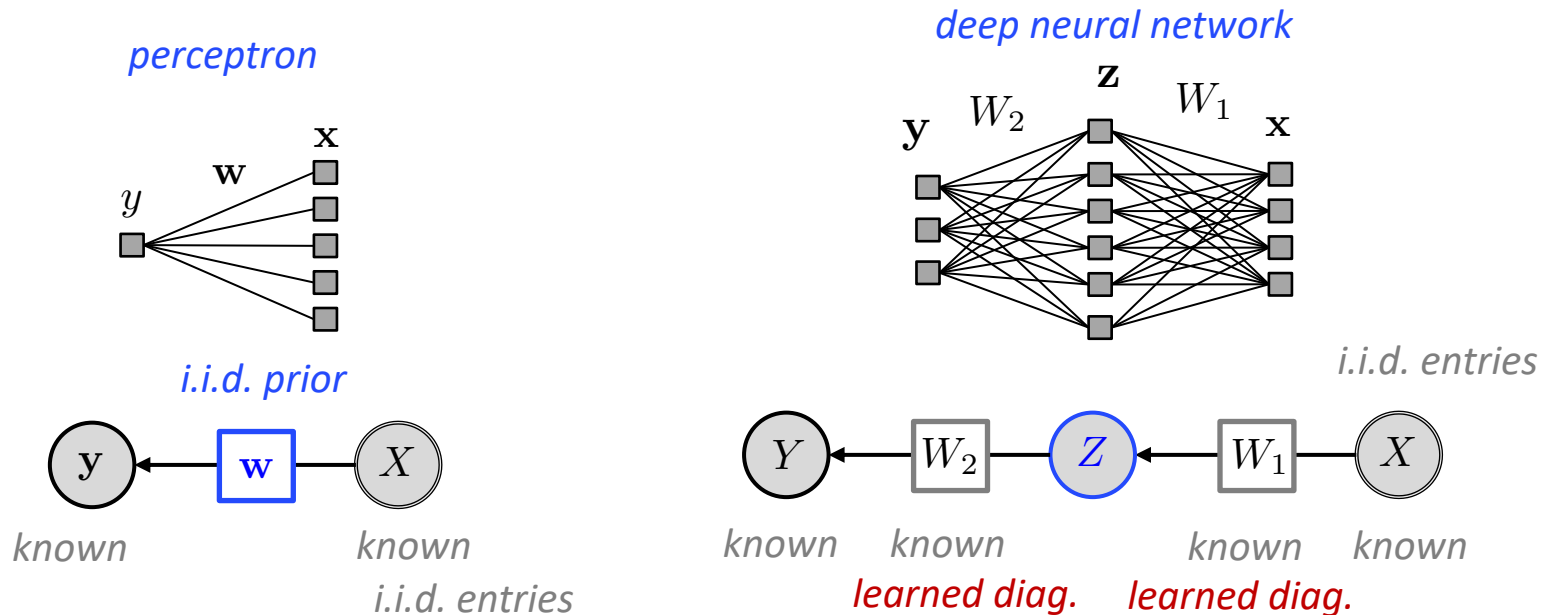
## Numerical verification?

- Linear networks trained
- Gaussian inputs



Replica correct  
with learned matrices

# From perceptron/GLM with random i.i.d. matrices to deep neural networks ?

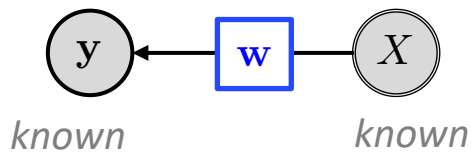
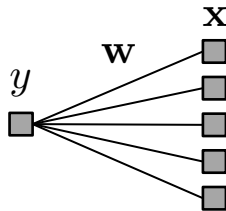


1. Inference of layers variables in deep networks (with learned weight matrices)

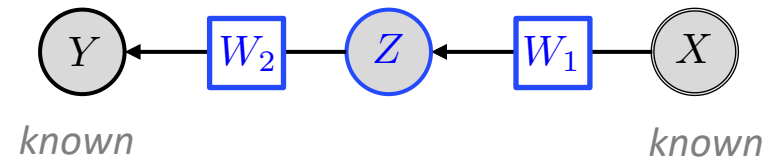
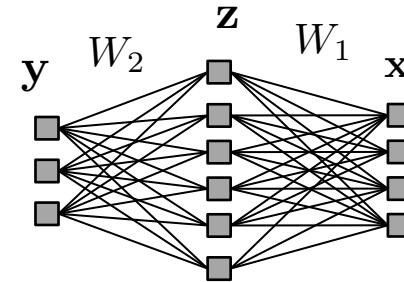
2. The challenge of weight inference and structured weights

# From GLM with random i.i.d. matrices to deep neural networks ?

*perceptron*



*deep neural network*



1. Inference of layers variables in deep networks (with learned weight matrices)
2. The challenge of weight inference and structured weights

# Weight inference in deep neural networks decomposed

$$\begin{array}{c}
 Y \\
 \begin{array}{|c|c|c|c|c|} \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \end{array} \\
 M \times P \\
 \text{known}
 \end{array}
 = f_{\xi} \left( \begin{array}{c}
 W_2 \\
 \begin{array}{|c|c|c|c|} \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \end{array} \\
 M \times K
 \end{array} \times f_{\xi} \left( \begin{array}{c}
 W_1 \\
 \begin{array}{|c|c|c|c|} \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \end{array} \\
 K \times N
 \end{array} \times \begin{array}{c}
 X \\
 \begin{array}{|c|c|c|c|c|} \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \end{array} \\
 N \times P \\
 \text{known}
 \end{array} \right) \right)
 \end{array}
 \begin{array}{l}
 N \text{ input dim} \\
 K \text{ hidden dim} \\
 M \text{ output dim} \\
 P \text{ sample size}
 \end{array}$$

## First idea: decompose the inference in sub-problems

(alike Multi layer - AMP)

$$\begin{array}{c}
 \triangleright \begin{array}{c}
 Y \\
 \begin{array}{|c|c|c|c|c|} \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \end{array} \\
 \text{known}
 \end{array} = f_{\xi} \left( \begin{array}{c}
 W_2 \\
 \begin{array}{|c|c|c|c|} \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \end{array} \\
 \times \begin{array}{c}
 Z \\
 \begin{array}{|c|c|c|c|} \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \end{array} \\
 K \times P
 \end{array} \right) \approx \text{matrix factorization} \\
 \text{with rank } K
 \end{array}
 \begin{array}{l}
 \text{hidden layer states} \\
 \text{over the } P \text{ samples}
 \end{array}$$

$$\begin{array}{c}
 \triangleright \begin{array}{c}
 Z \\
 \begin{array}{|c|c|c|c|} \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \end{array} \\
 \end{array} = f_{\xi} \left( \begin{array}{c}
 W_1 \\
 \begin{array}{|c|c|c|c|} \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \end{array} \\
 \times \begin{array}{c}
 X \\
 \begin{array}{|c|c|c|c|c|} \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \end{array} \\
 \text{known}
 \end{array} \right) \approx P \times \text{GLMs}
 \end{array}$$

# Scaling of the size of the hidden layer?

$$\begin{array}{c} Y \\ \begin{array}{|c|c|c|c|} \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \end{array} \\ M \times P \\ \text{known} \end{array} = f_{\xi} \left( \begin{array}{c} W_2 \\ \begin{array}{|c|c|c|c|} \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \end{array} \\ M \times K \end{array} \times \begin{array}{c} Z \\ \begin{array}{|c|c|c|c|} \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \end{array} \\ K \times P \end{array} \right) \approx \text{matrix factorization} \\ \text{with rank } K$$

$N \rightarrow \infty$

▷  $K = O(1)$

- “low-rank matrix factorization”: good mean field understanding [1, 2]
- finite number of hidden units, committee machines: great body of work! [3, 4, 5, 6, ..]

[1] Lesieur et al (2016), *MMSE of probabilistic low-rank matrix estimation: Universality with respect to the output channel*

[2] Lesieur et al (2017), *Constrained Low-rank Matrix Estimation: Phase Transitions, Approximate Message Passing and Applications*

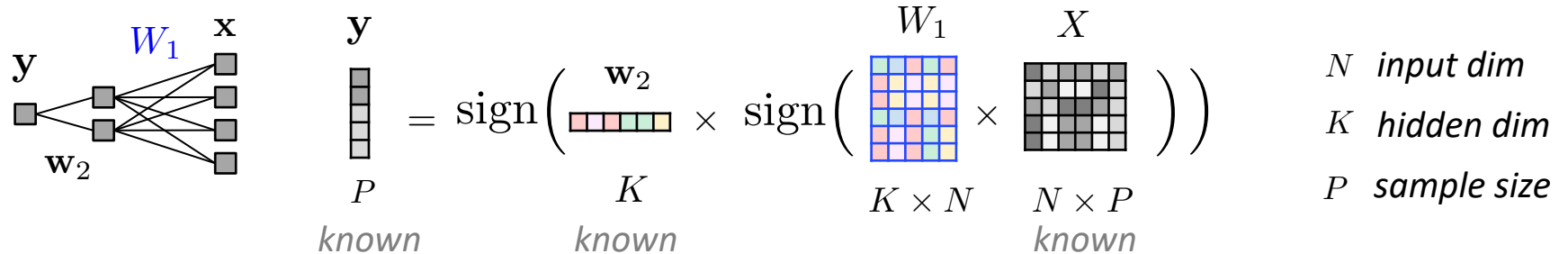
[3] Aubin et al (2018). *The committee machine: Computational to statistical gaps in learning a two-layers neural network*

[4] Monasson et al (2004). *Learning and Generalization Theories of Large Committee-Machines*

[5] Schwarze & Hertz (1993). *Generalization in Fully Connected Committee Machines.*

[6] Schwarze (1993). *Learning a Rule in a Multilayer Neural-Network.*

# Phase transitions for committee machines



✓ Committee-AMP [1]

✓ Corresponding state evolution [1]

✓ Replica free energy (mmse) [2, 3, 4]

✓ Proof [1]

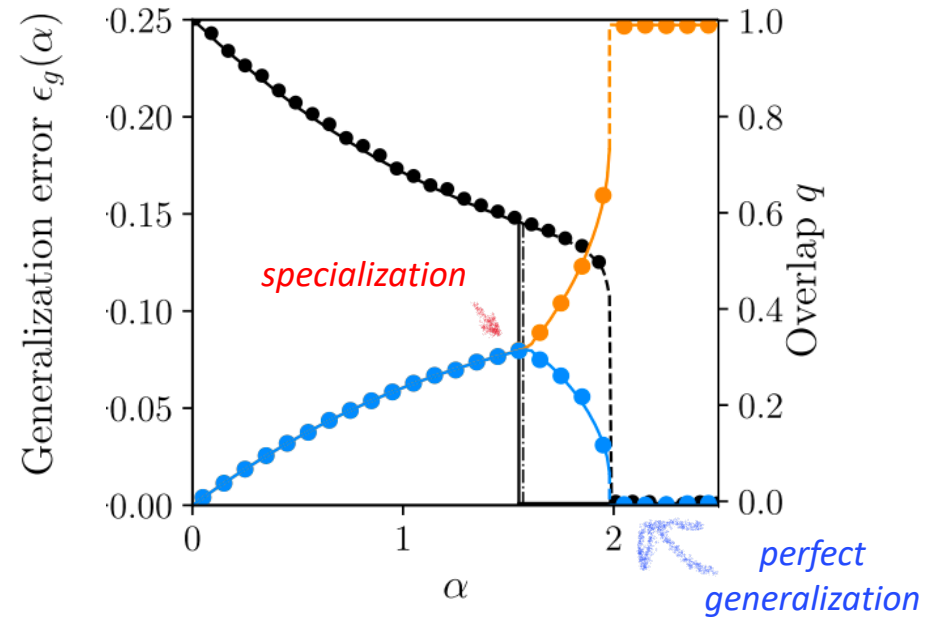
teacher → student

$$q_{00} = \text{overlap}\{(W_1^*)_{0,\cdot}; (W_1)_{0,\cdot}\}$$

$$q_{01} = \text{overlap}\{(W_1^*)_{0,\cdot}; (W_1)_{1,\cdot}\}$$

$K = 2$   
binary weights

|                |               |                            |
|----------------|---------------|----------------------------|
| ● AMP $q_{00}$ | — SE $q_{00}$ | — SE $\epsilon_g(\alpha)$  |
| ● AMP $q_{01}$ | — SE $q_{01}$ | ● AMP $\epsilon_g(\alpha)$ |



[1] Aubin et al (2018). *The committee machine: Computational to statistical gaps in learning a two-layers neural network*

[2] Monasson et al (2004). *Learning and Generalization Theories of Large Committee-Machines*

[3] Schwarze & Hertz (1993). *Generalization in Fully Connected Committee Machines.*

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# Scaling of the size of the hidden layer?

$$\begin{array}{c} Y \\ \begin{array}{|c|c|c|c|c|} \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \end{array} \\ M \times P \\ \text{known} \end{array} = f_{\xi} \left( \begin{array}{c} W_2 \\ \begin{array}{|c|c|c|c|} \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \end{array} \\ M \times K \end{array} \times \begin{array}{c} Z \\ \begin{array}{|c|c|c|c|} \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \end{array} \\ K \times P \end{array} \right) \approx \text{matrix factorization} \\ \text{with rank } K
 \end{array}$$

$N \rightarrow \infty$

▷  $K = O(1)$

- “low-rank matrix factorization”: good mean field understanding [1, 2]
- finite number of hidden units, committee machines: great body of work! [3, 4, 5, 6, ..]

▷  $K = O(N)$

- “high-rank matrix factorization”: mean-field analysis?
- number of hidden units scaling like the inputs

[1] Lesieur et al (2016), *MMSE of probabilistic low-rank matrix estimation: Universality with respect to the output channel*

[2] Lesieur et al (2017), *Constrained Low-rank Matrix Estimation: Phase Transitions, Approximate Message Passing and Applications*

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[5] Schwarze & Hertz (1993). *Generalization in Fully Connected Committee Machines.*

[6] Schwarze (1993). *Learning a Rule in a Multilayer Neural-Network.*

# Structured weights inference $K = O(N)$

$$\begin{array}{c}
 Y \\
 \begin{array}{|c|c|c|c|c|} \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \end{array} \\
 M \times P \\
 \text{known}
 \end{array}
 = f_{\xi} \left( \begin{array}{c} W_2 \\
 \begin{array}{|c|c|c|c|c|} \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \end{array} \\
 M \times K
 \end{array} \times \begin{array}{c} Z \\
 \begin{array}{|c|c|c|c|c|} \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \end{array} \\
 K \times P
 \end{array} \right)
 \quad \# \text{ parameters } O(N^2)$$

## Second idea: learn structured simpler weights

$$\begin{array}{c}
 Y \\
 \begin{array}{|c|c|c|c|c|} \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \end{array} \\
 M \times P \\
 \text{known}
 \end{array}
 \triangleright = f_{\xi} \left( \begin{array}{c} S_2 \\
 \begin{array}{|c|c|c|c|c|} \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \end{array} \\
 M \times M
 \end{array} \times \begin{array}{c} \tilde{W}_2 \\
 \begin{array}{|c|c|c|c|c|} \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \end{array} \\
 M \times K \\
 \text{known}
 \end{array} \times \begin{array}{c} Z \\
 \begin{array}{|c|c|c|c|c|} \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \end{array} \\
 K \times P
 \end{array} \right)
 \quad \# \text{ parameters } O(N)$$

- ▷ Also used in deep learning literature:
  - Speed / memory concerns: e.g. ACDC layers [1], Ensemble learning [2]
  - Theoretical papers: e.g. Porcupine networks [3], Replica entropy [4]
- ▷ Signal processing literature: a.k.a. Blind Calibration

[1] Moczulski et al (2015), *ACDC: A Structured Efficient Linear Layer*

[2] Wen et al (2020), *BatchEnsemble: An Alternative Approach to Efficient Ensemble and Lifelong Learning*

[3] Feizi et al (2016) *Porcupine Neural Networks: (Almost) All Local Optima are Global*

[4] Gabrié et al (2018), *Entropy and mutual information in models of deep neural networks*

# Blind calibration mean field analysis

## Simultaneous recovery of input signal and “calibration variables”

$$\begin{array}{c}
 \begin{array}{c} Y \\ \begin{array}{|c|c|c|c|} \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \end{array} \\
 M \times P \\
 \text{known}
 \end{array}
 = f_{\xi} \left( \begin{array}{c} \begin{array}{c} \text{i.i.d. prior} \\ \downarrow \\ S \\ \begin{array}{|c|c|c|c|} \hline \square & \square & \square & \square \\ \hline \square & \color{red}{\square} & \square & \square \\ \hline \square & \color{green}{\square} & \square & \square \\ \hline \square & \square & \color{orange}{\square} & \square \\ \hline \end{array} \\
 M \times M \\
 \text{to be calibrated}
 \end{array}
 \times \begin{array}{c} \begin{array}{c} \text{i.i.d. entries} \\ \downarrow \\ \tilde{W} \\ \begin{array}{|c|c|c|c|} \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \end{array} \\
 M \times N \\
 \text{known}
 \end{array}
 \times \begin{array}{c} \begin{array}{c} \text{i.i.d. prior} \\ \downarrow \\ X \\ \begin{array}{|c|c|c|c|} \hline \color{blue}{\square} & \color{green}{\square} & \color{red}{\square} & \color{orange}{\square} \\ \hline \color{blue}{\square} & \color{green}{\square} & \color{red}{\square} & \color{orange}{\square} \\ \hline \color{blue}{\square} & \color{green}{\square} & \color{red}{\square} & \color{orange}{\square} \\ \hline \color{blue}{\square} & \color{green}{\square} & \color{red}{\square} & \color{orange}{\square} \\ \hline \end{array} \\
 N \times P
 \end{array}
 \right)
 \end{array}
 \begin{array}{l}
 N \text{ input dim} \\
 M \text{ output dim} \\
 P \text{ sample size}
 \end{array}
 \end{array}$$

- ✓ Calibration - AMP algorithm [1, 2]
- ✓ Corresponding state evolution [3]
- ✓ Replica free energy [3]
- ✗ Rigorous proof

[1] Schulke C. et al (2013), *Blind Calibration in Compressed Sensing using Message Passing Algorithms*

[2] Schulke C. et al (2016), *Blind sensor calibration using approximate message passing*

[3] Gabrié M. et al (2020), *Blind calibration for compressed sensing: State evolution and an online algorithm*

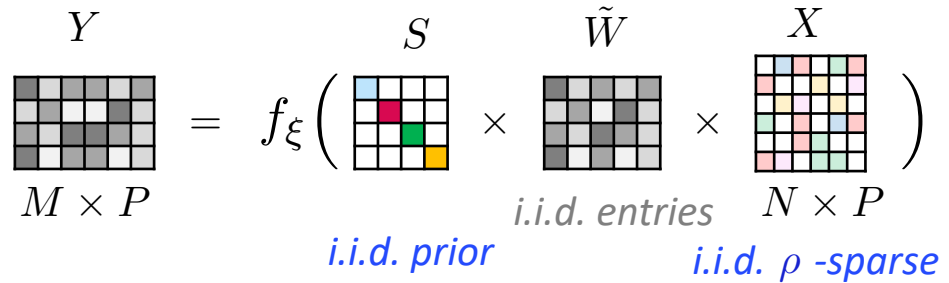
# Numerical results for sparse priors

## Example sparse signal recovery:

output dim / input dim  $\alpha = M/N$

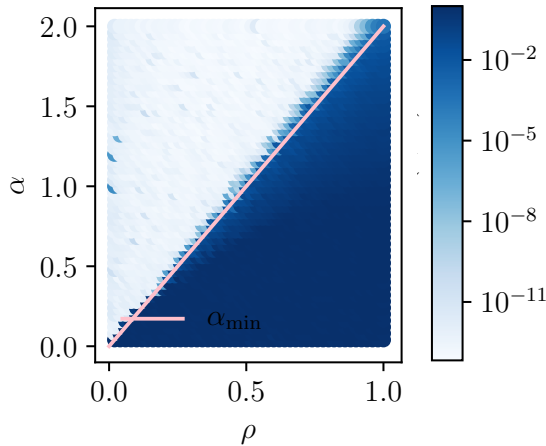
input sparsity  $\rho$

naive count  $\alpha_{\min} = \rho \frac{P}{P-1}$

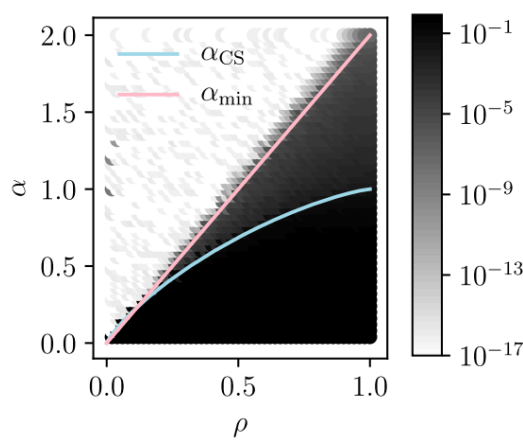


Cal- AMP reconstruction errors ( $P = 2$ )

$S$  error

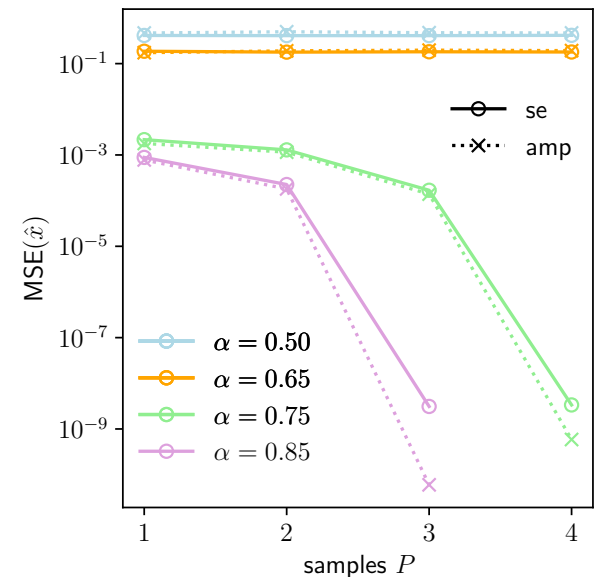


$X$  error



*Cal-AMP reconstructs efficiently with a finite number of samples*

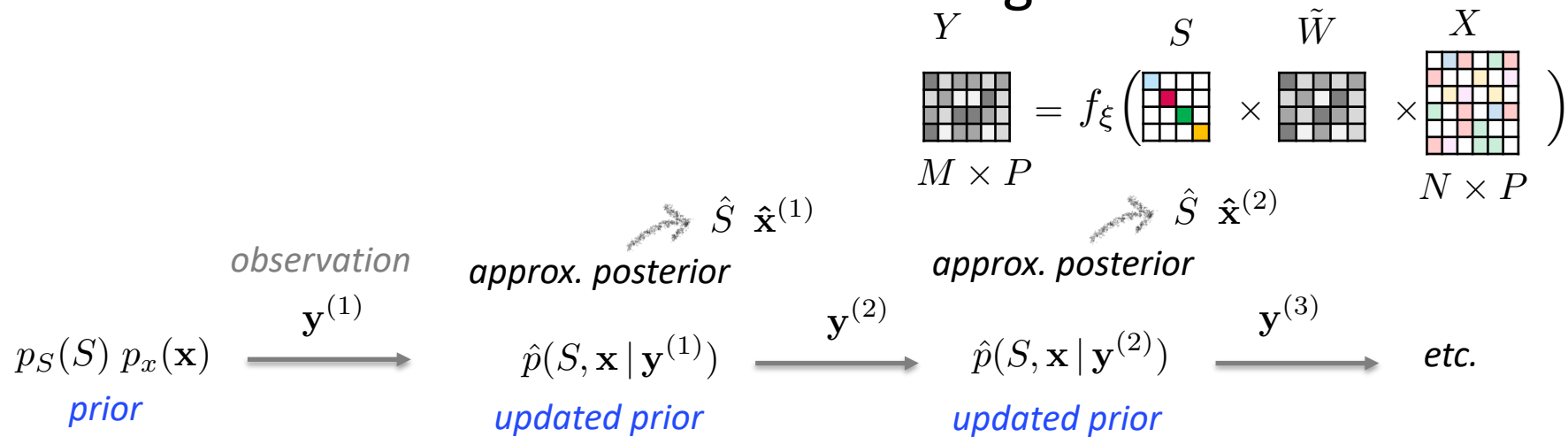
Cal- AMP State evolution



*Good agreement SE and Cal-AMP*

[1] Gabrié M. et al (2020), *Blind calibration for compressed sensing: State evolution and an online algorithm*

# Statistical mechanics of online learning



## ► Streaming AMP for GLM [1], for blind calibration [2]

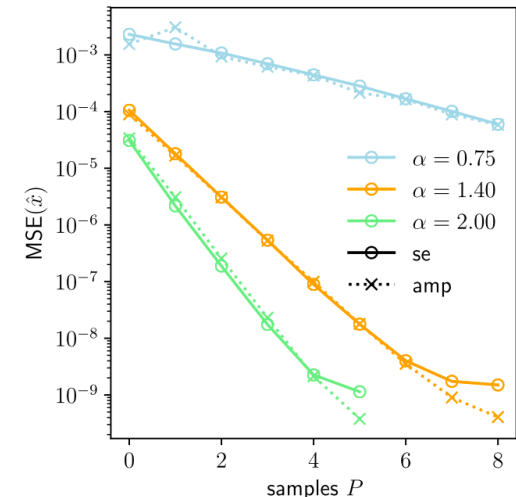
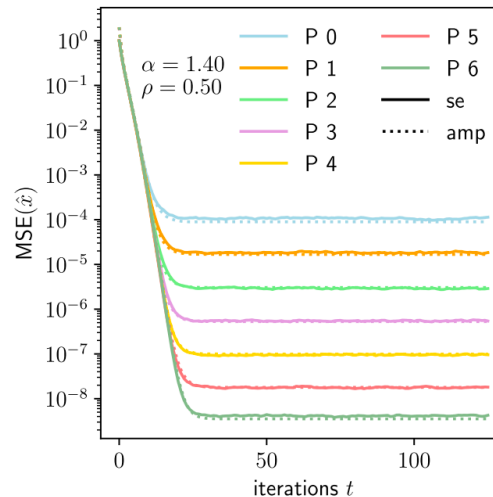
### Numerical results:

### Example of sparse signal recovery

$X$  i.i.d.  $\rho$ -sparse

$$\alpha = M/N$$

output dim / input dim



[1] Manoel et al. (2018). Streaming Bayesian inference: Theoretical limits and mini-batch approximate message-passing

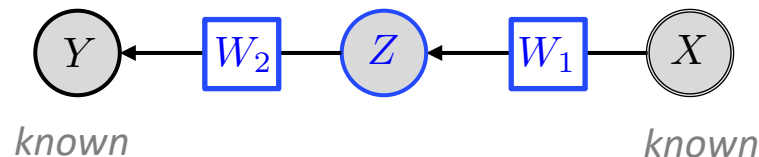
[2] Gabrié M. et al (2020), Blind calibration for compressed sensing: State evolution and an online algorithm

# Perspectives for weight inference in deep NNs

$$Y = f_{\xi} \left( S \times \tilde{W} \times X \right)$$

## Weight inference in hidden layers for the stat mech of deep learning (offline/batch and online/mini-batch)

- ▷ Perspective: Combine Cal-AMP in layers to infer structured weights in NNs (extensive number of hidden units!)
- ▷ Challenge: Back to the teacher-student scenario?



# Perspectives for mean-field methods for inference and information/computational thresholds

- ▷ **More and more complex matrix ensembles (weights, data)**
- ▷ **Combining solutions to more complex models**
- ▷ **Great open source package for algorithms**



 [sphinxteam / tramp](#)

Tutorial review:

Gabriel (2020), *Mean field inference methods for neural networks* – arXiv/1911.00890

Software:

Baker et al (2020), *Compositional Inference with Tree Approximate Message Passing*

**Thank you!**