



THE LEARNING MACHINE AND BEYOND

A TOUR FOR THE CURIOUS

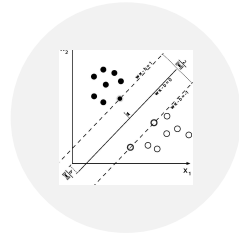
Cláudia Soares MPML May 14



A TENTATIVE
TIMELINE



ML AND
OTHER FIELDS



KINDS OF
LEARNING

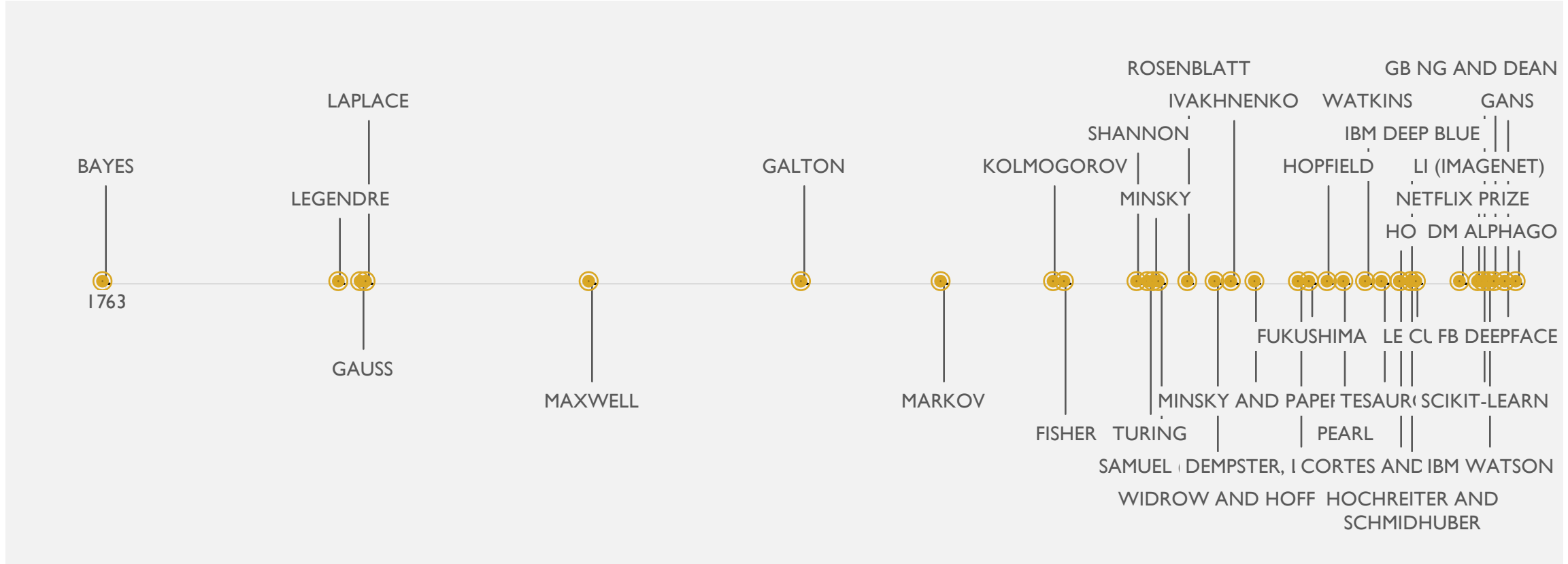


LIMITATIONS



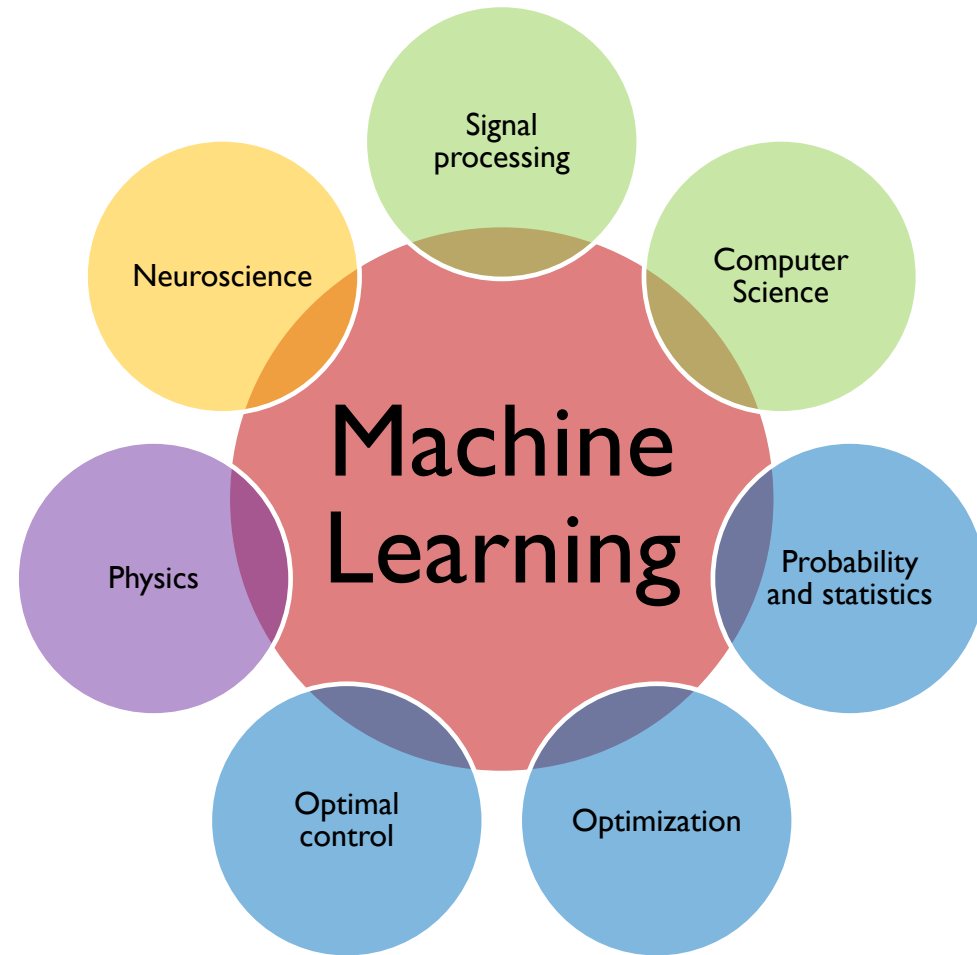
FUTURE

CONTENTS

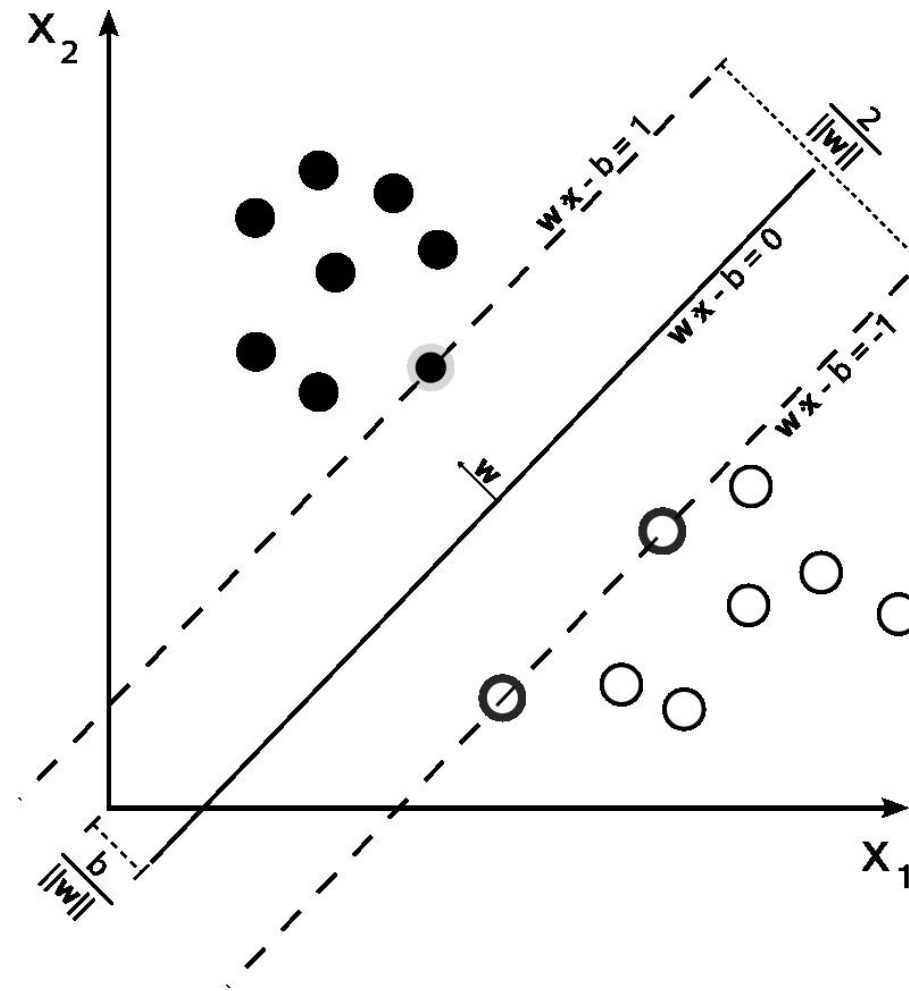


LEARNING MACHINES: A TIMELINE

ML AND (A FEW) OTHER FIELDS



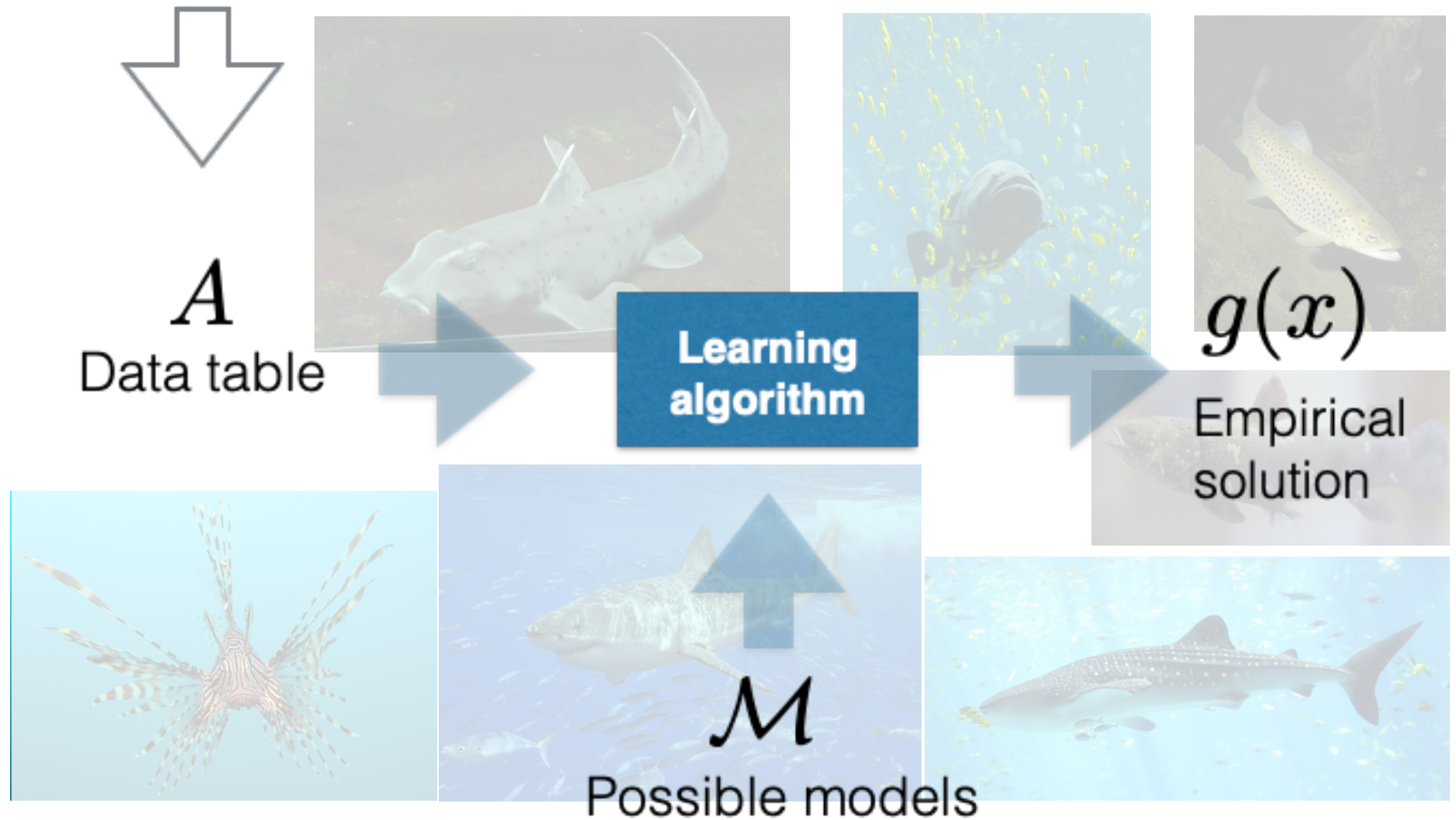
INCIPIIT: LEARNING FROM DATA



WE ALL LEARN
FROM DATA



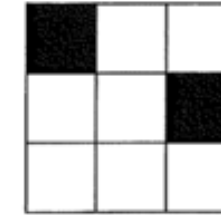
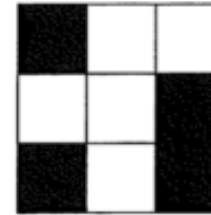
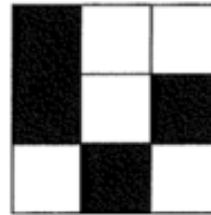
$$f(x) = ? \quad f(x) = ?$$



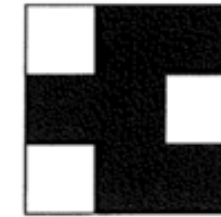
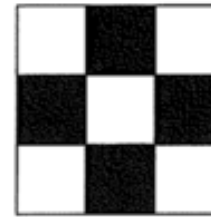
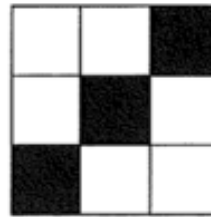
IS LEARNING FEASIBLE?

- How can a **limited data set** inform us about an **entire unknown function**?
- We know all the values of the unknown function on the training examples.
- Does this mean we know f ?
- Does the data set tell us anything about the function outside of the data set?

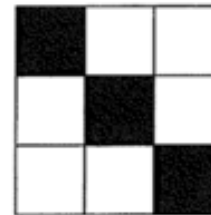
$f(x)$ Is completely unknown outside of the dataset



$f = -1$



$f = +1$



$f = ?$

OUTSIDE THE TRAINING SET

Learn $f(x)$

Predict its values outside of the dataset

Will our prediction be **incorrect**?

Possible!

Will our prediction be **likely correct**?

With some probability, yes!

KINDS OF LEARNING



SUPERVISED LEARNING

$$A = \begin{bmatrix} x_{11} & \cdots & x_{1d-1} & y_1 \\ \vdots & \vdots & \vdots & \vdots \\ x_{N1} & \cdots & x_{Nd-1} & y_N \end{bmatrix}$$

Choose a feature that you want to predict

You will be learning

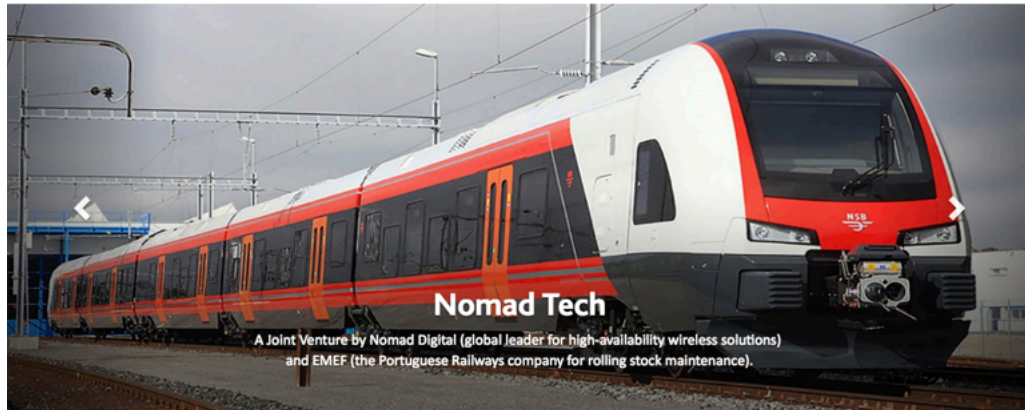
$$f(x_i) \approx y_i$$

SUPERVISED LEARNING TASKS

- Classification (discrete, not ordered outcome)
- Regression (real, ordered outcome)
- Preference learning (discrete, ordered outcome)

CLASSIFICATION

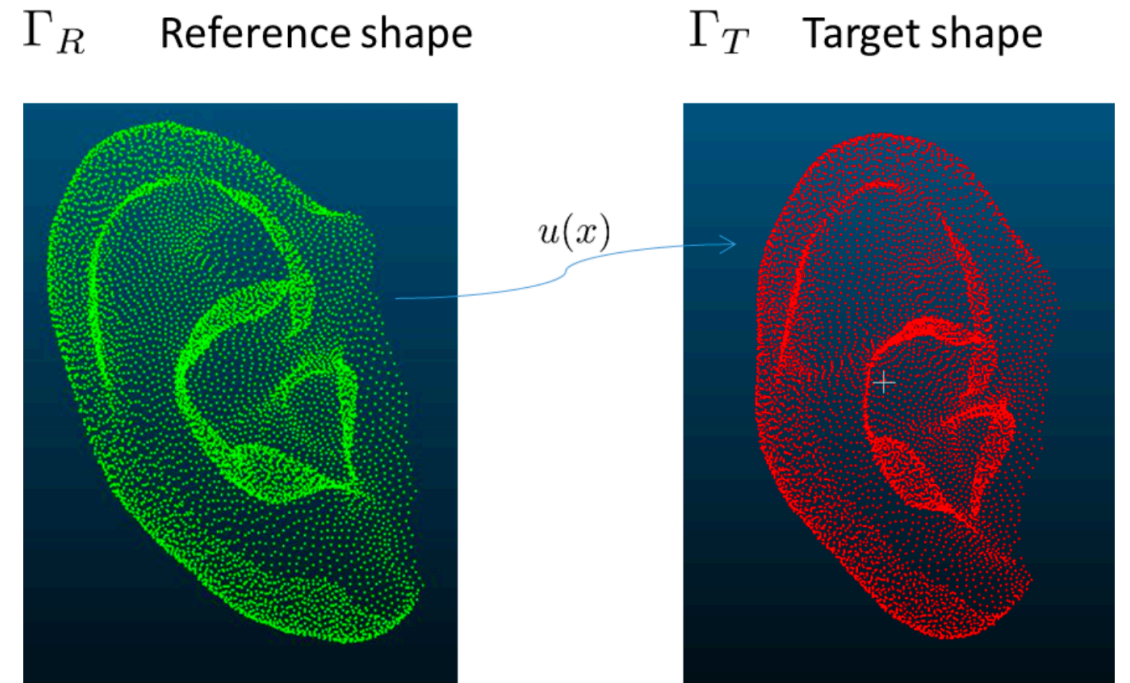
Failure prediction of suburban trains



- ~1000 variables every 10mn
- Real data issues
 - Class imbalance
 - Noise
 - Missing data
- High-dimensional large data streams

REGRESSION

- Problem: face prosthetics of ears and noses, such that the created face part fits well with the face and respects border conditions
- Parametric Gaussian Process regression



PREFERENCE LEARNING: PERCEPTUAL SCALE FROM PAIRWISE JUDGEMENTS

City-SAFE

SIPG

CITY-SAFE: MAPPING URBAN PERCEPTION OF SAFETY

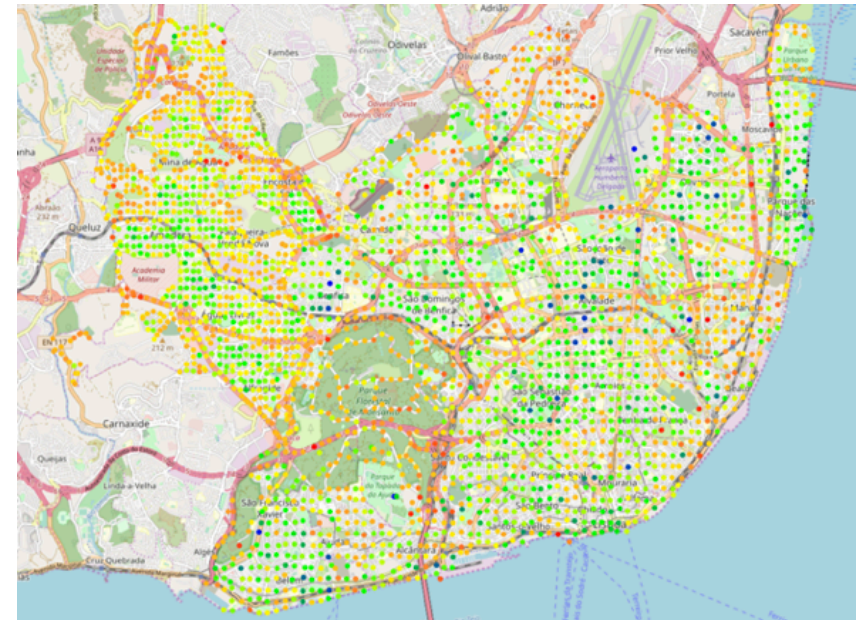
WHICH PLACE LOOKS SAFER?



18964 clicks collected

Goal: 150,000 clicks

Big data analysis is increasingly allowing to give communities valuable insights. One can argue that safety perception is a major concern in urban life. This project seeks to explore machine learning methods to estimate the perception of safety



With M. Marques and G. Costa

UNSUPERVISED LEARNING

- Find **patterns** and **structure** in data
- Which features better represent the data? (Dimensionality reduction)
- Is data aggregated in subgroups? (Clustering)

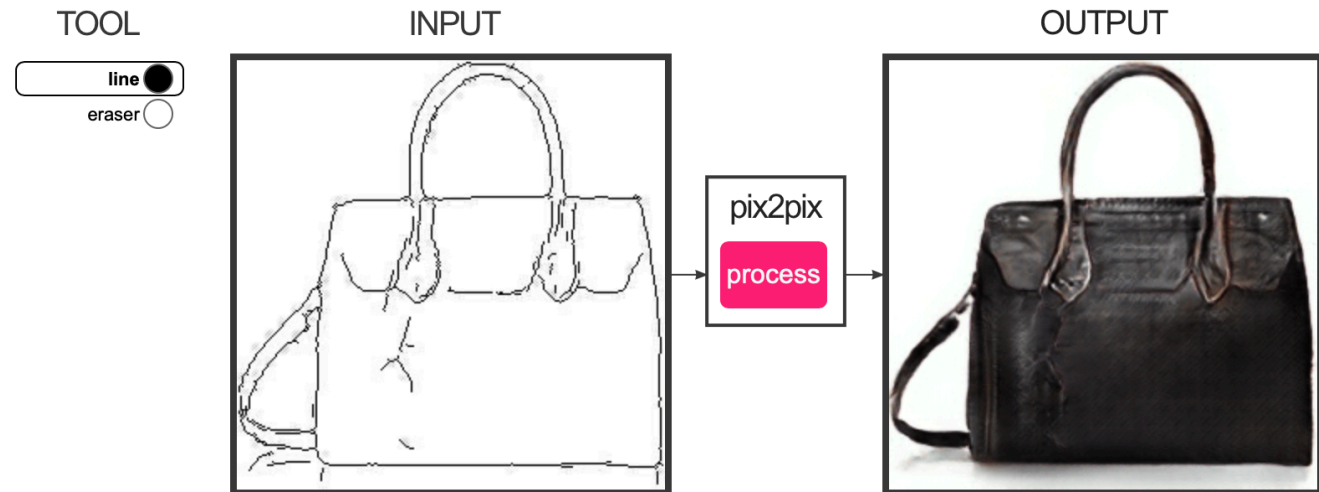
UNSUPERVISED LEARNING TASKS

- Clustering (Classification)
- Dimensionality reduction (Regression)
- Generative models

GENERATIVE ADVERSARIAL NETWORKS (GAN)

- Example: pix2pix Trained on a database of ~137k handbag pictures collected from Amazon and automatically generated edges from those pictures
- GANs are a game with 2 DNN as players. Nash equilibrium is a local minimizer of the generator and discriminator losses.

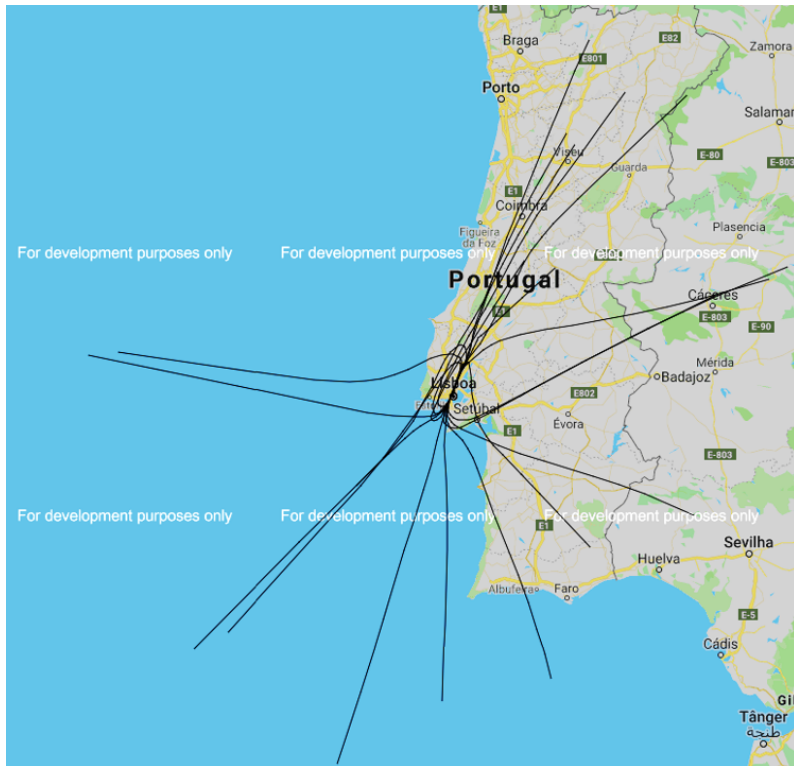
edges2handbags



Isola et al, 2016

GENERATIVE MODEL FOR CLUSTERING AND DENSITY ESTIMATION

Landing time inference for the Lisbon airport



- Fitted a GMM to aircraft trajectory data
- Discovered number of clusters
- Took advantage of the density model to compute the posterior given a small entry point trajectory piece

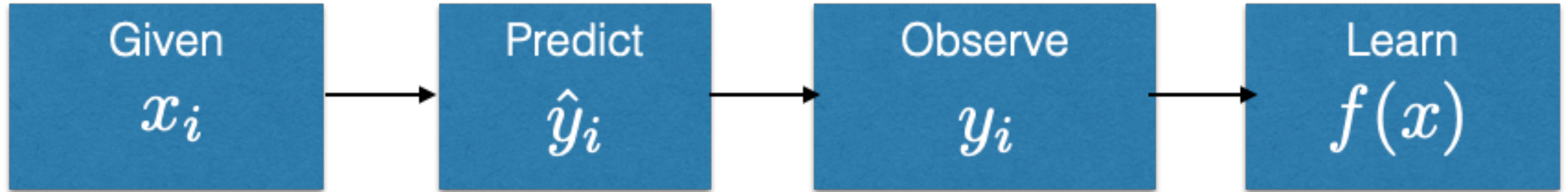
With R. Ventura and A. Fallah

**Unsupervised
learning** (to better
understand data)



**Supervised
learning**

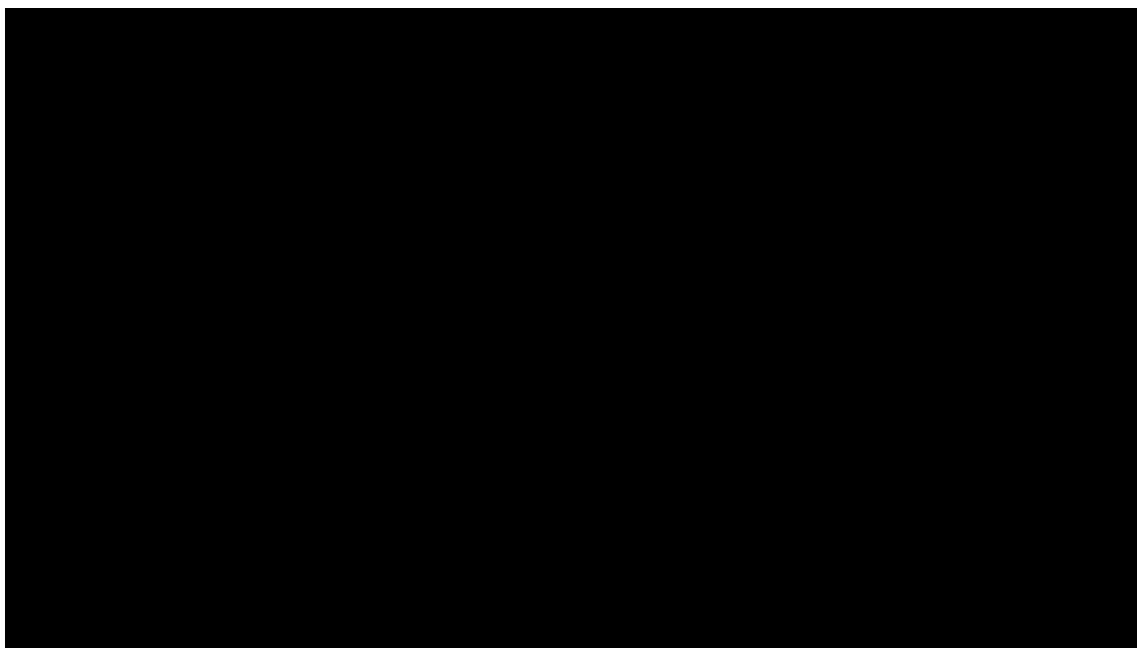
**SUPERVISED
AND
UNSUPERVISED
LEARNING**



ONLINE LEARNING

- **Offline:** Learning and prediction are separated in time. Model is frozen after learning.
- **Online:** Algorithm sees the dataset one example at a time

ONLINE LEARNING USING TIME-VARIANT LOSSES (ONGOING!)



Goal: learn the model of the face as the animation is unrolling

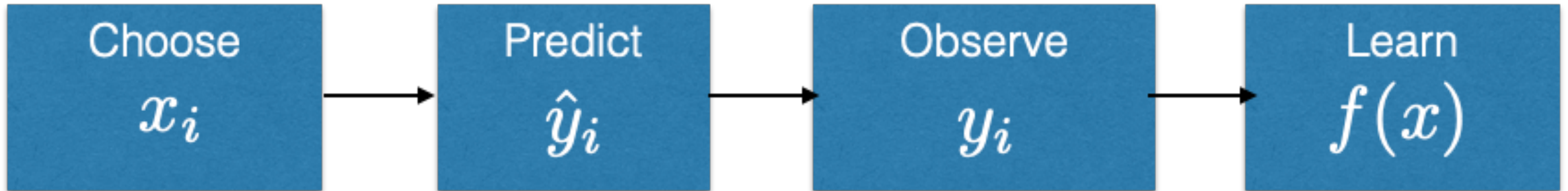
Optimization of a nonconvex loss using online proximal gradient descent

With F. Caldas, D. Jakovetic (UNS), Z. Desnica (3L)



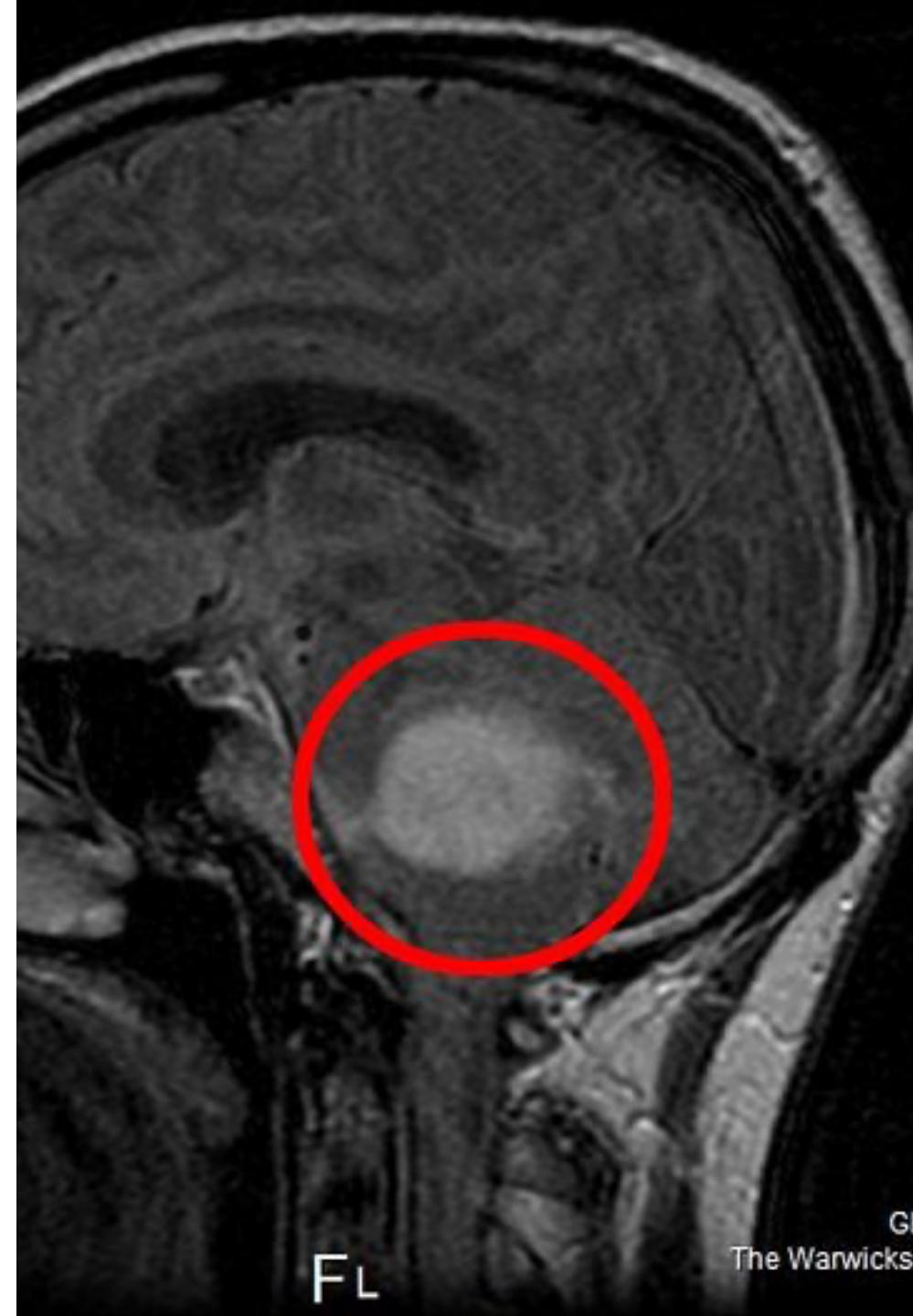
ACTIVE LEARNING

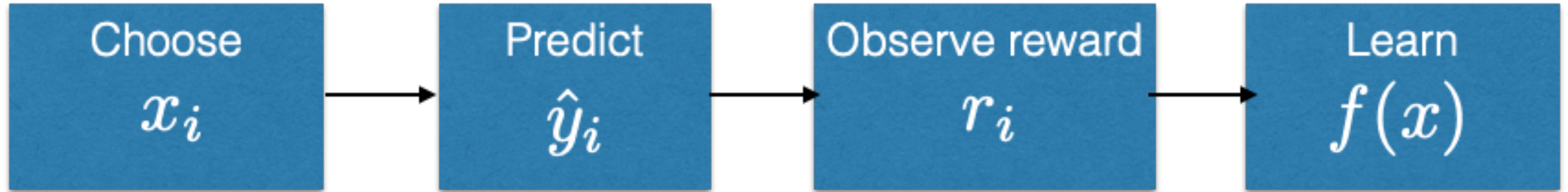
- We **choose** the input point to **maximize** its information value



CHOOSING DATA LABELING STRATEGIES

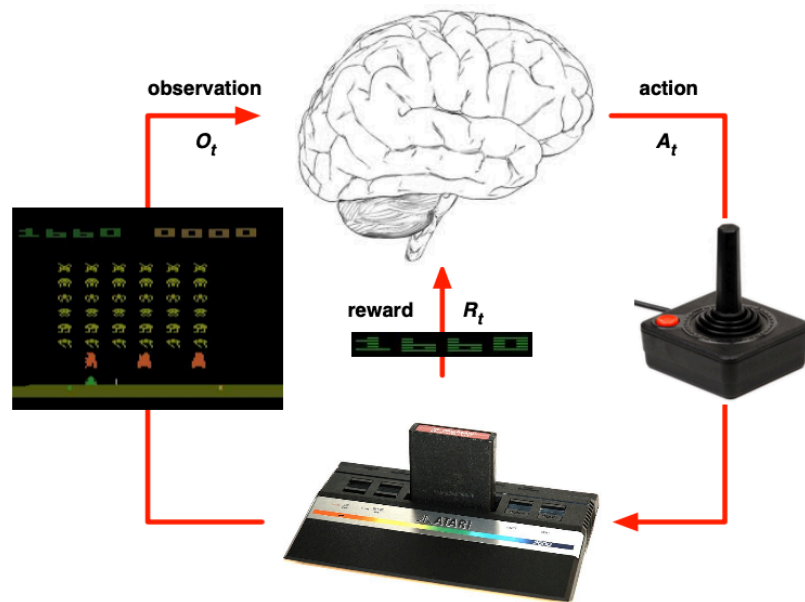
- Large datasets for supervised learning are costly to label.
- Can machines learn with fewer labeled training instances if they are allowed to ask questions?
 - YES!





REINFORCEMENT LEARNING

- There is no supervisor, only a reward signal
- Feedback can be delayed, not instantaneous
- Time really matters (sequential, non i.i.d data)
- Algorithm's choices affect the subsequent data it receives



- Rules of the game are unknown
- Learn directly from interactive game-play
- Pick actions on joystick, see pixels and scores

David Silver, Deepmind

PLAYING ATARI GAMES

USE DNN AS A FUNCTION
APPROXIMATOR FOR THE
ACTION VALUE FUNCTION (Q
LEARNING): THE DQN
ARCHITECTURE

SUPERHUMAN PERFORMANCE
ON MOST GAMES

ALGORITHMS FOR MODEL TRAINING AND INFERENCE

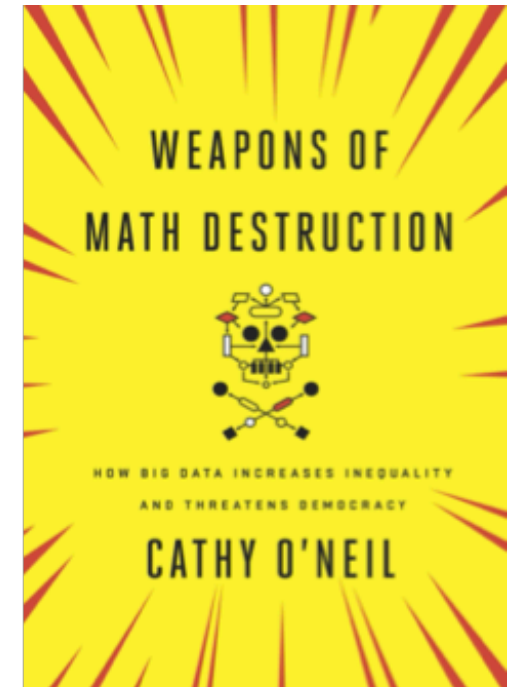
- Variational inference
- Stochastic gradient descent family
- Transfer learning of pre-trained model
- Federated learning / distributed learning

ETHICS

- Data Science is ML at the frontline in dealing with real data
- New ethical challenges
- Need of effective generalization theory

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2012

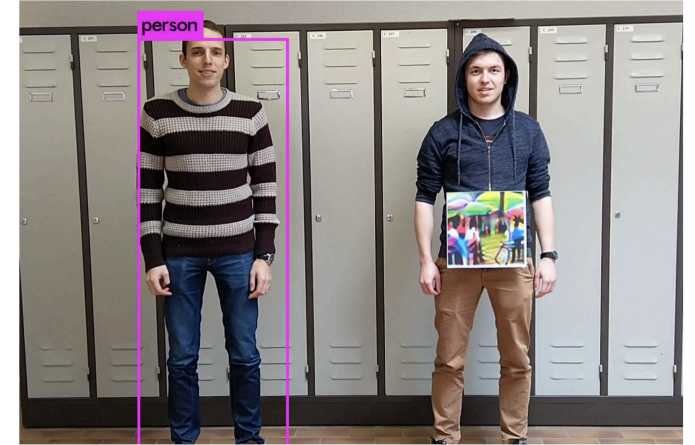


2016

LIMITATIONS: ADVERSARIAL EXAMPLES



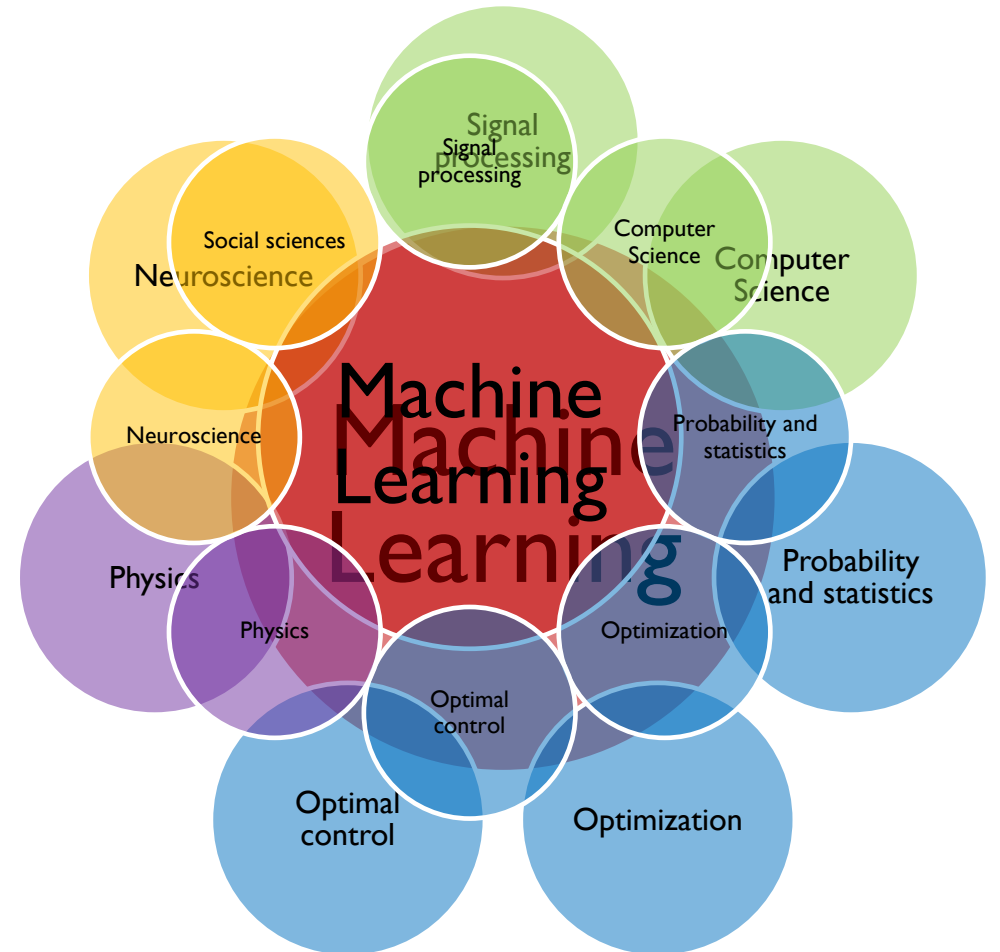
Teapot(24.99%)
Joystick(37.39%)



- Adversarial examples on deep Q Networks for Atari games: 1 px leads to 50% of human performance
- Pixel attacks for image classification on ImageNet
- Physical patch attack to object recognizer
- Catastrophic forgetting

IS LEARNING FEASIBLE (IN THE REAL WORLD)?

- Robust Machine Learning by helping algorithms to train in a more generalizable way
- Devising models that are both accurate and explainable
- Ethical learning machines



MPML SEMINAR SERIES GOALS: REJOINING FORCES

- Rejoin forces from the fields of Mathematics, Physics, Machine Learning to address some of these difficult problems in ML
 - Rejoin those forces to look at strong theory-backed results in Mathematics and Physics to successfully predict and interact with the real world
-

RECENT EXAMPLES OF SYNERGIES

- Theodorou et al., (2010) Learning Policy Improvements with Path Integrals
- Carlsson et al., (2018) Topological Approaches to Deep Learning
- Hofer, Christoph, et al. (2017) Deep learning with topological signatures.
- Chmiela, Stefan, et al. (2017) Machine learning of accurate energy-conserving molecular force fields.
- ...