

Upscaling and spatial localization of non-local energies with applications to crystal plasticity

JM, M. Morandotti, D. R. Owen and E. Zappale

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Joint work with

Marco Morandotti - Politecnico di Torino

David R. Owen - Carnegie-Mellon University

Elvira Zappale - Università di Roma, La Sapienza

Structured deformations

First order (Del Piero, Owen)

The model sets a basis to address problems in non-classical deformations of continua (for instance, study of equilibrium configurations of crystals with defects) where an analysis at **macroscopic** and **microscopic** levels is required, dividing the study of deformations in two parts: the part arising from **smooth changes** and the part due to **slips and separations (disarrangements)** at smaller length scales.



StD pair(g, G)

with $f_n \xrightarrow{L^\infty} g$, $\nabla f_n \xrightarrow{L^\infty} G$, and with f_n injective.

▶ g accounts for the *macroscopic change in geometry*.

$$M := \nabla g - G$$

is attained through **slips** and **separations (disarrangements)** that take place at a smaller length scale.

Structured deformations

More precisely:

1. **Simple deformations** are pairs (K, g) where $K \subset \Omega$ consists of a finite union of Lipschitz sets of Hausdorff dimension $N - 1$ and $g|_{\Omega \setminus K}$ is a one-to-one differentiable function.
2. A triple (K, g, G) is a **limit of simple deformations** if $K \subset \Omega$, $g \in L^\infty(\Omega; \mathbb{R}^N)$ and $G \in L^\infty(\Omega; \mathbb{R}^{N \times N})$ and there exists a sequence of simple deformations (K_n, f_n) such that $K := \bigcup_{p=1}^{\infty} \bigcap_{n=p}^{\infty} K_n$, $f_n \xrightarrow{L^\infty} g$, $\nabla f_n \xrightarrow{L^\infty} G$.
3. A triple (K, g, G) is a **structured deformation** if (K, g) is a simple deformation, $G : \Omega \setminus K \rightarrow \mathbb{R}^{N \times N}$ is continuous and there exists $m > 0$ such that, for all $x \in \Omega \setminus K$, $m < \det G(x) \leq \det \nabla g(x)$.
4. **Approximation Theorem**: there exists f_n injective and piecewise smooth such that $f_n \xrightarrow{L^\infty} g$, $\nabla f_n \xrightarrow{L^\infty} G$,
 $K = \bigcup_{n=1}^{\infty} \bigcap_{p=n}^{\infty} K_p$.

Example *Deck of cards*

$$N = 2, \Omega = (0, 1)^2,$$

$$g(x_1, x_2) = (x_1 + x_2, x_2), \text{ (simple shear) } G = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$f_n(x) = (x_1 + \frac{k}{n}, x_2), \frac{k}{n} \leq x_2 < \frac{k+1}{n}, k = 0, \dots, n-1$$

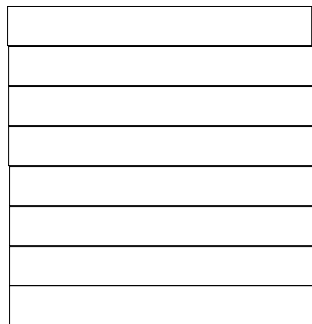
$$f_n \xrightarrow{L^\infty} g, \nabla f_n \xrightarrow{L^\infty} G, Df_n \rightarrow \nabla g = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$$

$$M = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$$

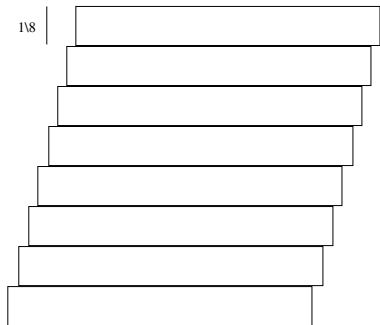
Example

Deck of cards

f_8



1



d

Structured Deformations (Choksi & Fonseca) by means of BV-SBV spaces

- ▶ A function $u \in L^1(\Omega; \mathbb{R}^d)$ ($d \geq 1$) is of **bounded variation**, i.e. $u \in BV(\Omega; \mathbb{R}^d)$, if $D_j u_i \in \mathcal{M}(\Omega)$, $i = 1, \dots, d$, $j = 1, \dots, N$.

$$Du = \nabla u \mathcal{L}^N \llcorner \Omega + ([u] \otimes \nu_{(u)}) \mathcal{H}^{N-1} \llcorner S_{(u)} + D^c u.$$

$$[u] = u^+ - u^-, \quad S_{(u)} \text{ is countably } N - 1 \text{ rectifiable}$$



$$SBV(\Omega; \mathbb{R}^d) = \{u \in BV(\Omega; \mathbb{R}^d) : D^c u = 0\}$$

BV-SBV spaces

- ▶ Theorem (Alberti) Let $F \in L^1(\Omega; \mathbb{R}^{d \times N})$, then there exists $f \in SBV(\Omega; \mathbb{R}^d)$ such that: $\nabla f = F \mathcal{L}^N$ a.e. in Ω and

$$|D^s f|(\Omega) \leq C \|F\|_{L^1(\Omega; \mathbb{R}^{d \times N})}, \quad |f|_{L^1(\Omega; \mathbb{R}^d)} \leq C \|F\|_{L^1(\Omega; \mathbb{R}^{d \times N})}.$$

- ▶ Given $G \in L^1(\Omega; \mathbb{R}^{d \times N})$ and $g \in SBV(\Omega; \mathbb{R}^d)$, there exists $h \in SBV(\Omega; \mathbb{R}^d)$ such that $\nabla h = G - \nabla g$.
Let h_n be a piecewise constant approximation of h in L^1 norm.
- ▶ Define $u_n := g + h - h_n$. Then $u_n \rightarrow g$ in L^1 and $\nabla u_n = G$.

Structured Deformations: an important remark about SBV

Assume for simplicity that $g \in W^{1,1}$, i.e. there are no macroscopic "cracks". If $u_n \rightarrow g$, then $Du_n \rightarrow Dg \equiv \nabla g$ in the sense of distributions and therefore if $\nabla u_n \xrightarrow{*} G$, we have that $D^s u_n \rightarrow M = \nabla g - G$ in the sense of distributions. Hence, the difference between macroscopic and microscopic "bulk densities" is achieved by a limit of singular measures.

By Ambrosio's Compactness Theorem in SBV, we have that $\nabla g = G \mathcal{L}^N$ a.e. unless $\mathcal{H}^{N-1}(S_{(u_n)}) \rightarrow +\infty$, i.e. unless there is a diffusion of cracks whose amplitude is tending to zero.

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Integral representation (SBV framework)

The energy associated with the structured deformation (g, G) can be defined as the **most economical way** to build up the pair using approximations in *SBV*:

$$I_L(g, G) = \inf_{u_n \in SBV(\Omega; \mathbb{R}^d)} \left\{ \liminf_{n \rightarrow \infty} E_L(u_n), u_n \xrightarrow{L^1} g, \nabla u_n \xrightarrow{L^p} G \right\} \quad (1)$$

for $(g, G) \in SBV(\Omega; \mathbb{R}^d) \times L^p(\Omega; \mathbb{R}^{d \times N})$, $p \geq 1$, with

$$E_L(v) = \int_{\Omega} W(x, \nabla v) dx + \int_{S_v} \psi(x, [v], \nu_v) d\mathcal{H}^{N-1}, \quad (2)$$

$$v \in SBV(\Omega; \mathbb{R}^d)$$

Integral representation result in CF

- ▶ Under appropriate assumptions (among which **linear growth** of ψ), $I_L(g, G)$ admits an integral representation of the form:

$$I_L(g, G) = \int_{\Omega} H_p(x, \nabla g, G) dx + \int_{S(g)} h_p(x, [g], \nu_{(g)}) d\mathcal{H}^{N-1},$$

with H and h defined through appropriate cell formulae.

- ▶ The relaxed bulk energy density H depends **both** on W and ψ .

Integral representation result in CF

We start by introducing the assumptions on the bulk and interfacial energy densities W and ψ . Let $p > 1$ and let $W: \Omega \times \mathbb{R}^{d \times N} \rightarrow [0, +\infty)$ and $\psi: \Omega \times \mathbb{R}^d \times \mathcal{S}^{N-1} \rightarrow [0, +\infty)$ be continuous functions satisfying the following conditions

(W1)_p there exists $C > 0$ such that, for all $x \in \Omega$ and $A, B \in \mathbb{R}^{d \times N}$,

$$|W(x, A) - W(x, B)| \leq C|A - B|(1 + |A|^{p-1} + |B|^{p-1});$$

(W2) there exists a continuous function $\omega_W: [0, +\infty) \rightarrow [0, +\infty)$ with $\omega_W(s) \rightarrow 0$ as $s \rightarrow 0^+$ such that, for every $x, x_0 \in \Omega$ and $A \in \mathbb{R}^{d \times N}$,

$$|W(x, A) - W(x_0, A)| \leq \omega_W(|x - x_0|)(1 + |A|^p);$$

Integral representation result in CF

(ψ 1) there exist $c, C > 0$ such that, for all $x \in \Omega$, $\lambda \in d$, and $\nu \in \mathcal{S}^{N-1}$,

$$c|\lambda| \leq \psi(x, \lambda, \nu) \leq C|\lambda|;$$

(ψ 2) (positive 1-homogeneity) for all $x \in \Omega$, $\lambda \in d$, $\nu \in \mathcal{S}^{N-1}$, and $t > 0$

$$\psi(x, t\lambda, \nu) = t\psi(x, \lambda, \nu);$$

(ψ 3) (sub-additivity) for all $x \in \Omega$, $\lambda_1, \lambda_2 \in d$, and $\nu \in \mathcal{S}^{N-1}$,

$$\psi(x, \lambda_1 + \lambda_2, \nu) \leq \psi(x, \lambda_1, \nu) + \psi(x, \lambda_2, \nu);$$

(ψ 4) there exists a continuous function $\omega_\psi: [0, +\infty) \rightarrow [0, +\infty)$ with $\omega_\psi(s) \rightarrow 0$ as $s \rightarrow 0^+$ such that, for every $x, x_0 \in \Omega$, $\lambda \in d$, and $\nu \in \mathcal{S}^{N-1}$,

$$|\psi(x, \lambda, \nu) - \psi(x_0, \lambda, \nu)| \leq \omega_\psi(|x - x_0|)|\lambda|.$$

Integral representation result in CF

We introduce the classes of competitors for the cell formulae for the relaxed bulk and surface energy densities. For $A, B \in \mathbb{R}^{d \times N}$ let

$$C_p^{bulk}(A, B) = \left\{ u \in SBV(Q; \mathbb{R}^d) : u|_{\partial Q}(x) = Ax, \right. \\ \left. \int_Q \nabla u \, dx = B, |\nabla u| \in L^p(Q) \right\} \quad (3)$$

and for $\lambda \in \mathbb{R}^d$ and $\nu \in \mathcal{S}^{N-1}$ let

$$C_p^{surface}(\lambda, \nu) = \left\{ u \in SBV(Q_\nu; \mathbb{R}^d) : u|_{\partial Q_\nu}(x) = u_{\lambda, \nu}(x) \right. \\ \left. \nabla u(x) = 0 \text{ for } \mathcal{L}^N\text{-a.e. } x \in Q_\nu \right\}$$

where the function $u_{\lambda, \nu}$ is defined by

$$u_{\lambda, \nu}(x) = \begin{cases} \lambda & \text{if } x \cdot \nu \geq 0, \\ 0 & \text{if } x \cdot \nu < 0, \end{cases}$$

Integral representation result in CF

Let $p > 1$ and let $W: \Omega \times \mathbb{R}^{d \times N} \rightarrow [0, +\infty)$ and $\psi: \Omega \times \mathbb{R}^d \times \mathcal{S}^{N-1} \rightarrow [0, +\infty)$ be continuous functions satisfying hypotheses $(W1)_p$, $(W2)$, $(\psi1)$, $(\psi2)$, $(\psi3)$, and $(\psi4)$; let $(g, G) \in \text{StD}(\Omega)$. Then there exist $H_p: \Omega \times \mathbb{R}^{d \times N} \times \mathbb{R}^{d \times N} \rightarrow [0, +\infty)$ and $h_p: \Omega \times \mathbb{R}^d \times \mathcal{S}^{N-1} \rightarrow [0, +\infty)$ such that

$$\begin{aligned} I_L(g, G) &= \int_{\Omega} H_p(x, \nabla g(x), G(x)) dx \\ &\quad + \int_{\Omega \cap S_g} h_p(x, [g](x), \nu_g(x)) d\mathcal{H}^{N-1} \end{aligned} \tag{4}$$

Integral representation result in CF

Furthermore, for all $x_0 \in \Omega$ and $A, B \in \mathbb{R}^{d \times N}$,

$$H_p(x_0, A, B) = \inf \left\{ \int_Q W(x_0, \nabla u(x)) dx + \int_{Q \cap S_u} \psi(x_0, [u](x), \nu_u(x)) d\mathcal{H}^{N-1} : u \in C_p^{\text{bulk}}(A, B) \right\}$$

and for all $x_0 \in \Omega$, $\lambda \in \mathbb{R}^d$, and $\nu \in \mathcal{S}^{N-1}$,

$$h_p(x_0, \lambda, \nu) = \inf \left\{ \int_{Q_\nu \cap S_u} \psi(x_0, [u](x), \nu_u(x)) d\mathcal{H}^{N-1} : u \in C_p^{\text{surface}}(\lambda, \nu) \right\}$$

Motivation of our work

The theory of structured deformation in the SBV setting developed by Choksi & Fonseca only takes into account the **linear dependence** on jumps along the approximating sequences. Del Piero & Owen proposed a 1-D model toward capturing the non-linear dependence on the jumps. The idea was to modify the initial energy as follows: for each $r \in (0, 1)$ let

$$F^r(u) = \int_0^1 W(u'(x)) dx + \sum_{z \in S_u} \psi([u](z)) \\ + \int_0^1 \Psi \left(\sum_{z \in S_u \cap (x-r, x+r)} \frac{[u](z)}{2r} \right) dx,$$

and then undergo a relaxation process in the context of structured deformations followed by taking the limit as $r \rightarrow 0^+$.

Framework

The present approach to relaxation of non-local energies rests on **two** limiting processes:

1. Start from a submacroscopical level where we have a **weighted average of disarrangements** within neighborhoods of fixed size $r > 0$ and pass to the macrolevel, permitting disarrangements to diffuse through such a neighborhood. This limiting process determines a structured deformation as well as the non-local dependence of the energy density of such a structured deformation.
2. Pass to the **limit as $r \rightarrow 0$** , to obtain purely local bulk and interfacial energy densities for the structured deformation identified in the first step.

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Framework

1. Previous research on relaxation of energies for continuous bodies relies on one or the other, but not on both processes described above. For instance, the approach of **CF** relies on the first process, while the second process is used for instance in **peridynamics**.
2. Peridynamics is a new Continuum Mechanics formulation where the governing equations are integro-differential equations that do not contain spatial derivatives. This is an important new tool to address problems with discontinuities such as cracks.

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Framework

1. It is important to point out that the first limiting process, in the context of structured deformations, gives rise to relaxed energy densities that exclude a **periodic** dependence of the relaxed energy on the disarrangement tensor, which are used to predict **yielding** (passage from elastic to plastic behavior) and **hysteresis** (dependence of the state of a system on its history).
2. We consider an **explicit** dependence on x in both the **CF** scheme and the bulk part of the relaxed non-local energy Ψ motivated by some explicit applications to crystal plasticity. This is important in order to account for frame-indifference.

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Averaging processes

Let $\Omega \subset \mathbb{R}^N$ a bounded connected open set with Lipschitz boundary $\partial\Omega$ and $u \in SBV(\Omega; \mathbb{R}^d)$. For a continuous function $\Psi: \Omega \times \mathbb{R}^{d \times N} \rightarrow [0, +\infty)$ and fixed $r > 0$ we define the **non-local** contribution by

$$E^{\alpha_r}(u) := \int_{\Omega_r} \Psi(x, (D^s u * \alpha_r)(x)) dx, \quad (5)$$

where $\Omega_r := \{x \in \Omega : \text{dist}(x; \partial\Omega) > r\}$.

Averaging processes

In (??)

$$\alpha_r := \frac{1}{r^N} \alpha\left(\frac{x}{r}\right),$$

where

$$\alpha \in C_c^\infty(B_1)$$

with

$$\int_{B_1} \alpha(x) dx = 1, \quad \alpha \geq 0, \quad \alpha(-x) = \alpha(x)$$

The symbol $*$ denotes the convolution operation.

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Averaging processes

Given $(g, G) \in \text{StD}(\Omega; \mathbb{R}^d)$, let $\{u_n\} \subset \text{SBV}(\Omega; \mathbb{R}^d)$ such that

(a) $u_n \rightarrow g$ in L^1 , $\nabla u_n \rightharpoonup G$ in L^p ($\overset{*}{\rightharpoonup}$ in L^1),

(b) $D^s u_n \overset{*}{\rightharpoonup} (\nabla g - G)\mathcal{L}^N + D^s g$ in $\mathcal{M}^+(\Omega)$,

We will denote by $Ad(g, G)$ the class of sequences satisfying (a) and (b).

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Averaging processes - the limit in n

We take the limit as $n \rightarrow \infty$ of $E^{\alpha_r}(u_n)$, obtaining

$$\begin{aligned} I_{NL}^r(g, G) &:= \lim_{n \rightarrow \infty} E^{\alpha_r}(u_n) \\ &= \lim_{n \rightarrow \infty} \int_{\Omega_r} \Psi(x, (D^s u_n * \alpha_r)(x)) \, dx \\ &= \int_{\Omega_r} \Psi\left(x, ((\nabla g - G)\mathcal{L}^N + D^s g) * \alpha_r\right) \, dx \end{aligned} \quad (6)$$

Averaging processes

We consider now an extension of (g, G) to $(\tilde{g}, \tilde{G}) \in \mathbb{R}^N \times \mathbb{R}^{d \times N}$ in the following sense:

$$(e1) \quad (\tilde{g}, \tilde{G})|_{\Omega} = (g, G),$$

$$(e2) \quad |D\tilde{g}|(\mathbb{R}^N) \leq C \|g\|_{BV(\Omega; \mathbb{R}^d)},$$

$$(e3) \quad |D\tilde{g}|(\partial\Omega) = 0.$$

Averaging processes

For such (\tilde{g}, \tilde{G}) , we extend $I_{NL}^r(g, G)$ to Ω by defining:

$$\begin{aligned} \tilde{I}_{NL}^r(\tilde{g}, \tilde{G}) &:= \int_{\Omega_r} \Psi(x, ((\nabla g - G)\mathcal{L}^N + D^s g) * \alpha_r) dx \\ &+ \int_{\Omega \setminus \Omega_r} \Psi(x, ((\nabla \tilde{g} - \tilde{G})\mathcal{L}^N + D^s \tilde{g}) * \alpha_r) dx \end{aligned} \quad (7)$$

In any case, independently of the extension considered, we can show that the difference between $I_{NL}^r(g, G)$ and $\tilde{I}_{NL}^r(\tilde{g}, \tilde{G})$ goes to zero as $r \rightarrow 0^+$.

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The limit as $r \rightarrow 0^+$

We work with $\tilde{I}_{NL}^r(\tilde{g}, \tilde{G})$ where Ψ can be of two types:

E) $\Psi \in C(\Omega \times \mathbb{R}^{d \times N})$ and $\Psi^\infty(x, \xi) := \lim_{\substack{x' \rightarrow x \\ \xi' \rightarrow \xi \\ t \rightarrow +\infty}} \frac{\Psi(x', t\xi')}{t}$ exists

in $\bar{\Omega} \times \mathbb{R}^{d \times N}$

L) $\Psi \in C(\Omega \times \mathbb{R}^{d \times N})$, Lipschitz continuous in the second variable with Ψ^∞ defined as $\Psi^\infty(x, \xi) := \limsup_{\substack{x' \rightarrow x \\ \xi' \rightarrow \xi \\ t \rightarrow +\infty}} \frac{\Psi(x', t\xi')}{t}$

The proof relies in [Reshetnyak continuity \(upper semicontinuity\) theorems](#).

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The limit as $r \rightarrow 0^+$

We have that, for any $(g, G) \in \text{StD}(\Omega; \mathbb{R}^d)$,

$$I_{NL}(g, G) := \lim_{r \rightarrow 0^+} \tilde{I}_{NL}^{\alpha_r}(\bar{g}, \bar{G}) = \int_{\Omega} \Psi(x, (\nabla g - G)(x)) \, dx \\ + \int_{\Omega \cap S(g)} \Psi^{\infty}\left(x, \frac{dD^s g}{d|D^s g|}(x)\right) \, d|D^s g|$$

Coupling

- ▶ $I(g, G) = I_L(g, G) + I_{NL}(g, G)$ where

$$I_L(g, G) = \int_{\Omega} H(x, \nabla g(x), G(x)) dx + \int_{S_{(g)} \cap \Omega} h(x, [g](x), \nu_{(g)}(x)) d\mathcal{H}^{N-1}$$

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Example from crystal plasticity

- ▶ **Crystallographic slip**: The discontinuity in deformation arises only across a limited family of slip planes.
- ▶ For a single crystal in the reference configuration Ω the data required for the analysis of crystallographic slip consists of **pairs of orthogonal unit vectors** (s^a, m^a) for $a = 1, \dots, A$, with **A the number of potentially active slip systems**.
- ▶ The unit vector s^a provides the **direction of slip**, while the unit vector m^a is a **normal to the slip plane** for the a^{th} slip-system (s^a, m^a) .

Crystallographic structured deformation

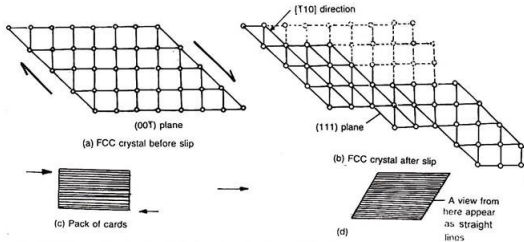


Fig. 6.15. Slip resembles distortion of deck of playing cards when pushed as shown (c & d). (a) FCC Crystal before slip, (b) FCC crystal after slip, (c) Pack of cards, (d) Pack of cards after slip.

Slip-neutral two level shears

Crystallographic slip is physically activated within very thin bands, (**slip-bands**) with thickness typically of the order 10^2 atomic units, while the separation of active slip-bands is typically of order 10^4 atomic units. Following [CDPFO1999], for each $a = 1, \dots, A$, there is a number $p^a > 0$ such that a **two-level shear** $(g_{\mu, x_0}^a, G_\nu^a)$ for which the shear due to slip $\mu - \gamma$ satisfies

$$\mu - \gamma = mp^a \quad \text{with } m \in \mathbb{Z} \quad (8)$$

and gives rise to **submacroscopic slips** equal to an integer number of atomic units in the direction of slip s^a .

Special properties for Ψ , under crystallographic slip

- ▶ Let $x_o \in \Omega$, $a \in A$, $\mu = mp^a$ with $m \in \mathbb{Z}$, and a crystallographic structured deformation (g, G) be given. The lattice on which (g, G) acts, when following the completely neutral two-level shear (g_{μ, x_o}^a, I) , differs from that on which (g, G) acts, when **not** following (g_{μ, x_o}^a, I) , only by the undetectable translations of the lattice between active slip-planes for system a .
- ▶ Consequently, the submacroscopic kinematical states of the crystal lattice attained by means of the two purely submacroscopic structured deformations $(i, K_{(g, G) \diamond (g_{\mu, x_o}^a, I)})$ and $(i, K_{(g, G)})$ are indistinguishable.

Special properties for Ψ , under crystallographic slip

- ▶ This leads to the conclusion that, the **non-local** relaxed bulk density, in the context of crystal plasticity, can have **periodicity properties**, provided that it is restricted to each member of a family of two-dimensional affine subspaces of $\mathbb{R}^{3 \times 3}$, with (vector) period depending on the corresponding subspace.
- ▶ The periodicity stems from the fact that special families of two-level shears associated with the slip systems of the crystal are geometrically undetectable.

Prediction of yielding and hysteresis

- ▶ An additive decomposition for the relaxed bulk energy density of the form

$$H(G) + \Psi(M)$$

is used to predict yielding and hysteresis [CDPFO1999], [Del Piero 2018])

- ▶ It was shown ([Larsen2000]) that such a decomposition doesn't always hold in the CF setting.
- ▶ Our double limiting process points in that direction. For each crystallographic structured deformation, departing from Ψ satisfying the periodicity properties compatible with completely neutral crystallographic slips and from the CF scheme with $p > 1$ growth on W and with $\psi = 0$ we attain such a decomposition.

Thank you for your attention!