

# Neural Density Fields

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European Space Agency

Irregular bodies in the solar system













Representing the gravity field (state-of-the-art)





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 $U(r,\theta,\phi) = \frac{\mu}{r} \sum_{l=0}^{l=\infty} \sum_{m=0}^{m=l} \left(\frac{r_0}{r}\right) P_{lm}(\cos\theta) \cdot \left(C_{lm}\cos m\phi + S_{lm}\sin m\phi\right)$  $C_{lm} = \frac{(2 - \delta_{m,0})}{M} \frac{(l - m)!}{(l + m)!} \int_{V} \rho\left(\frac{r}{r_0}\right)^l \cdot P_{lm}(\cos\theta) \cos m\phi dV$ Stokes Coefficients  $S_{lm} = \frac{(2 - \delta_{m,0})}{M} \frac{(l-m)!}{(l+m)!} \int_{V} \rho\left(\frac{r}{r_0}\right)^l \cdot P_{lm}(\cos\theta) \sin m\phi dV$ → THE EUROPEAN SPACE AGENCY

#### 1. Spherical harmonics - $(\frac{1}{3})$





#### Spherical harmonics - $(\frac{2}{3})$





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## Spherical harmonics - (3/3)





Poor convergence properties next to irregular surfaces.



### 2.Polyhedral gravity (1/2)





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## Polyhedral gravity (2/2)





code: https://github.com/esa/polyhedral-gravity-model

Relies and needs on the asteroid shape, unable to see inside.

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#### 3.Mascon models





Great flexibility but poor precision next to the surface and needs shape information.

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## An ill-posed problem! (gravity inversion)









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observations



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Newton's Shell theorem :(

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# a fourth way ... Neural Density Fields

<u>Izzo, Dario</u>, and Pablo Gómez. "Geodesy of irregular small bodies via neural density fields: geodesyNets." *arXiv preprint arXiv:2105.13031* (2021).

von Looz, Moritz, Pablo Gomez, and <u>Dario Izzo</u>. "Study of the asteroid Bennu using geodesyANNs and Osiris-Rex data." *arXiv preprint arXiv:2109.14427* (2021).

Inspired from NeRF: (neural radiance fields)

The weights of a neural network are able to store highly detailed information on complex 3D scene

Mildenhall, Ben, et al. "Nerf: Representing scenes as neural radiance fields for view synthesis." *European conference on computer vision*. Springer, Cham, 2020.



"With four parameters I can fit an elephant, with five I can make him wiggle his trunk"

John von Neumann









	Approach					
	Masc.	Harm.	Poly.	geodesyNets		
Differentiable	X	$\checkmark$	~	$\checkmark$		
Inside Brillouin sphere	~	X	$\checkmark$	$\checkmark$		
Heterogeneous densities	~	~	X	$\checkmark$		
Shape model not needed	~	~	X	$\checkmark$		
Can utilize shape model	~	X	~	$\checkmark$		
Accurate in the near field	X	$\checkmark$	$\checkmark$	$\checkmark$		

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#### **Network architecture: SIREN**



$$\Phi(\mathbf{x}) = \mathbf{W}_n \left( \phi_{n-1} \circ \phi_{n-2} \circ \ldots \circ \phi_0 \right) (\mathbf{x}) + \mathbf{b}_n, \quad \mathbf{x}_i \mapsto \phi_i \left( \mathbf{x}_i \right) = \sin \left( \mathbf{W}_i \mathbf{x}_i + \mathbf{b}_i \right).$$





Sitzmann, Vincent, et al. "Implicit neural representations with periodic activation functions." *Advances in Neural Information Processing Systems* 33 (2020): 7462-7473.

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The loss



constraint:  $\iiint_V 
ho(x,y,z) dV = M$ 

solution: 
$$ho(x,y,z)=c\mathcal{N}(x,y,z)$$

Its as if we added one more parameter (weight) after the output neurons!

$$\sum_{i} (y_i - c\hat{y}_i)^2 = c^2 \sum_{i} \hat{y}_i^2 - 2c \sum_{i} y_i \hat{y}_i + \sum_{i} y_i^2$$
$$(c = \frac{\sum y_i \hat{y}_i}{\sum \hat{y}_i^2}) \qquad \dots \text{ can also be used in g}$$

generic ML tasks

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# Experiments

## **Test cases**



## Sampling points



Model

Surface normals

Samples taken at three altitudes low, mid and high

# Nominal Learning

#### **Results** Nominal learning

		Sampling Altitudes			Absolute Errors			Relative Errors		
	Body	$h_{low}[m]$	$h_{med}[m]$	$h_{hi}[m]$	$\epsilon_{low}[m/s^2]$	$\epsilon_{med}[m/s^2]$	$\epsilon_{hi}[m/s^2]$	$\epsilon_{low}$ [%]	$\epsilon_{med}[\%]$	$\epsilon_{hi}[\%]$
HMG	Bennu	14.1	28.2	70.4	2.63e-08	4.75e-09	6.89e-10	0.11	0.02	0.005
	Churyumov- Gerasimenko	125	250	625	1.13e-07	2.02e-08	2.20e-09	0.19	0.04	0.006
	Eros	817	1630	4080	2.24e-06	4.45e-07	5.52e-08	0.16	0.04	0.01
	Itokawa	14	28	70.1	3.15e-08	6.35e-09	1.06e-09	0.15	0.04	0.01
	Planetesimal	125	250	625	5.69e-08	1.31e-08	3.43e-09	0.11	0.03	0.011
	Torus	125	250	625	1.41e-07	3.74e-08	8.49e-09	0.28	0.09	0.034
HTG	Bennu	14.1	28.2	70.4	4.70e-08	9.57e-09	1.57e-09	0.20	0.05	0.011
	Itokawa	14	28	70.1	4.27e-08	9.36e-09	9.33e-10	0.20	0.05	0.009
	Planetesimal	125	250	625	9.90e-08	2.53e-08	4.22e-09	0.20	0.06	0.014



Visualizing the Neural Density field

Torus

Visualizing the Neural Density field

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# **Differential Learning**

fusing in camera information

## Results

differential learning

Heterogeneous body	Sampling Altitudes			Absolute Errors			Relative Errors		
	$h_{low}[m]$	$h_{med}[m]$	$h_{hi}[m]$	$\epsilon_{low}[m/s^2]$	$\epsilon_{med}[m/s^2]$	$\epsilon_{hi}[m/s^2]$	$\epsilon_{low}$ [%]	$\epsilon_{med}[\%]$	$\epsilon_{hi}[\%]$
Bennu	14.1	28.2	70.4	4.07e-08	1.19e-08	7.67e-09	0.10	0.03	0.031
Itokawa	14	28	70.1	2.49e-08	1.45e-08	1.01e-08	0.12	0.08	0.091
Planetesimal	125	250	625	3.55e-08	2.29e-08	1.84e-08	0.08	0.06	0.071



Do we need a neural model for the density field?

		Bennu	Churyumov-Gerasimenko	Eros	Itokawa
GeodesyNet	low	0.72	2.30	1.82	2.13
	hi	0.02	1.75	0.17	0.38
masconCUBE	low	1.00	2.87	2.39	2.47
	hi	0.01	2.03	0.13	0.70



#### Open questions:

- Pumping up the card memory (points used limited by NVIDIA 2080 RTX capability).
- Numerical quadrature vs Monte Carlo methods.
- Sensitivity to data noise (random and non gravitational).
- Sensitivity to data availability (spacecraft orbit design).
- On-board training effectiveness.
- Thorough comparison with masconCUBE and spherical harmonics using the same training.

# **Eclipse Nets**

... also an implicit neural representation

Biscani, Francesco, and <u>Dario Izzo</u>. "Reliable event detection for Taylor methods in astrodynamics." *Monthly Notices of the Royal Astronomical Society* 513.4 (2022): 4833-4844.

#### The eclipse function: $F(\mathbf{r}, \hat{\mathbf{i}}_S)$







The eclipse function can be used to determine the presence or absence of solar radiation pressure.

#### The eclipse function: $F(\mathbf{r}, \hat{\mathbf{i}}_S)$





Even intersections -> EF is the length of the ray inside the asteroid

No intersections -> EF is the distance of the point to the shadow cone.

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## The eclipse function: $F(\mathbf{r}, \hat{\mathbf{i}}_S)$





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#### eclipseNet





$$\ddot{\mathbf{r}} = -G \sum_{j=0}^{N} \frac{m_j}{|\mathbf{r} - \mathbf{r}_j|^3} (\mathbf{r} - \mathbf{r}_j) - 2\omega \times \mathbf{v} - \omega \times \omega \times \mathbf{r} - \eta v(\mathbf{r}) \mathbf{\hat{i}}_S(t),$$

$$\nu(\mathbf{r}) = 1$$
no penubra



$$\eta(\mathbf{r}, \mathbf{i}_S) = H(F(\mathbf{r}, \mathbf{i}_S))$$

We obtain a "neural" ODE on top of which to perform event detection -> heyoka!

Biscani, Francesco, and Dario Izzo. "Reliable event detection for Taylor methods in astrodynamics." *Monthly Notices of the Royal Astronomical Society* 513.4 (2022): 4833-4844.

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# Thank you for listening!

