



- selected topics -

# The MODE Collaboration Effort

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### Machine-Learning Optimised Design of Experiments https://mode-collaboration.github.io

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# MODE



End of 2020







- Dark matter
- Stability of the universe
- Grand unifying theories
- Resolution ~ energy



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### What are we looking for?











# **Underlying Model**





• Go deeper: new, more powerful colliders







## **Detect Particles and Processes**





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Photon

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Neutral hadron (e.g. neutron)

- We measure decay products of the stochastic process
- Detectors employ parts of or all of the above concepts





# Simulation of detector response



- High fidelity simulation of particles interacting with matter
- Carefully validated
- Validity also spans orders of magnitude

http://arxiv.org/abs/2108.02803







## The status quo



- - Tuning often by hand and optimisations take a lot of time and person power

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# Determining multiple parameters

- Determining multiple parameters ~ fitting a function
- The optimisation of a detector or a reconstruction chain is conceptually the same thing



- To perform this optimisation we need to know  $\partial \epsilon / \partial \vartheta$ : how does our photon efficiency change w.r.t. the reconstruction parameters  $\vartheta$ ?
- Gradients can be calculated
- Numerically: unfeasible for many parameters
- Algorithmically: requires *unbroken* gradients throughout the whole chain: every step needs to be differentiable
- ➡ Differential programming

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- Differentiable programming is used by, but is independent of machine learning.
- At its core: in any operation, include a way to access its gradient w.r.t. all parameters (if it exists): auto differentiation
- Auto-differentiation is neither pure numeric nor pure symbolic differentiation
  - Numerical differentiation is not feasible for large optimisation problems
- Fully symbolic differentiation can easily become not feasible from computational point of view
- In most cases, back propagation is used  $A \rightarrow x \rightarrow L$ dL/dA = dx/dAdL/dx
  - Calculate the numerical values of b = dL/dx using the analytic gradient of the operation
  - Calculate the numerical values of b \* dx/dA in the same way
- Each 'atomic' simple operation only needs to be equipped with a simple analytic gradient, then evaluated numerically: best of both worlds.
- This is implemented in one way or another in all modern ML frameworks (TF, torch..)
- Even expressing non-ML algorithms in differentiable frameworks comes with huge advantages w.r.t. the capability of optimising their parameters, and using state-ofthe-art libraries to do so

(a) Forward pass  $\partial E/\partial w_{
m s}$  $E(y_3,t)$  $\partial E/\partial E$  $\partial E/\partial u$ (b) Backward pass f, original function  $\nabla f$ , numerical diff.  $\nabla f$ , forward AD  $\nabla f$ , reverse AD 2000 1000

For a nice overview see Atılım Günes Baydin et al (2018), arXiv:1502.05767v4









#### **EUROPEAN STRATEGY FOR PARTICLE PHYSICS**

The European Strategy for Particle Physics is the cornerstone of Europe's decision-making process for the long-term future of the field. Mandated by the CERN Council, it is formed through a broad consultation of the grass-roots particle physics community, it actively solicits the opinions of physicists from around the world, and it is developed in close coordination with similar processes in the US and Japan in order to ensure coordination between regions and optimal use of resources globally

> nformation for th physics communit



Use differentiable programming to optimise particle physics detectors given a quantification of the physics target(s) and the detector cost

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### The MODE Collaboration: Goals

















0.0 0.0 0.04 0.03 0.02 0.01 arxiv:2101.08150 60 80



Collider

- Overarching connection is missing
- Next: will be going backwards



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### What do we already have









### Data

• Includes the full chain up to final state particle reconstruction

### Simulation

- Simulate different physics processes
- Simulate detector response and electronics
- Proceed as for data
- Calibrate and correct using control samples in data
- Assign uncertainties on normalisation and shapes

### Analysis

- Create histograms of data and simulation
- A contribution of a process or a shape to the data: **signal**
- Contributions of other processes: **background**
- Perform profile likelihood fit of parameters of interest and parameters representing variations w.r.t. uncertainties

Uncertainties can be (significantly) reduced by choosing good observables to fit

# A typical high-energy physics analysis





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# Automatising analyses on simulation

- Standard analysis concept: perform fit to data based on histograms
  - Best signal fraction (S/S+B)
  - Often use a trained classifier here
  - Lowest uncertainties
- Can take into account uncertainties in to learn not only best S/S+B, but also lowest uncertainty: INFERNO [2]
- Derive "best histogram" and perform a standard profile likelihood fit to extract the physics result



 $\checkmark$  Concepts for generalisable, differentiable analyses workflows exist



Other methods overview in Bremer, Cranmer et al, arXiv:1911.01429 [2] P. Castro, T. Dorigo, arxiv:1806.04743v2







• Determine final state particles and their properties from detector hits

### The usual chain

- Local seeding (pattern recognition)
- Local clustering (pattern recognition)
- Software compensation (pattern recognition)
- Identification (pattern recognition)
- Linking of individual detector parts (pattern recognition)

### Always the same patterns

Many steps cutting / segmenting information: a priori non differentiable

# Reconstruction











### The usual chain

- Local seeding (pattern recognition)
- Local clustering (pattern recognition)
- Software compensation (pattern recognition)
- Identification (pattern recognition)
- Linking of individual detector parts (pattern recognition)

### •Use ML for the task: CNN structure

- Adapts itself to grid-like granularity
- Re-optimisation == a few GPU hours vs. months of optimisations by hand

### • Compare different segmentations

Saturation effects visible



### Use DNNs as generic reconstruction





C. Neubüser, JK, P Lujan, arxiv:2101.08150, EPJC









- At future very high energy colliders
  - Muons will deposit more energy
  - Muons will bent less  $\rightarrow$  tracks provide less information
- Based on CNNs



### Use known sub detectors in a new way



JK, G. Strong, et al., arXiv:2107.02119









- Detectors are not grids of sensors
- The reconstruction needs to account for that
- Graph neural networks are a powerful solution
- No sorting required
- No grid
- Sense of connection
- Basic principle: information exchange through edges (connections)



- A typical HEP detector has O(500k) active sensors each event
- The network needs to fit into the resources

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### Irregular Geometries





Image from https://news.voyage.auto/an-introduction-to-lidar-the-key-self-driving-car-sensor-a7e405590cff



[1] Y. Wang, et al, arXiv:1801.07829







- Developed to overcome resource limitation



- Tested on a HEP calorimeter reconstruction task



## GravNet



S.R. Qasim, J. K, Y. Iiyama, M Pierini, CMS DP-2020/001







# Multi-particle reconstruction

### The usual chain

- Local seeding (pattern recognition)
- Local clustering (pattern recognition)
- Software compensation (pattern recognition)
- Identification (pattern recognition)
- Linking of individual detector parts (pattern recognition)

### Challenges

- A priori unknown number of particles to reconstruct
- Particles are not dense objects with clean centres and boundaries
- The input data is represented by point clouds









N. Wang et al, arXiv:1904.01355 X. Zhou et al, arXiv:1904.07850









- Maximum number of objects per image/point cloud: number of pixels/vertices
- Learn to move pixels towards the object center
- Map to Gaussian probability

$$\phi_k(e_i) = \exp\left(-\frac{\|e_i - C_k\|^2}{2\sigma_k^2}\right)$$

Assign seed score

$$\mathcal{L}_{\text{seed}} = \frac{1}{N} \sum_{i}^{N} \mathbb{1}_{\{s_i \in S_k\}} \|s_i - \phi_k(e_i)\|^2 + \mathbb{1}_{\{s_i \in \text{bg}\}} \|s_i - 0\|^2$$

- Collect (from highest seeds score) around the seeds
- 'Only' performs segmentation
- Heavily relies on the center of an object
- Problematic concept for particles







D. Neven et al, arXiv:1906.11109B. Zhang, P. Wonka, arXiv:1912.00145

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- Merge object property determination and segmentation
- Create a decoupled 'clustering' space
  - Created by potentials
- Assign 'condensation score'  $\rightarrow$  charge
  - Highest score condensation points carry object properties
- Push non-differentiable 'clustering' step towards the very end

Segmentation

$$\breve{V}_k(x) = ||x - x_\alpha||^2 q_{\alpha k}, \text{ and}$$

$$\hat{V}_k(x) = \max(0, 1 - ||x - x_\alpha||) q_{\alpha k}.$$



Reconstruction efficiency and noise

$$L_{\beta} = \frac{1}{K} \sum_{k} (1 - \beta_{\alpha k}) + s_B \frac{1}{N_B} \sum_{i}^{N} n_i \beta_i,$$

Object properties

$$L_p = \frac{1}{\sum_{i=0}^{N} (1-n_i) \operatorname{arctanh}^2 \beta_i} \sum_{i=0}^{N} L(t_i, p_i) (1-n_i) \operatorname{arctanh}^2 \beta_i$$

➡Generalises to image data

### **Object Condensation**





JK, arxiv:2002.03605, EPJC







# High granular calorimeter application



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• Differentiable one-shot reconstruction from hits to final state particles



 Can also be applied to information from different sub detectors

### The usual chain

- ✓ Local seeding (pattern recognition)
- ✓ Local clustering (pattern recognition)
- ✓ Software compensation (pattern recognition)
- ✓ Identification (pattern recognition)
- ✓ Linking of individual detector parts (pattern) recognition)

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### What do we already have











Collider	Sensors
/	Electronics
"Space"	Geometry

- a sensor layer, switching positions, ...
- This is a very interesting conceptual challenge to contribute to!
- the SHIP muon shielding



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# Simulation







## Sweeping magnet optimisation



• Local differentiable surrogates can help solve the problem of nondifferentiable simulation

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sents number of the hits in a bin.

S. Shirobokov, A. Ustyuzhanin, A. Güneş Badyin et al., arXiv:2002.04632







# Writing a differentiable simulator: TOMOPT

- Atmospheric muons: 1/s/hand area
- Interact only sparsely with material
- Are scattered enough to be used for imaging applications
- Detectors: usually panels, with spatial resolution and detection efficiency
- Optimal starting point for a differentiable simulation
- TOMOPT: package to optimise muon tomography detectors (work in progress)







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Work in progress; G. Strong et al.









- The target of MODE is to design and offer to the community a scalable, versatile architecture that can provide end-to-end optimisation of particle detectors, proving it on a number of different applications across different domains.
- Study cases:
- Use known detector concepts in a new way: demonstration of muon energy measurement in calorimeter
- Optimise starting from 'simple' applications Muon tomography detector optimisation in progress
- Rethink decades old paradigms: Hybrid calorimeter design integrating tracking layers activity starting
- Other use cases being considered / about to start include:
  - Hadron therapy
  - Muon collider detector shielding

### • The developed architectures for optimisation are modular

- recycle part of the work for one application when moving to the next one
- Very happy about any suggestions / contributions

MODE Collaboration, "Toward Machine Learning Optimization of Experimental Design", Nuclear Physics News International, 2021.

# MODE





#### Dear Colleagues,

Initiated by the European Committees for Astroparticle (APPEC), Particle (ECFA) and Nuclear Physics (NuPECC), and following a first joint seminar held in Orsayin 2019, Expressions of Interest for common activities have meanwhile been endorsed in the following areas:

- Dark Matter (iDMEu)
- Machine-learning Optimized Design of Experiments (MODE)





